

# AUTOMATED TRAFFIC SIGNAL PERFORMANCE MEASURES: CASE STUDIES

INSTITUTE OF TRANSPORTATION ENGINEERS WEBINAR PART 2 – MAY 7, 2014



# ITE Webinar Series on Automated Traffic Signal Performance Measures (SPMs)

- ▶ Achieve Your Agency's Objectives Using SPMs  
April 9, 2014, 12:00 pm to 1:30 pm. Eastern
- ▶ SPM Case Studies  
May 7, 2014, 12:00 pm to 1:30 pm. Eastern
- ▶ Critical Infrastructure Elements for SPMs  
June 11, 2014, 12:00 pm to 1:30 pm. Eastern

# Automated Traffic Signal Performance Measures

## Technology Implementation Group: 2013 Focus Technology

<http://tig.transportation.org>

Mission: Investing time and money to accelerate technology adoption by agencies nationwide



# Your Speakers Today

Jamie Mackey, UDOT



Amanda Stevens, INDOT



Alex Hainen, Purdue



Steve Misgen, MnDOT



Mark Taylor, UDOT



# AUTOMATED TRAFFIC SIGNAL PERFORMANCE MEASURES CASE STUDIES: UDOT



INSTITUTE OF TRANSPORTATION ENGINEERS WEBINAR PART 1 – MAY 7, 2014

PRESENTED BY JAMIE MACKEY, UDOT

# What Can Automated Traffic Signal Performance Measures Do for You?

- ▶ Troubleshoot complaints and reduce wasted time for maintenance staff
- ▶ Catch problems as they happen
- ▶ Operate & optimize system without field data collection
- ▶ Retime signals as needed, not on a schedule
- ▶ Communicate signal/corridor/system performance to public & agency leaders

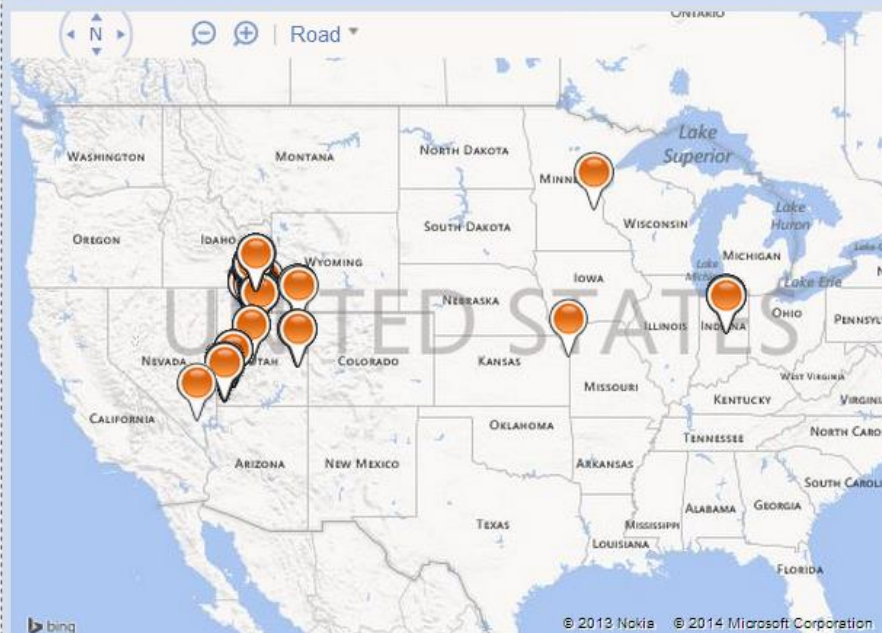
->Signal Metrics

Selected Signal  
 5600 West SR-201 Westbound

Signals  
 Region   
 Metric Type   
 Filter

Signal List

Map



Create Metrics

Metric Settings

Metric Type

- Approach Delay
- Approach Volume
- Arrivals On Red
- Purdue Coordination Diagram
- Purdue Phase Termination
- Speed
- Split Monitor

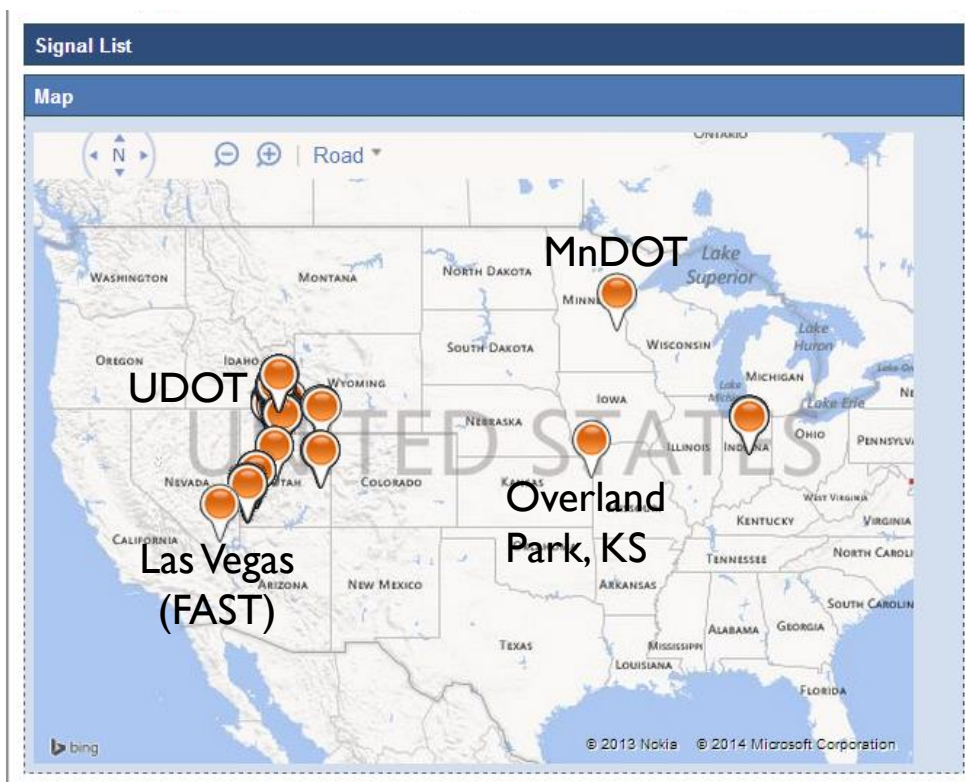
Y Axis Maximum   
 Percentile Split   
 Show Plan Stripes  Show % Max Out/ Force Off  
 Show Ped Activity  Show Percent Gap Outs  
 Show Average Split  Show Percent Skip  
 Upload Current Data

Dates

Start Date   AM  
 End Date   PM  
   

Sun	Mon	Tue	Wed	Thu	Fri	Sat
27	28	29	30	1	2	3
4	5	6	7	8	9	10
11	12	13	14	15	16	17
18	19	20	21	22	23	24
25	26	27	28	29	30	31
1	2	3	4	5	6	7

## Agencies using UDOT software for SPMs



Create Metrics

Y Axis Maximum

Percentile Split

Show Plan Stripes     Show % Max Out/ Force Off  
 Show Ped Activity     Show Percent Gap Outs  
 Show Average Split     Show Percent Skip  
 Upload Current Data

Dates

Start Date   AM

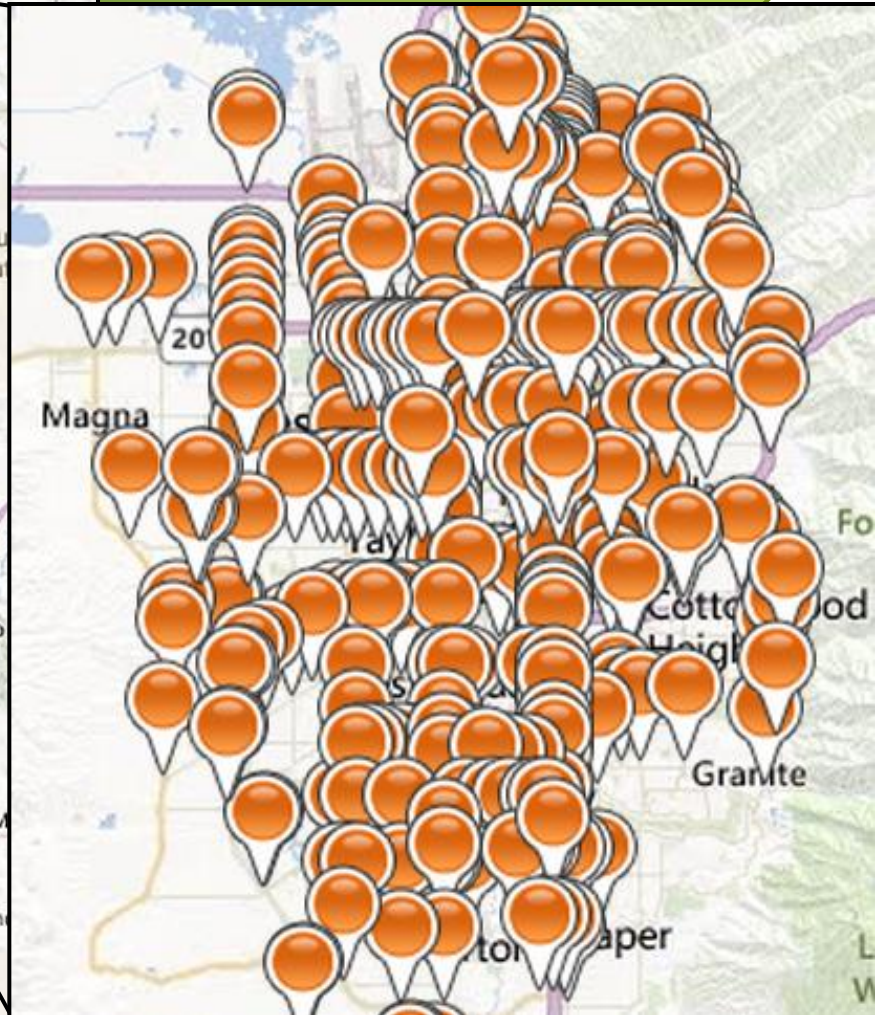
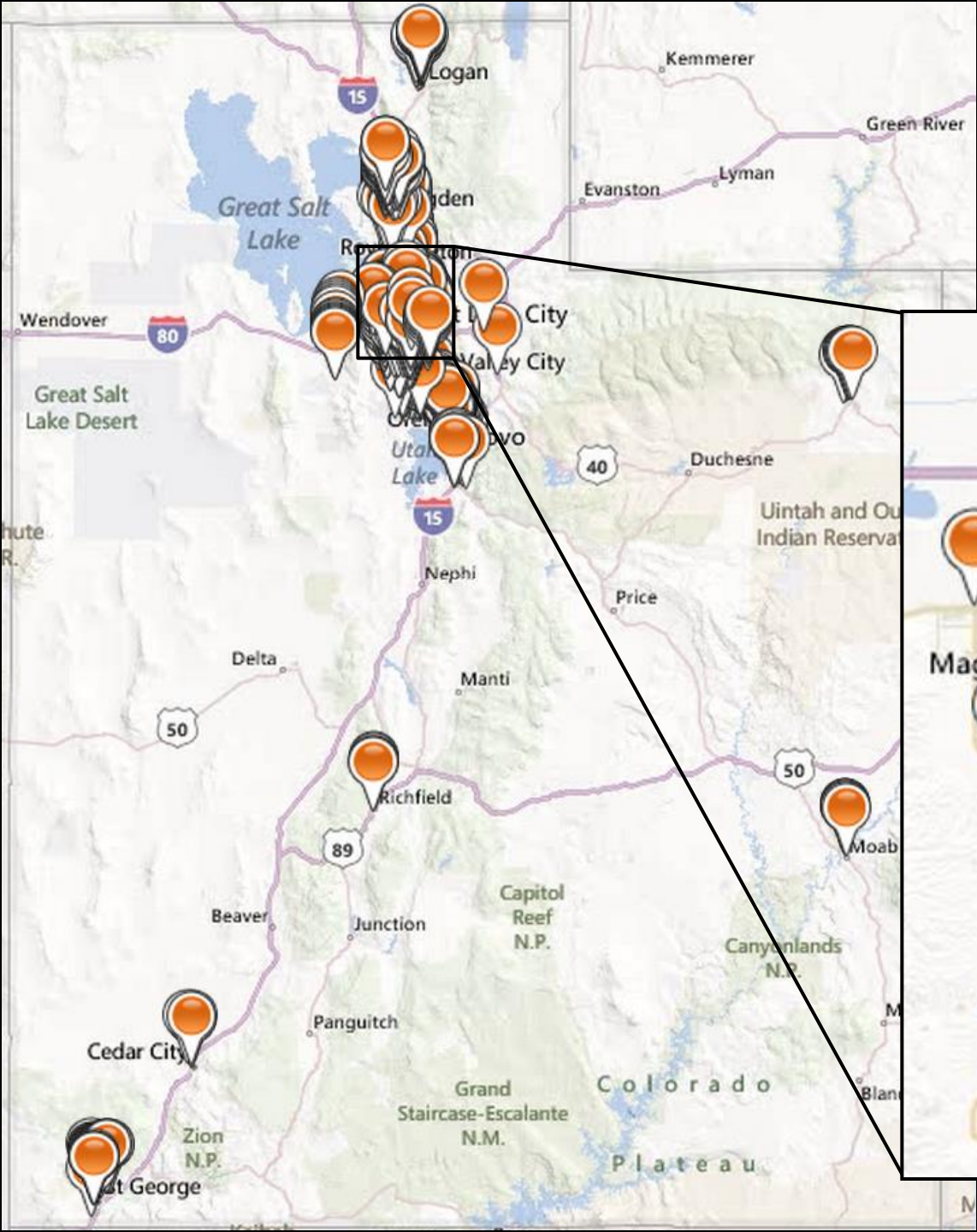
End Date   PM

Reset Date  May 2014

Sun	Mon	Tue	Wed	Thu	Fri	Sat
27	28	29	30	1	2	3
4	5	6	7	8	9	10
11	12	13	14	15	16	17
18	19	20	21	22	23	24
25	26	27	28	29	30	31
1	2	3	4	5	6	7



# Salt Lake Valley



# System Requirements



**High-resolution Controller**

**Communications**

**Can be done independent of a  
Central System!**

3) Store in Database

**Server**

**Website**

**Detection**  
(optional)

# Metrics & Detection Requirements

## Controller high-resolution data only

**Purdue Phase Termination**  
**Split Monitor**

## Advanced Count Detection (~400 ft behind stop bar)

**Purdue Coordination Diagram**

Approach Volume

Platoon Ratio

Arrivals on Red

Approach Delay

Executive Summary Reports

## Advanced Detection with Speed

Approach Speed

## Lane-by-lane Presence Detection

Split Failure (future)

## Lane-by-lane Count Detection

Turning Movement Counts

## Probe Travel Time Data (GPS or Bluetooth)

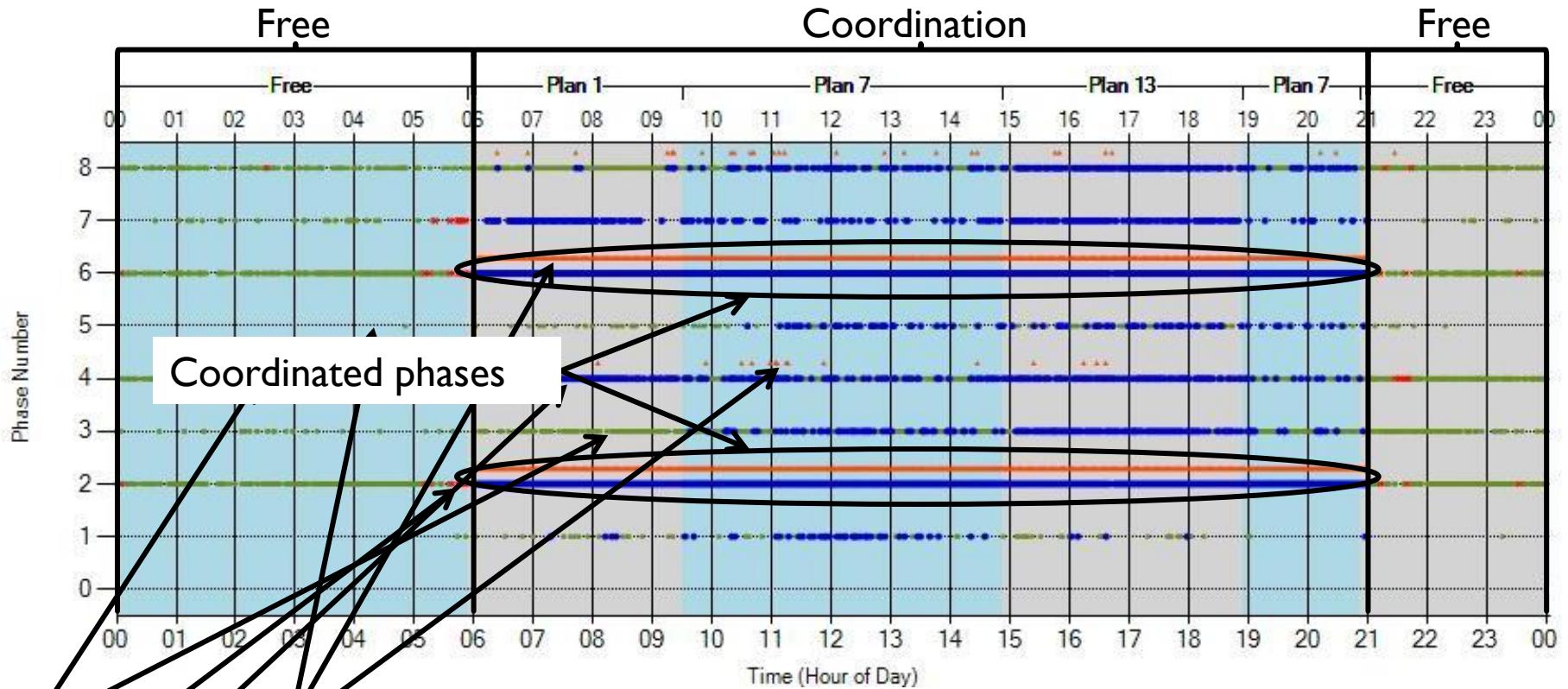
Purdue Travel Time Diagram

# UDOT Case Studies

- ▶ Complaints
- ▶ Maintenance
- ▶ Alerts
- ▶ Optimization

# Normal Intersection Example: Phase Termination Chart

- 8-phase signal with working detection

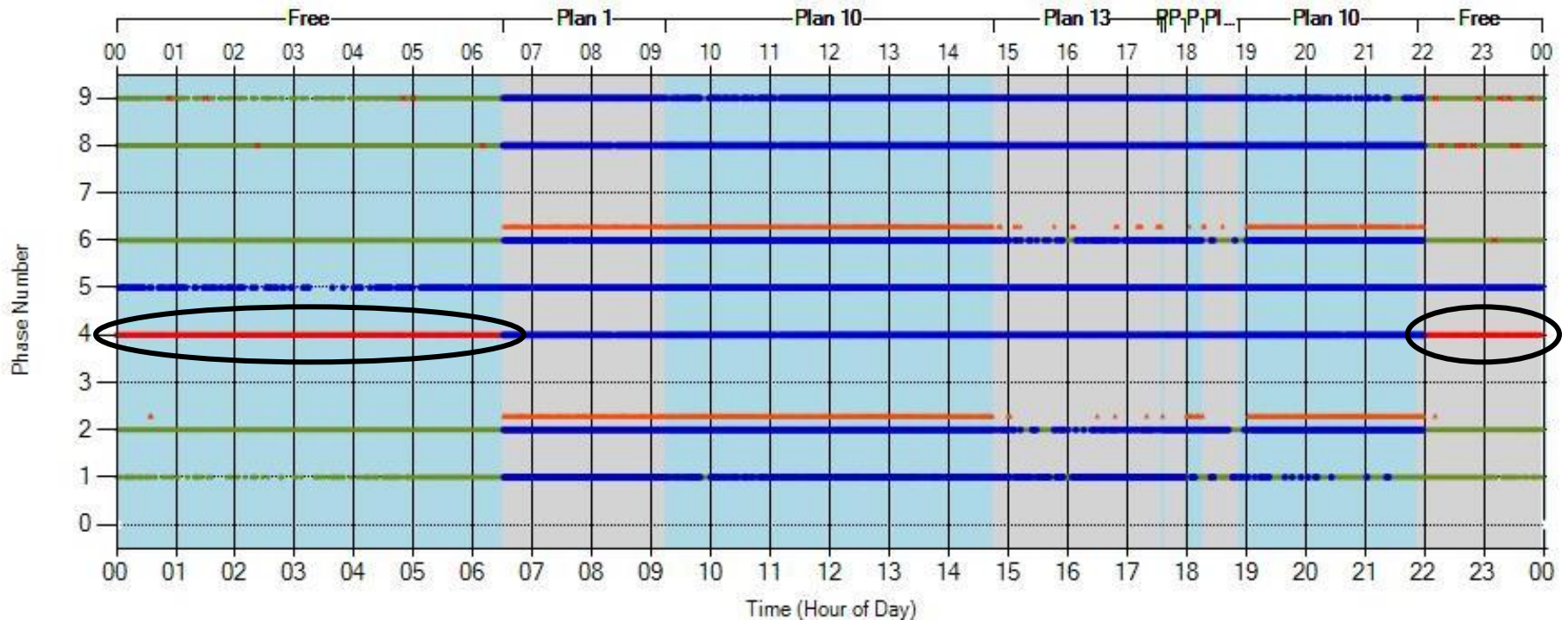


- Gap out
- Max out
- Force off
- Pedestrian activation (shown above phase line)
- Skip

**Metric: Phase Termination Chart**  
**Detection Requirements: None**

# Complaint Example: Red light too long

- ▶ Max recall was placed for broken NB detection

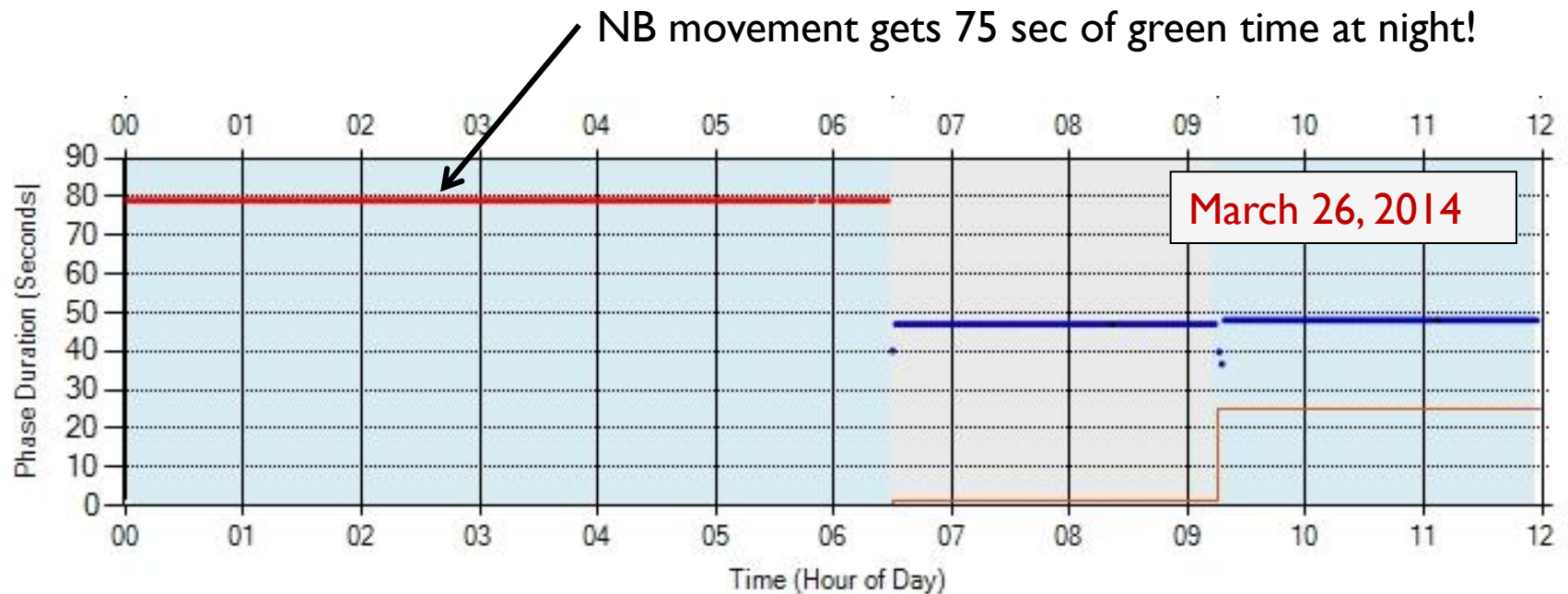


- Gap out
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Phase Termination Chart**  
**Detection Requirements: None**

# Complaint Example: Red light too long

- ▶ Max recall was placed for broken NB detection

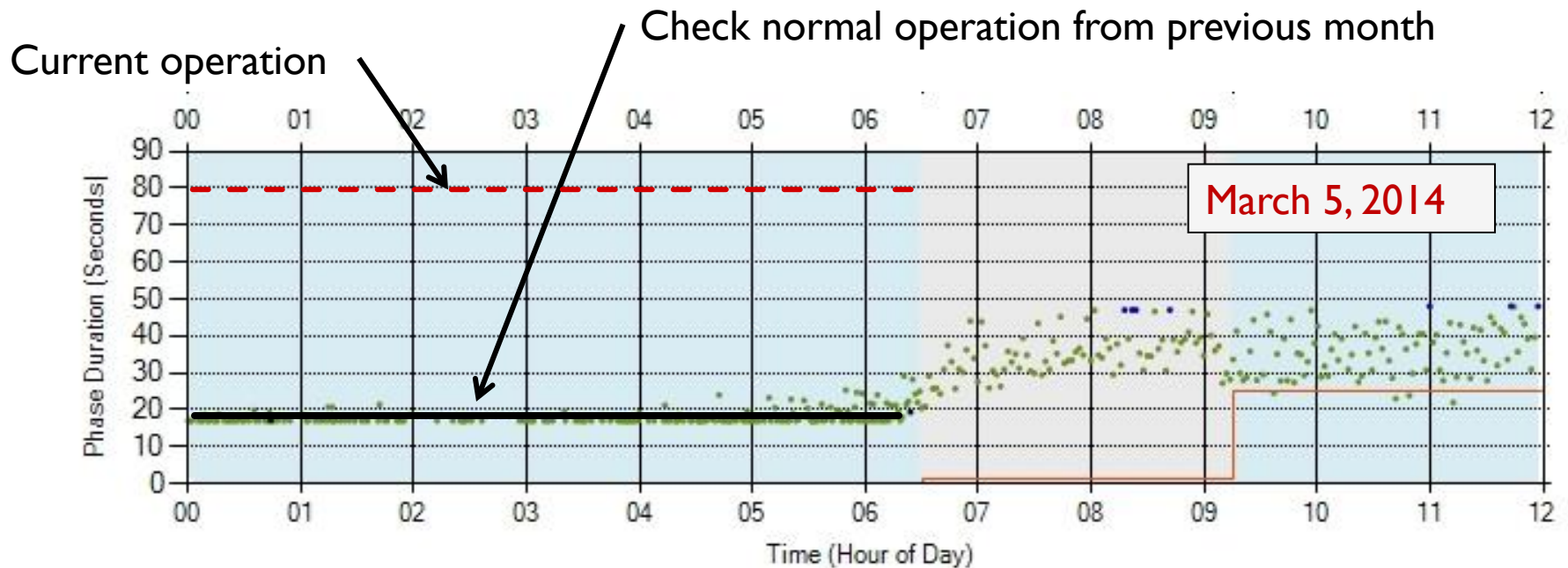


- Gap out
- Max out
- Force off
- Pedestrian activation (shown above phase line)
- Skip

**Metric: Split Monitor**  
**Detection Requirements: None**

# Complaint Example: Red light too long

- ▶ Max recall was placed for broken NB detection



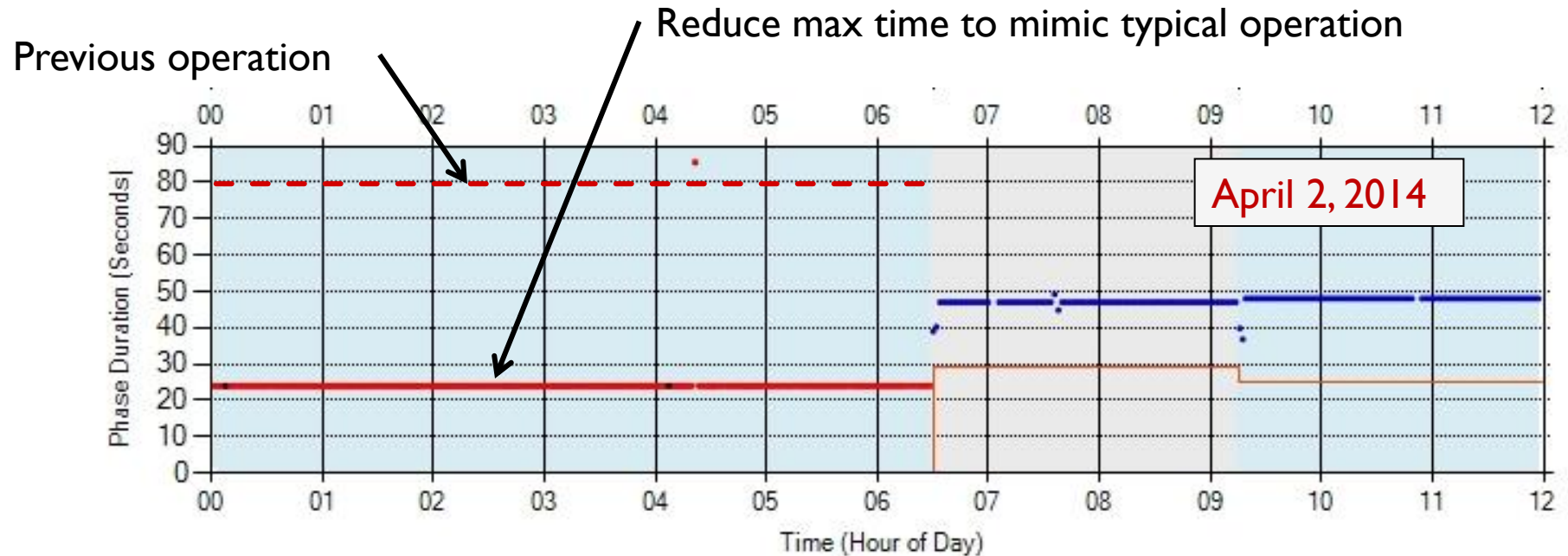
- Gap out
- Pedestrian activation  
(shown above phase line)
- Max out
- Skip
- Force off

**Metric: Split Monitor**  
**Detection Requirements: None**



# Complaint Example: Red light too long

- ▶ Max recall was placed for broken NB detection



- Gap out
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Split Monitor**  
**Detection Requirements: None**

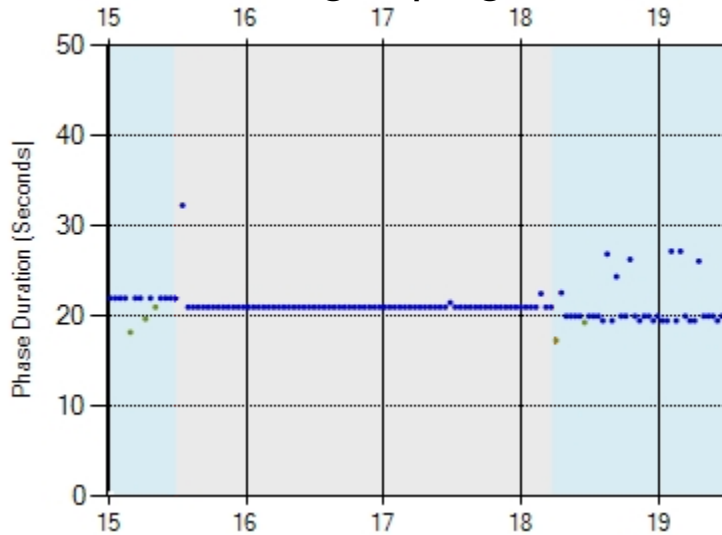
# Complaint Example: Split too short

► Is this a timing or a maintenance issue?

Timing Issue:

Phase always forces off

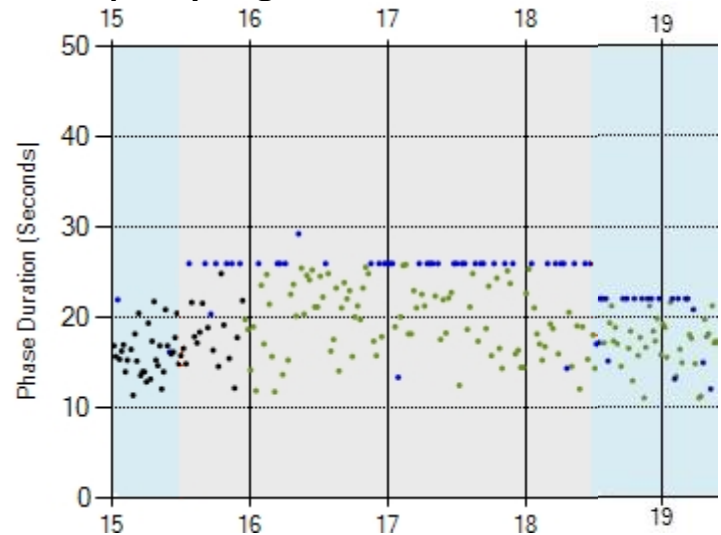
=> Phase is using all programmed time



Maintenance Issue:

Phase often gaps out

=> Spotty right-turn lane detection

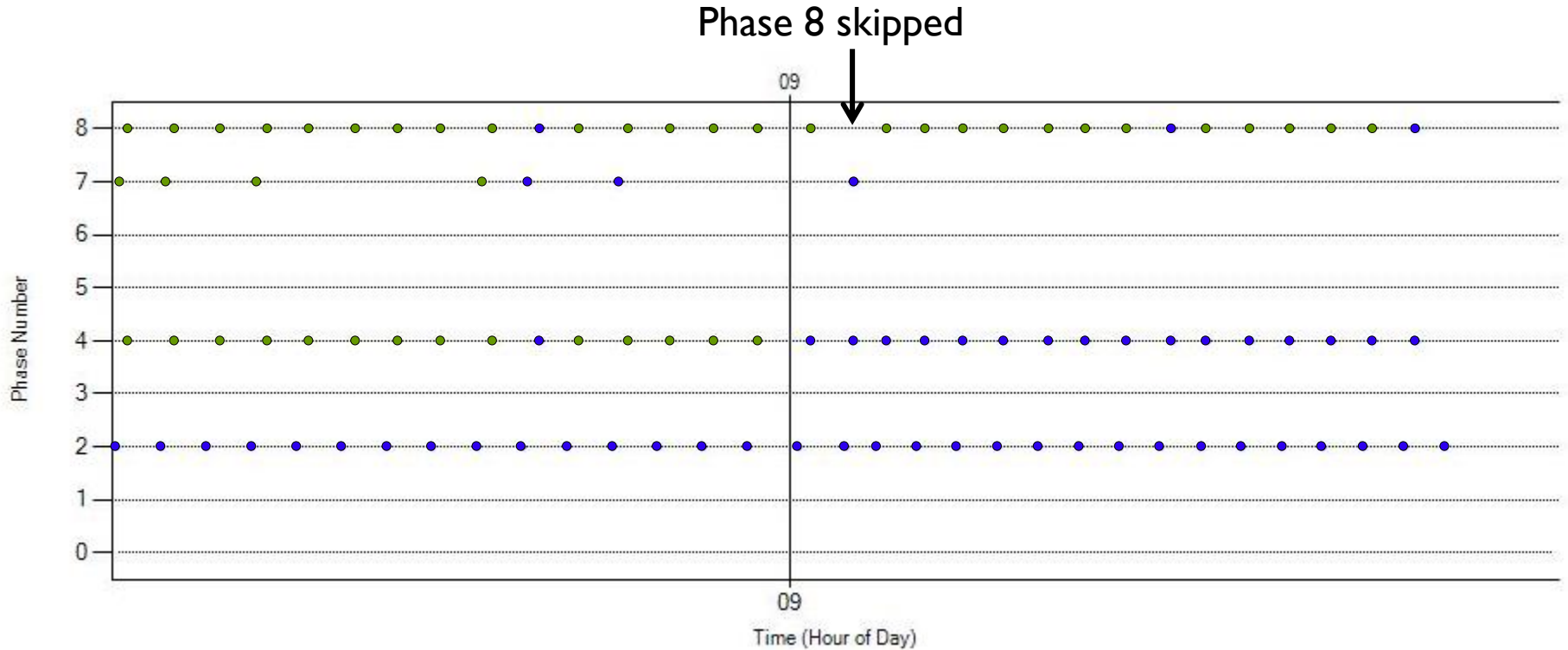


- Gap out
- Pedestrian activation  
(shown above phase line)
- Max out
- Skip
- Force off

**Metric: Split Monitor**  
**Detection Requirements: None**

# Complaint Example: Phase skipped

- ▶ SPMs confirm it was a fluke

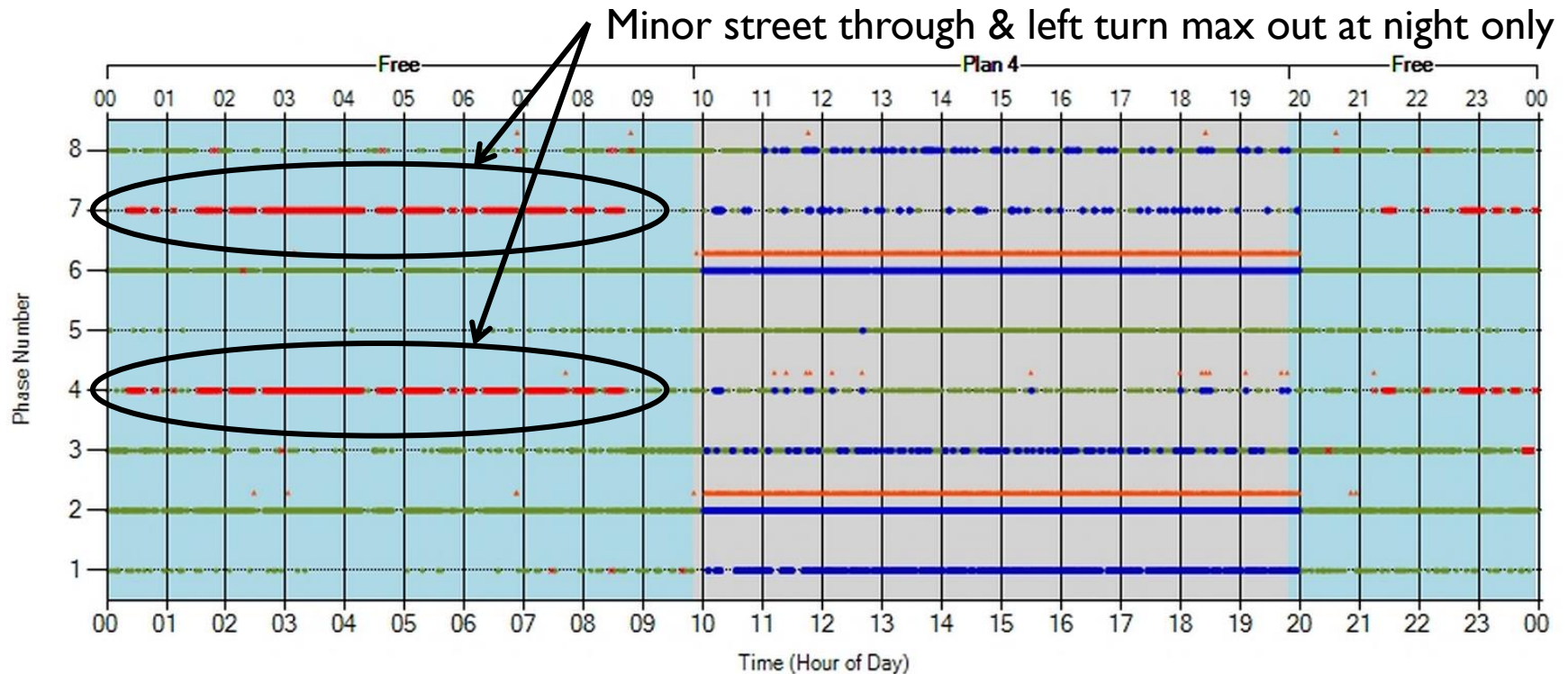


- Gap out
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination  
Detection Requirements: None**

# Maintenance Example: Nighttime detection problem

- ▶ BEFORE: Video detection not working at night

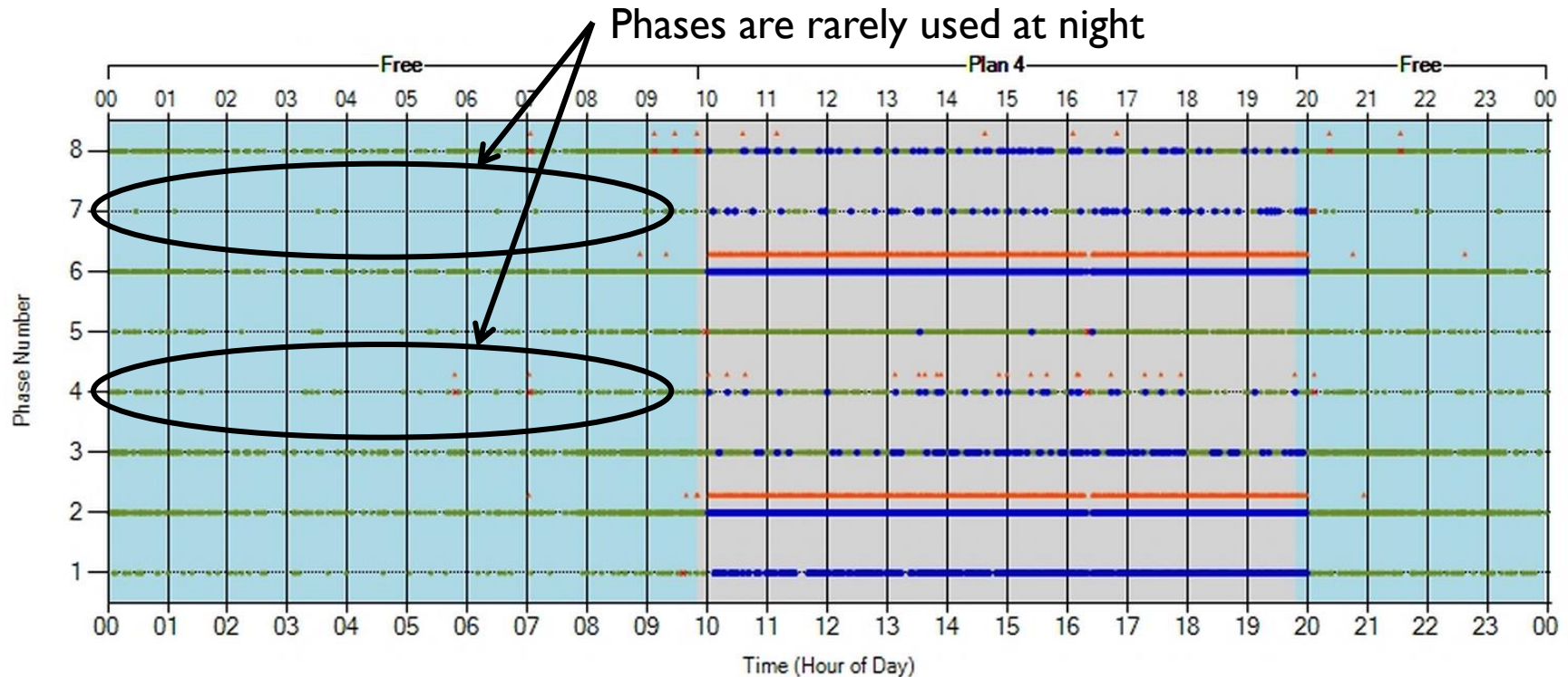


- Gap out
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination  
Detection Requirements: None**

# Maintenance Example: Nighttime detection problem

- ▶ AFTER: New detection technology installed



- Gap out
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination  
Detection Requirements: None**

# Maintenance Example: Check for additional problems

- Phase 2 ped problem was not noticed at field visit



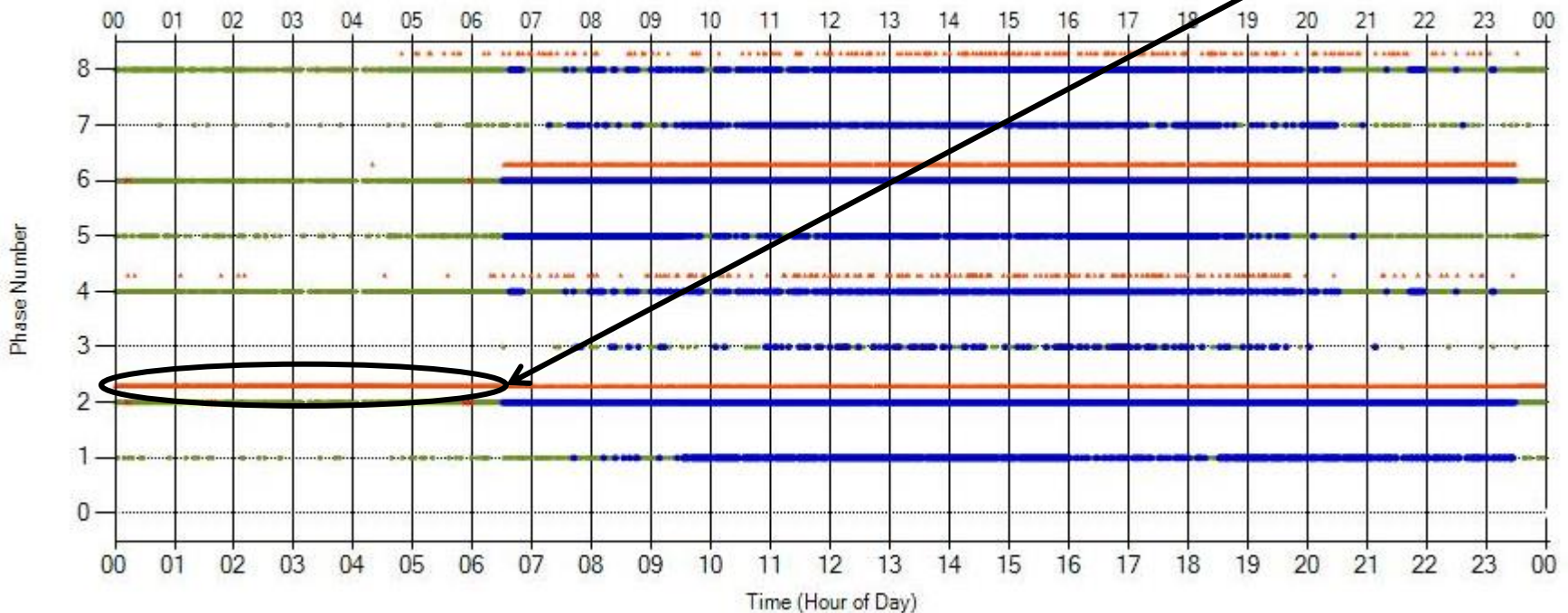
- Gap out
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination  
Detection Requirements: None**

# Maintenance Example: Check for additional problems

- Phase 2 ped problem was not noticed at field visit

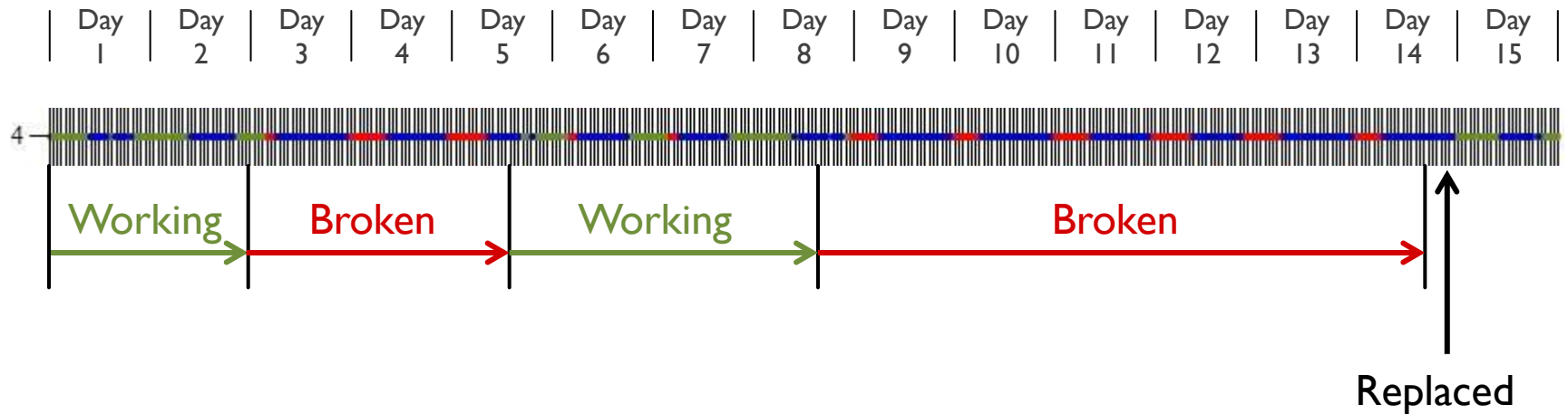
10/21/2013: Phase 3 & 8 problems were fixed, but not Phase 2 ped



**Metric: Purdue Phase Termination  
Detection Requirements: None**

# Maintenance Example: Detection Upgrade Justification

- Document recurring detection problems



- Gap out
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination**  
**Detection Requirements: None**



# Alert Example: 100% Max Out

## SPM Alerts for 4/9/2014

SPMWatchDog@utah.gov

5092 - SR-126 (1900 W) & Riverdale (5300 S) (Roy) - Phase: 1  
5105 - Antelope (SR-108/2000 N) & I-15 NB (Layton) - Phase: 4  
6022 - US-89 & Pacific Dr (American Fork) - Phase: 3  
6305 - 400 East & 800 North - Phase: 4  
6310 - Center Street (Orem) & I-15 SPUI - Phase: 8  
7055 - Bangerter Hwy (SR-154) & SR-201 DDI - Phase: 5  
7062 - Bangerter Hwy (SR-154) & 4700 South - Phase: 11  
7613 - 10600 South & 700 West - Phase: 8  
8114 - Bluff Street & I-15 NB Ramps - Phase: 4

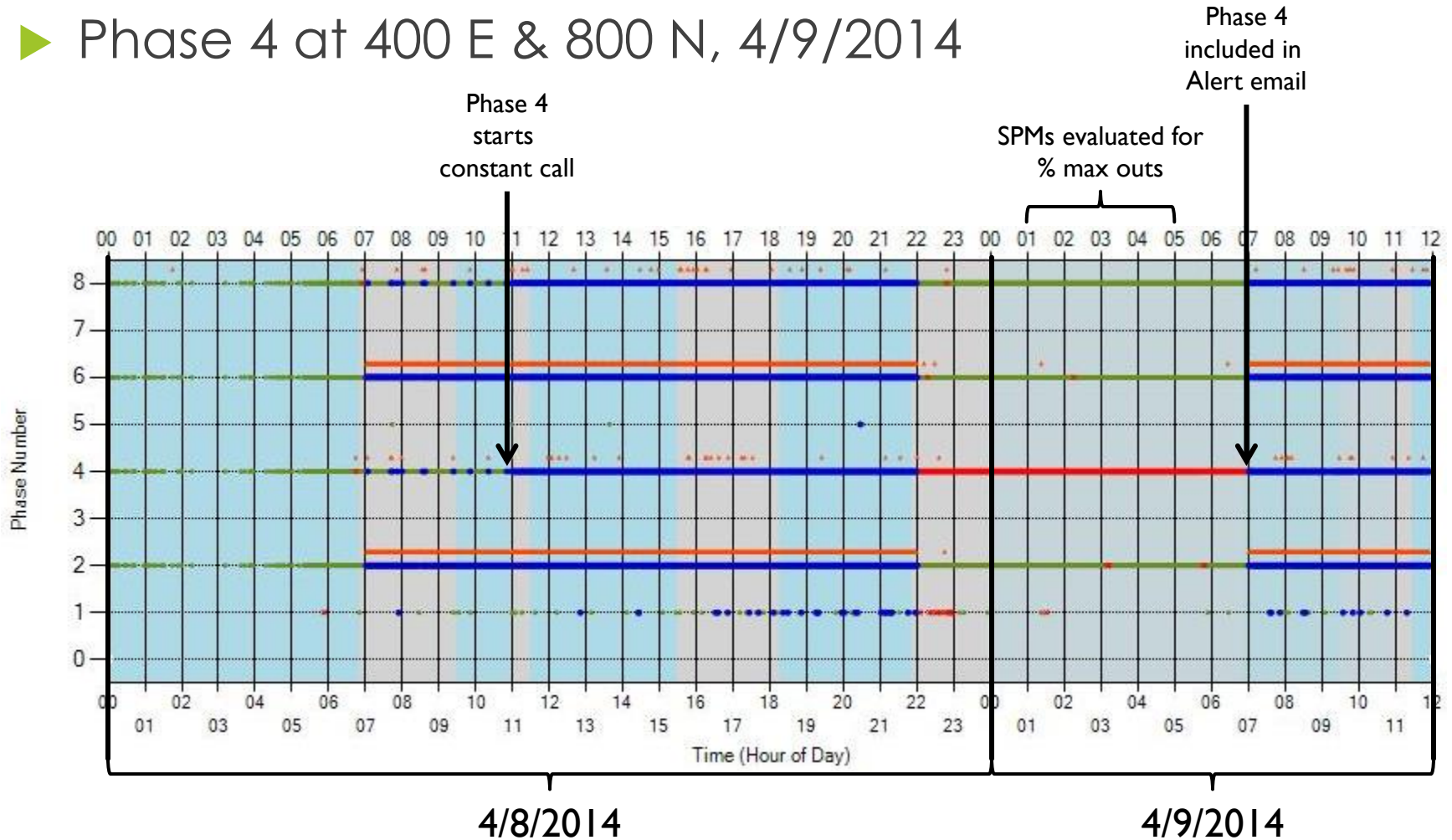
Example

- ▶ Daily email at 7 a.m.
- ▶ Uses Purdue Phase Termination chart data
- ▶ Flags phases with >90% max-outs on each phase between 1 a.m. and 5 a.m.
- ▶ Compare to previous day's list. Only phases with new flags are sent in the email.

**Metric: Purdue Phase Termination  
Detection Requirements: None**

# Alert Example: 100% Max Out

► Phase 4 at 400 E & 800 N, 4/9/2014



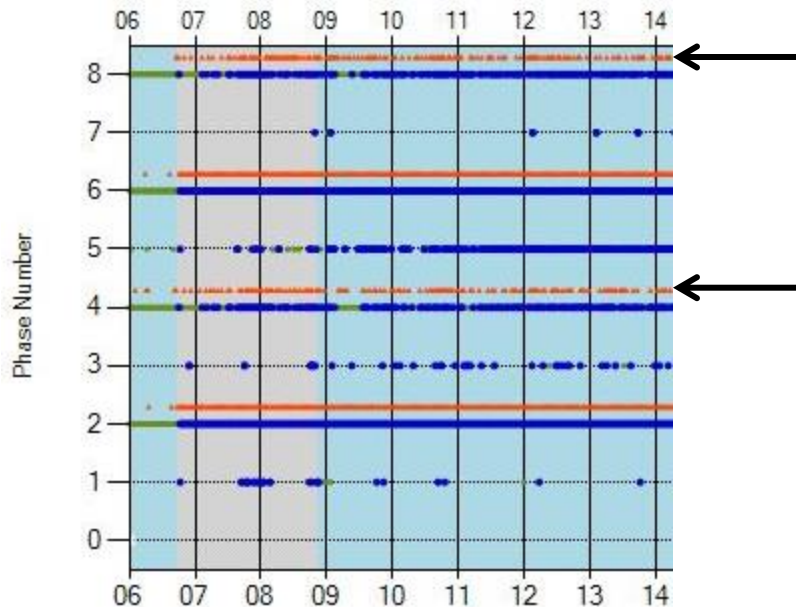
- Gap out
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination  
Detection Requirements: None**

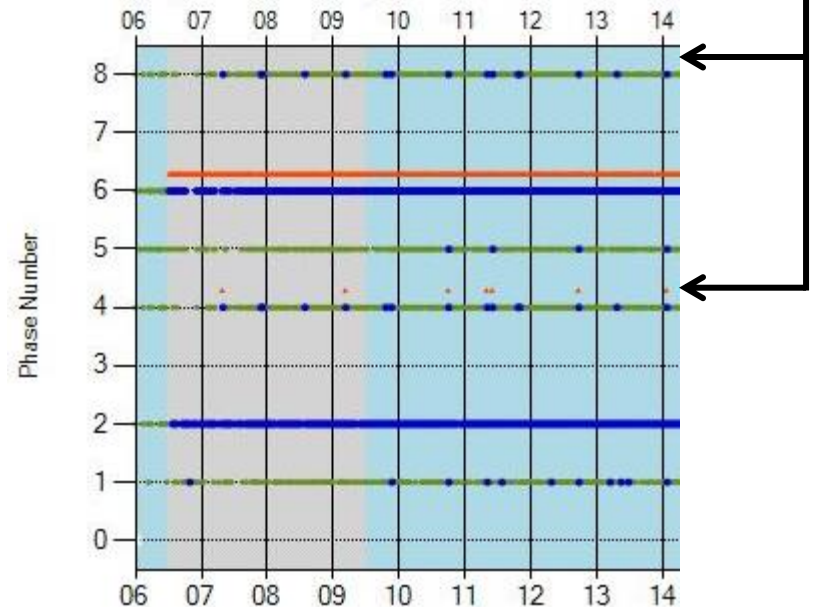
# Optimization Example: Oversize Peds

- Check frequency of ped calls

Peds for Phases 4 & 8 are called **frequently**  
Recommendation: Do not oversize peds



Peds for Phases 4 & 8 are **rarely** called  
Recommendation: Oversize peds, if needed

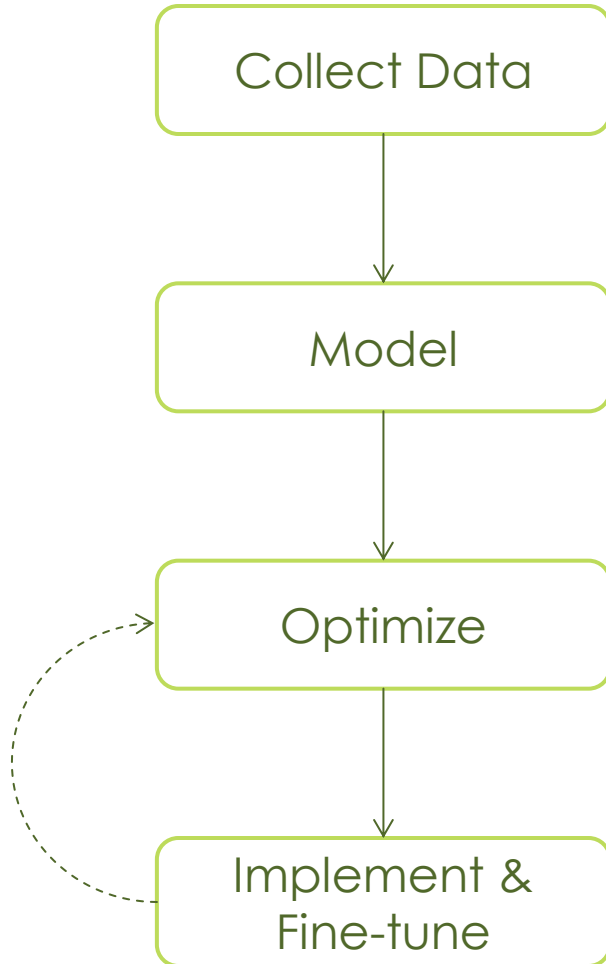


- Gap out
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

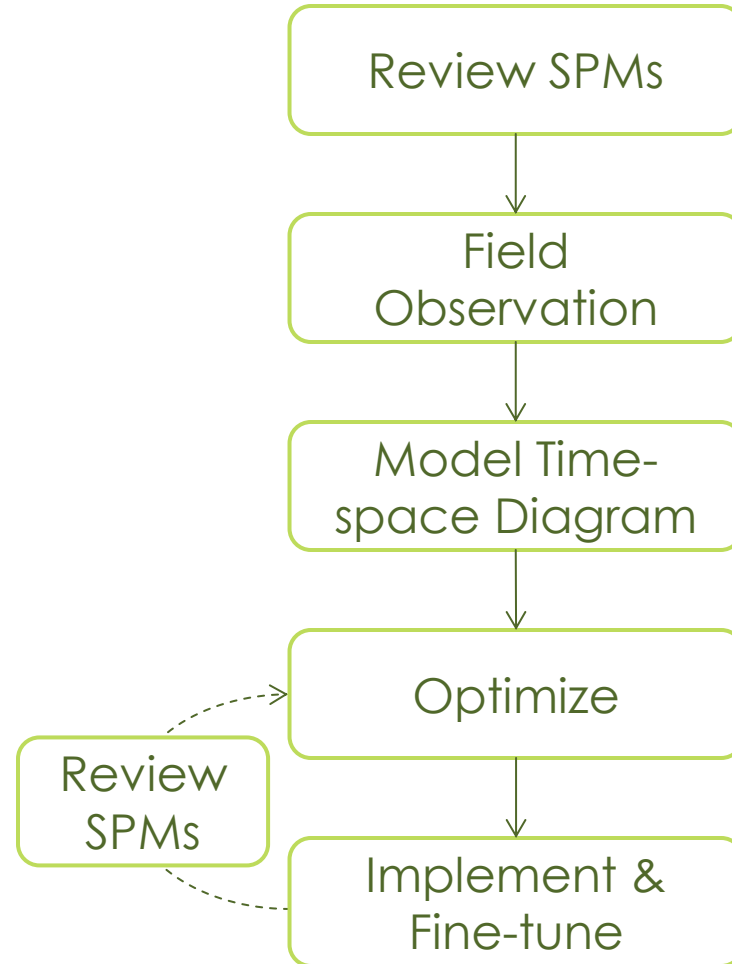
**Metric: Purdue Phase Termination**  
**Detection Requirements: None**

# Optimization with SPMs

## Traditional Process



## Modified Process with SPMs



# Before and After Coordination Results

Corridor: Bangerter Hwy, SLC

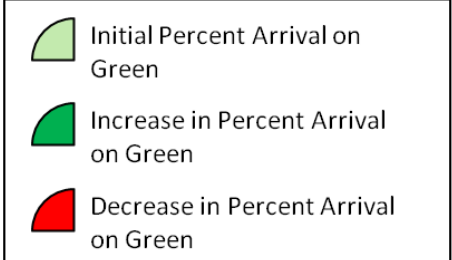
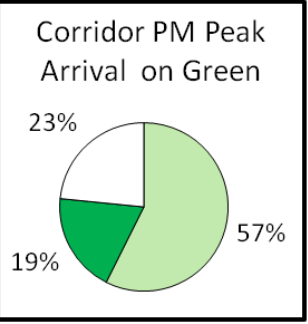
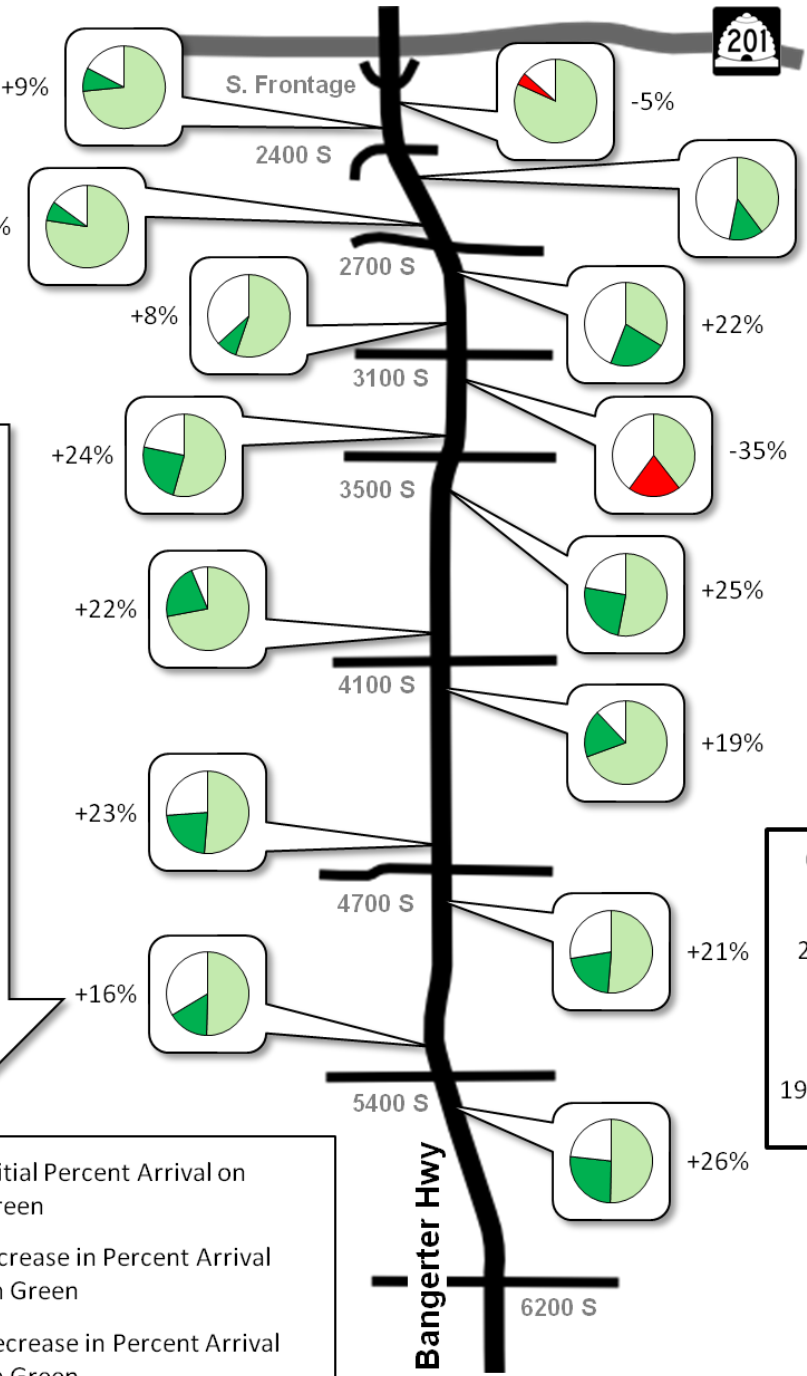
To/From: SR-201 - 6200 South

Date: March 2013

Time Period: PM Peak

## Results:

- Arrivals on Green: 19% ↑
- NB TT Savings: 0.3 Minutes
- NB Reliability: 55% ↑
- SB TT Savings: 1.1 Minute
- SB Reliability: 52% ↑



**Metric 1: Purdue Coordination Diagram**  
**Detection Requirements: Advance**  
**Metric 2: Purdue Travel Time Diagram**  
**Requirements: Probe data set**

# AUTOMATED TRAFFIC SIGNAL PERFORMANCE MEASURES CASE STUDIES: INDOT



**INSTITUTE OF TRANSPORTATION ENGINEERS WEBINAR PART 1 – MAY 7, 2014**

PRESENTED BY AMANDA STEVENS, INDOT AND ALEX HAINEN, PURDUE

### Active Phase Events:

0	Phase On
1	Phase Begin Green
2	Phase Check
3	Phase Min Complete
4	Phase Gap Out
5	Phase Max Out
6	Phase Force Off
7	Phase Green Termination
8	Phase Begin Yellow Clearance
9	Phase End Yellow Clearance
10	Phase Begin Red Clearance
11	Phase End Red Clearance

### Detector Events:

81	Detector Off
82	Detector On
83	Detector Restored
84	Detector Fault- Other
85	Detector Fault- Watchdog Fault
86	Detector Fault- Open Loop Fault

### Preemption Events:

101	Preempt Advance Warning Input
102	Preempt (Call) Input On
103	Preempt Gate Down Input Received
104	Preempt (Call) Input Off
105	Preempt Entry Started

# Controller Enumerations

Event Code, Event Description, Parameter

**Detector 5 ON**

06/27/2013 01:29:51.1	10	8
06/27/2013 01:29:51.1	82	5
06/27/2013 01:29:52.2	1	2
06/27/2013 01:29:52.2	1	6
06/27/2013 01:29:52.3	82	2
06/27/2013 01:29:52.8	82	4
06/27/2013 01:29:52.9	81	4
06/27/2013 01:29:53.3	81	6
06/27/2013 01:29:54.5	81	2
06/27/2013 01:30:02.2	8	2
06/27/2013 01:30:02.2	8	6
06/27/2013 01:30:02.2	33	2
06/27/2013 01:30:02.2	33	6
06/27/2013 01:30:02.2	32	2
06/27/2013 01:30:02.2	32	6
06/27/2013 01:30:06.1	10	2
06/27/2013 01:30:06.1	10	6
06/27/2013 01:30:08.1	1	8
06/27/2013 01:30:13.1	32	8
06/27/2013 01:30:15.8	81	5
06/27/2013 01:30:18.5	82	6
06/27/2013 01:30:27.5	81	6
06/27/2013 01:30:30.4	8	8

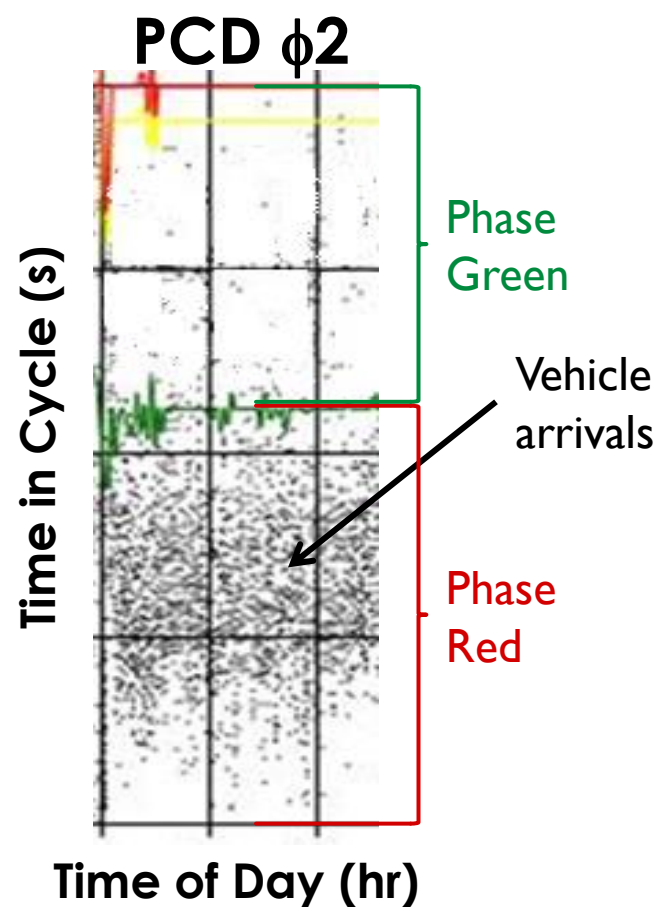
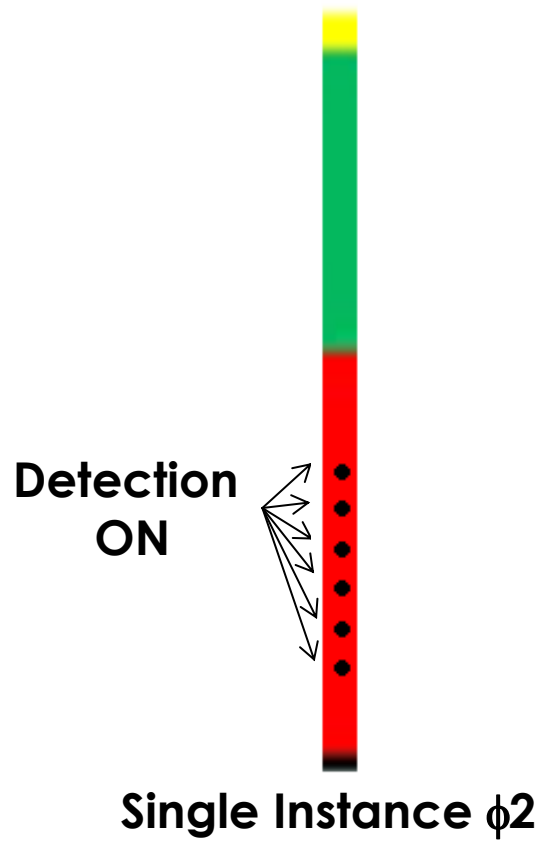
**Phase 8 GREEN**

**Detector 5 OFF**

# High-resolution Data

Timestamp, Enumeration Code, Parameter





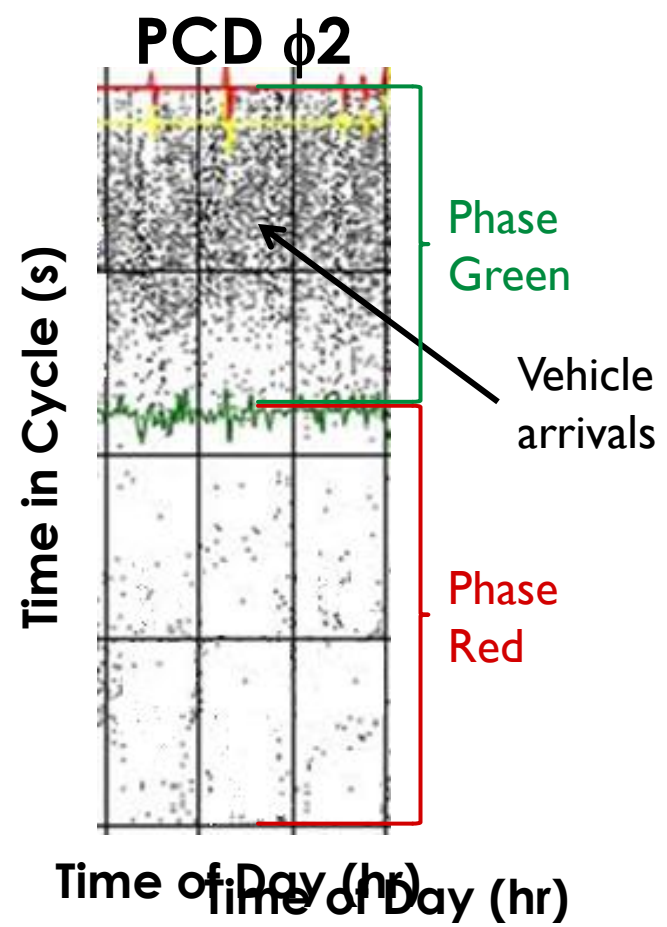
# Purdue Coordination Diagram: Red Arrival



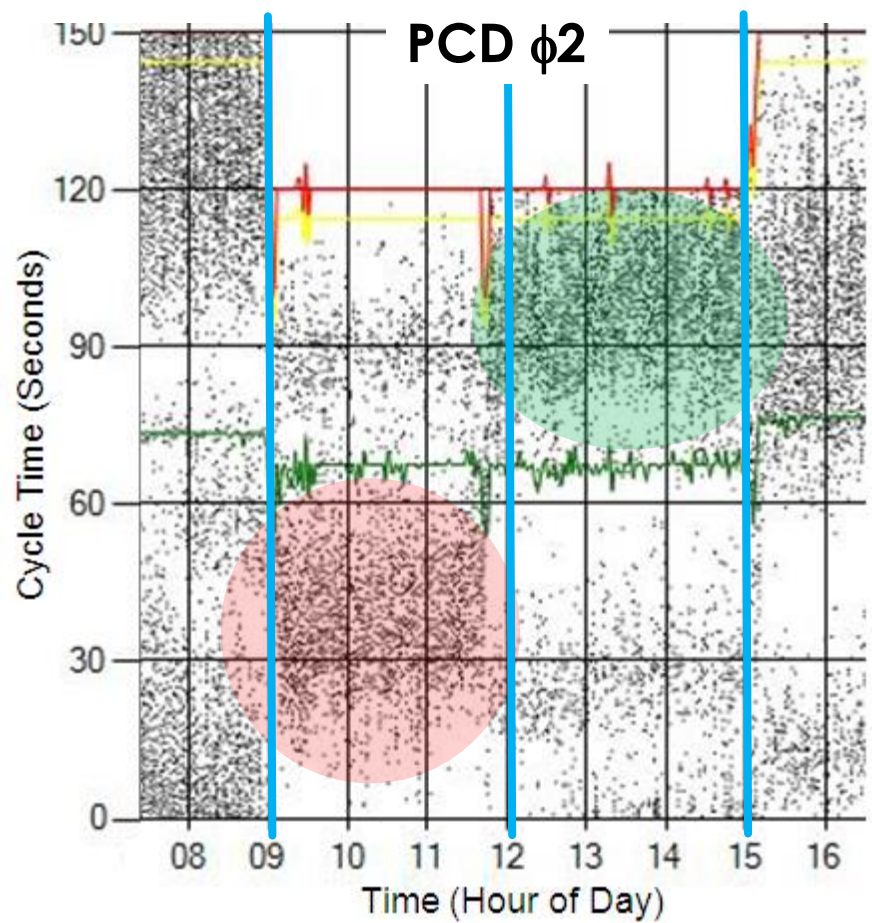
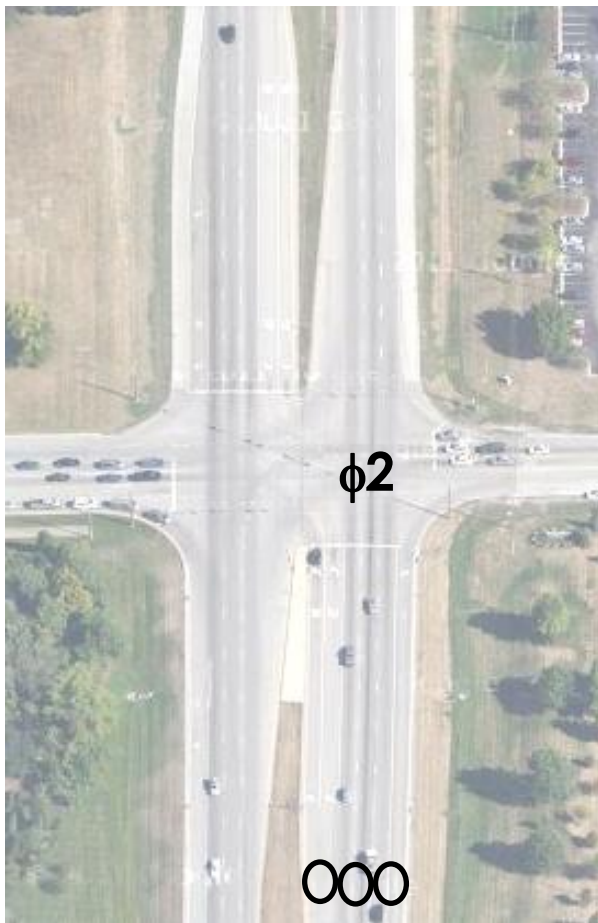
Detection  
ON



Single Instance  $\phi 2$

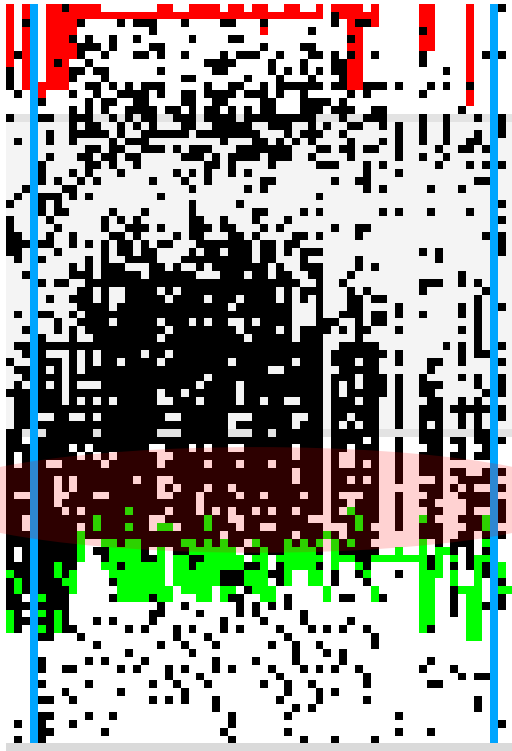


# Purdue Coordination Diagram: Green Arrival



**PCD: Platoon Arrival by  
TOD**

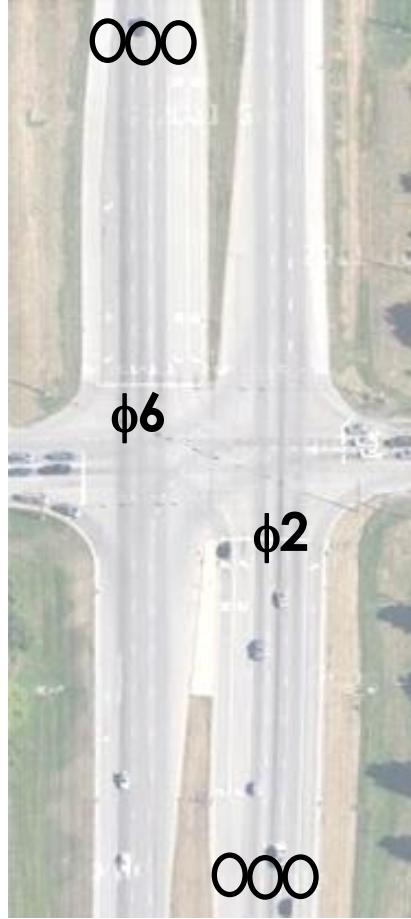
PCD  $\phi 6$



Green  
Band



000

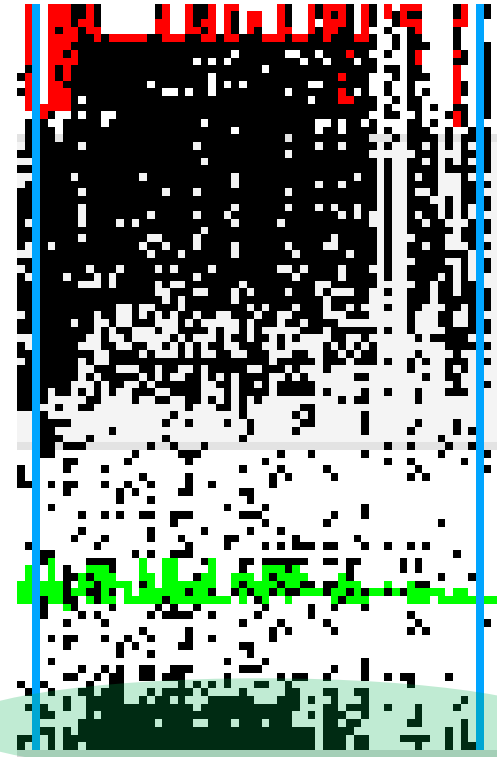


$\phi 6$

$\phi 2$

000

PCD  $\phi 2$



Green  
Band



PCD: Adjust Offsets

# INDOT System

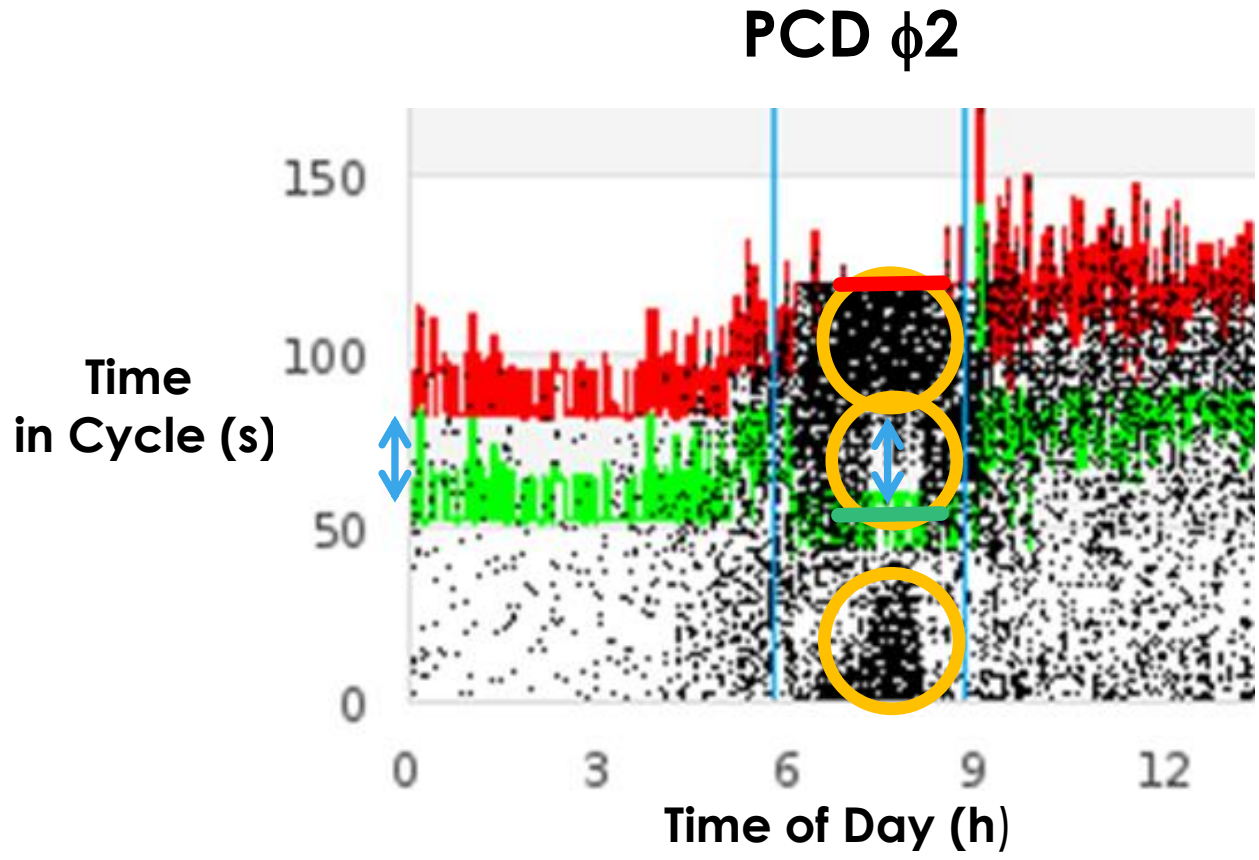
- **# SIGNALS TOTAL**
- **# SIGNALS ONLINE, AUTOMATICALLY STORING DATA & GENERATING PERFORMANCE MEASURE GRAPHS**
- **PEEK ATC, ECONOLITE ASC/3, SIEMENS M50 SERIES...**

# “Human-in-the- Loop- Adaptive”

- **WEEKENDS & OFF-PEAKS**
- **ROUTINE RETIMINGS**
- **CONSTRUCTION SEASON:**
  - You cannot be everywhere at once!
  - Could take Months for traffic to settle
  - Project in Flux:
    - Detection
    - Phases
    - Approaches / Lanes
    - Adjacent construction detours

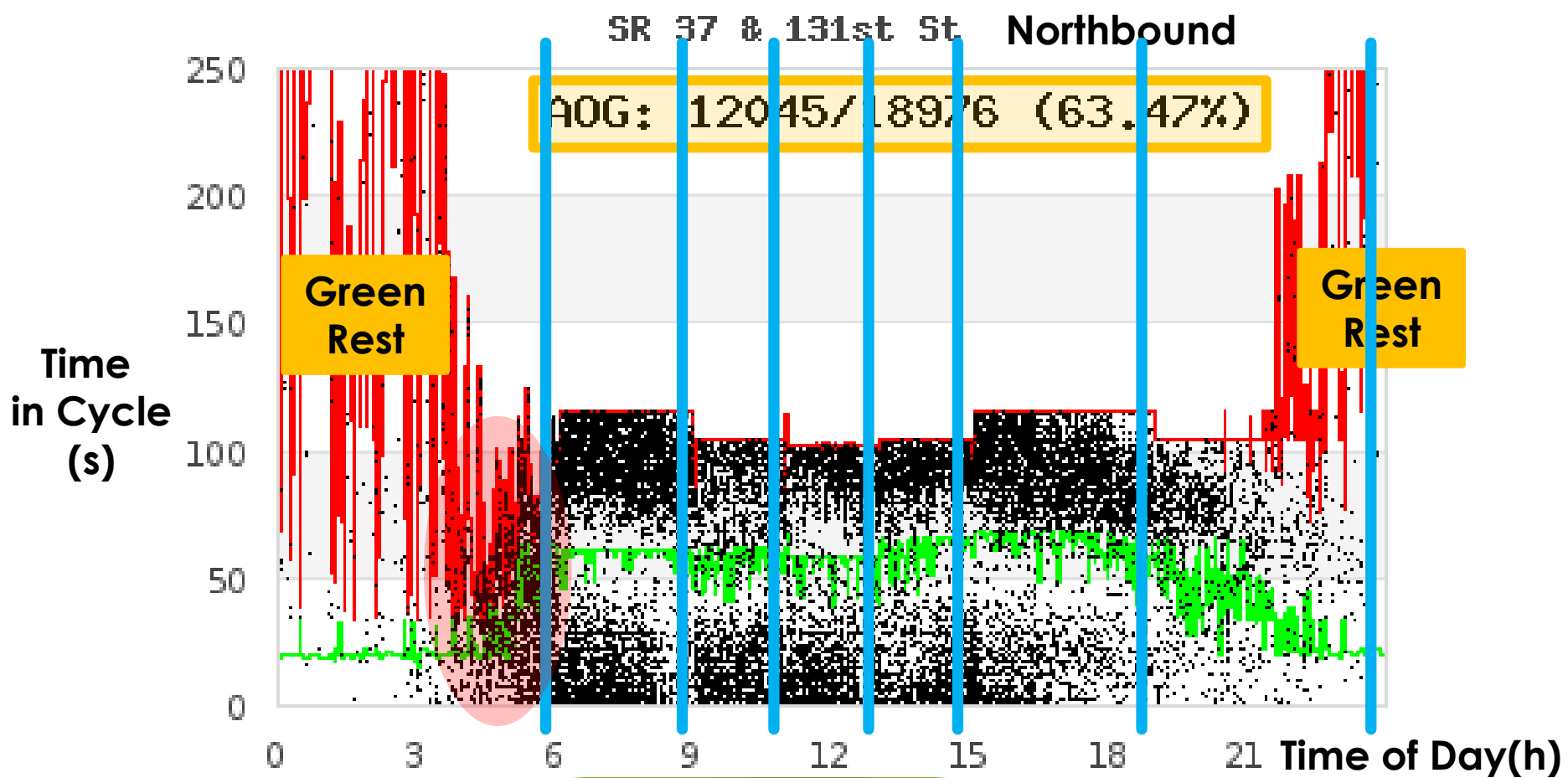
# Moving Forward:

- **CLOSELY-SPACED SIGNALS ALSO NEED ADVANCED DETECTION ON LEFT TURNS**
- **SEPARATE DETECTION CHANNELS FOR EACH LANE**



PCD: Cycle Failure





**PCD: Pattern Start & End Times**



# Hi-resolution Event-based Data for Diamond Interchange Operations

ALEX HAINEN

AMANDA STEVENS

CHRIS DAY

RICK FREIJE

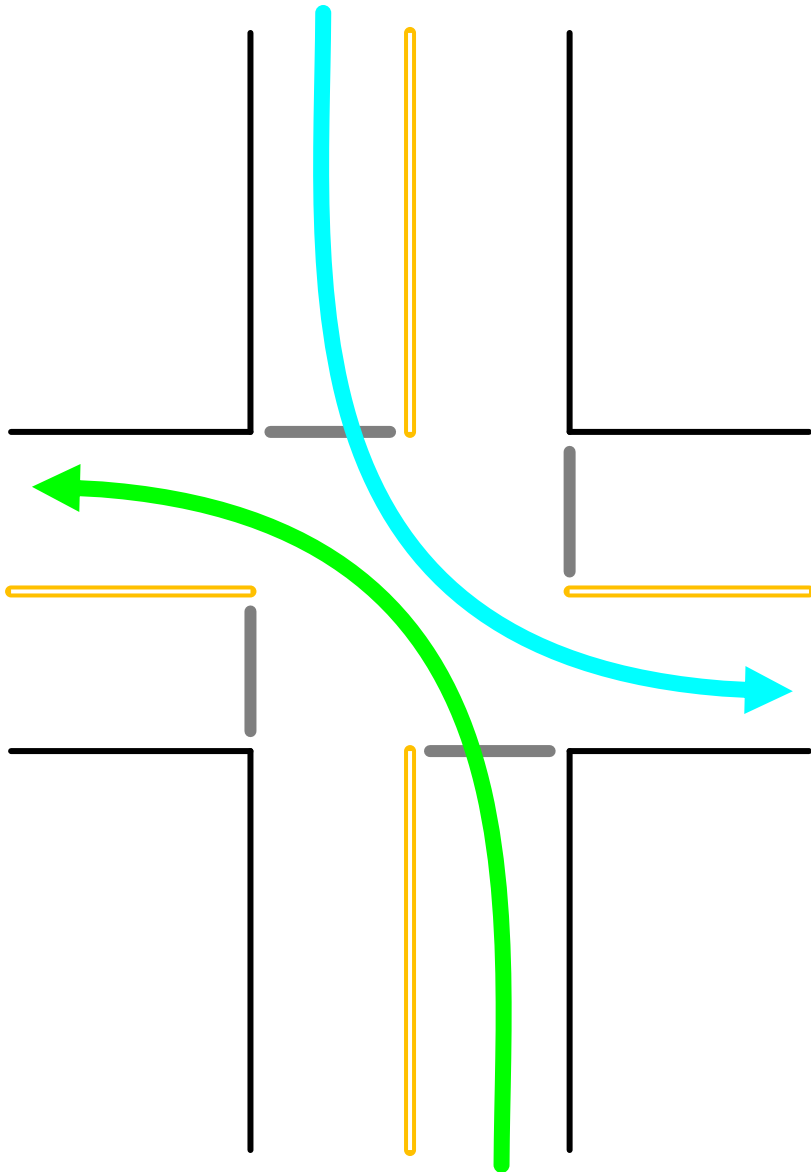
JIM STURDEVANT

DARCY BULLOCK

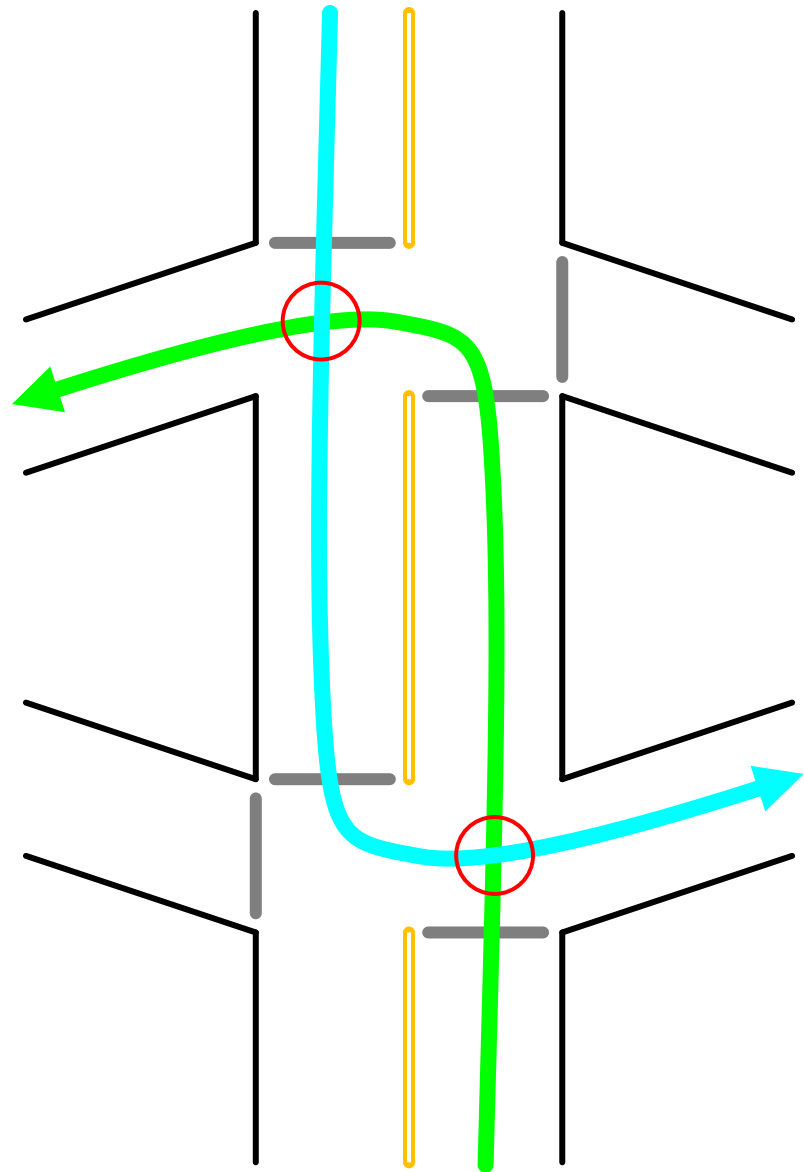
HOWELL LI

# Diamond Interchanges

*What are they and why do they matter?*



Normal Intersection

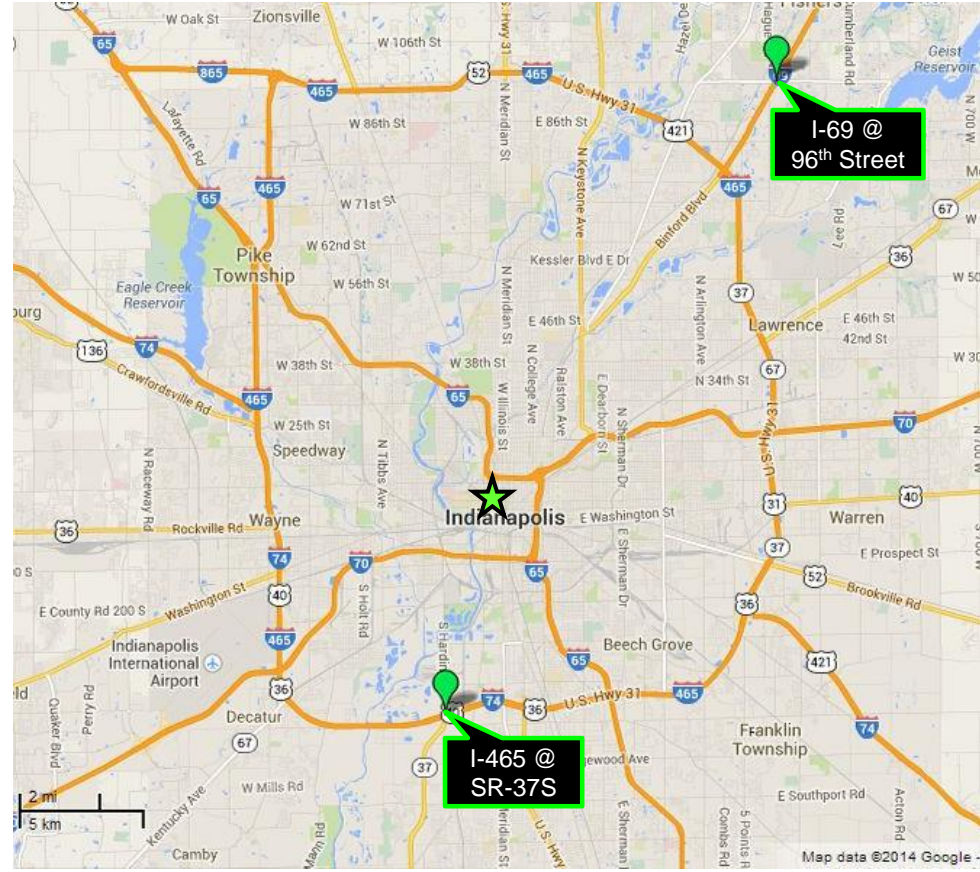
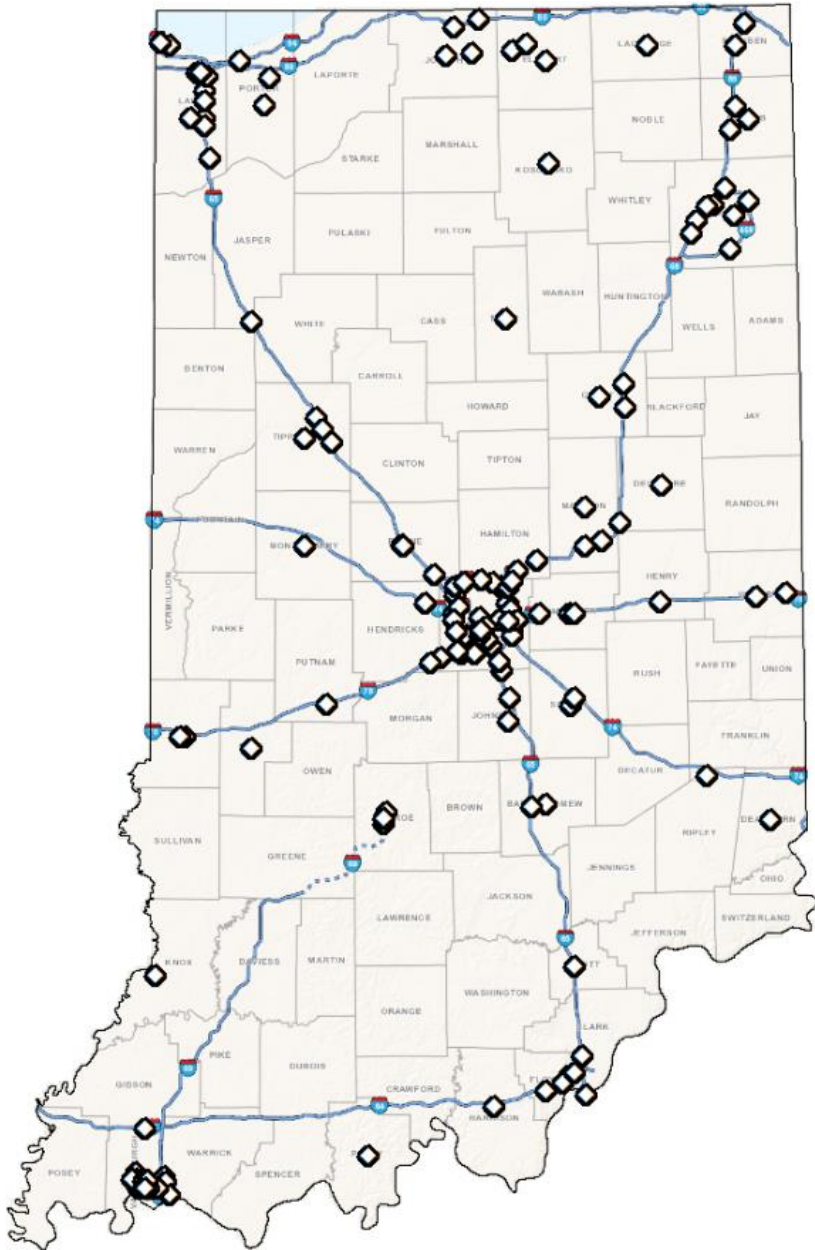


Diamond Interchange

# Diamond Interchanges

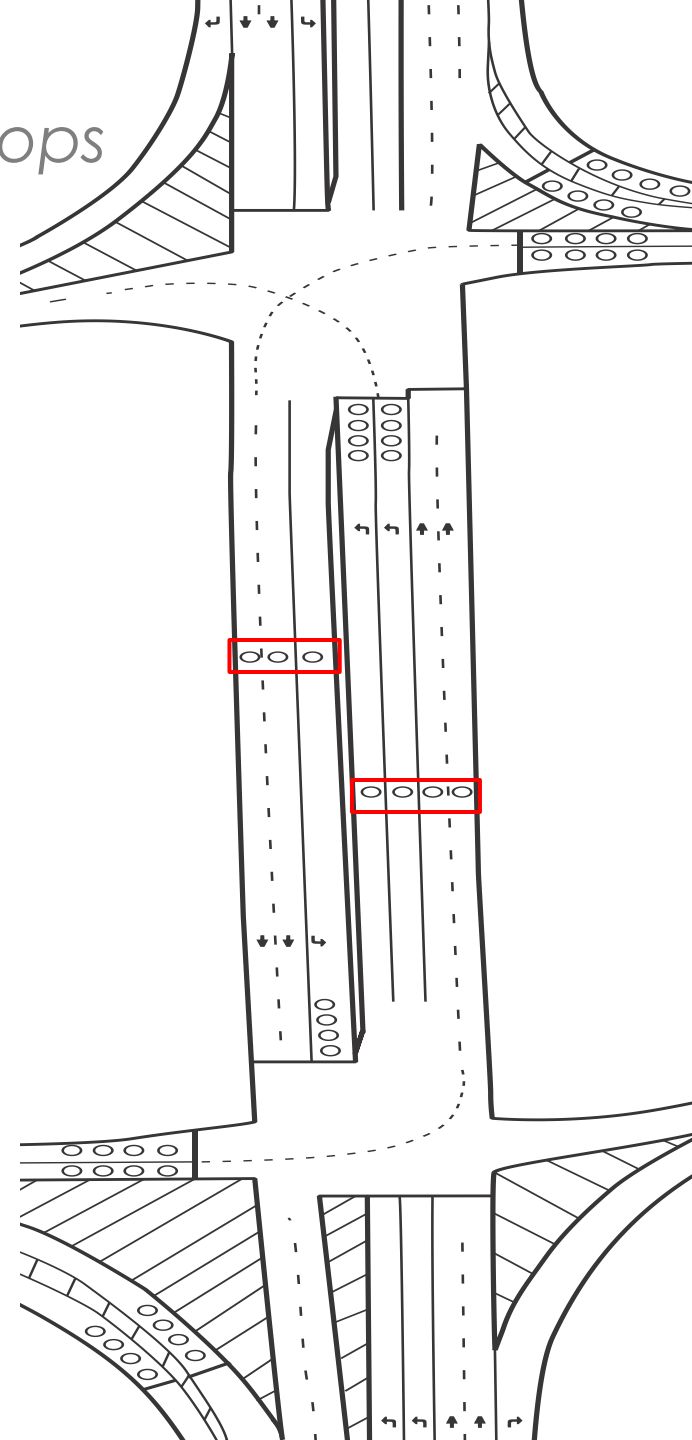
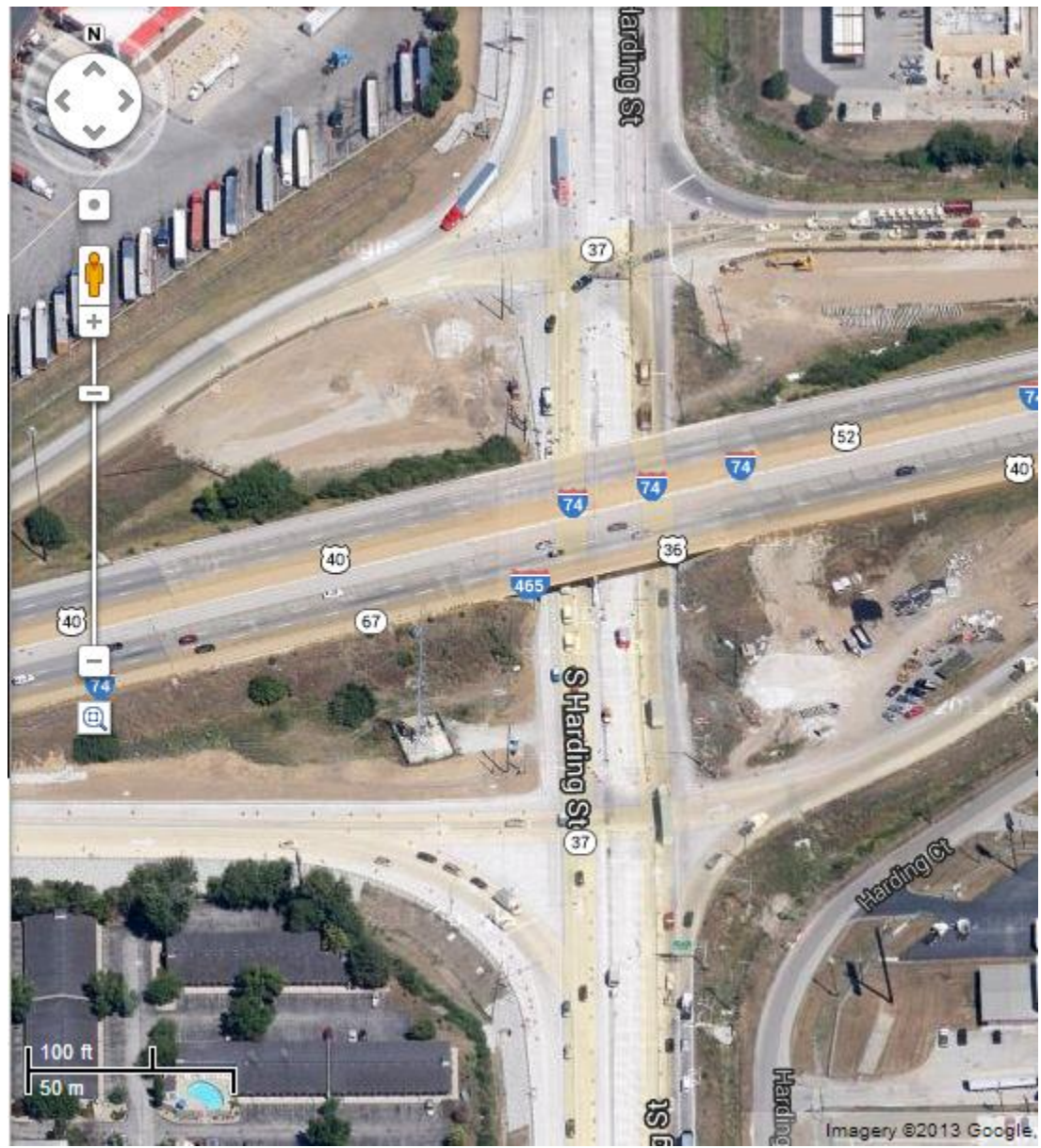
Indiana = 161 Interchanges

Nationally  $\geq 10,000$



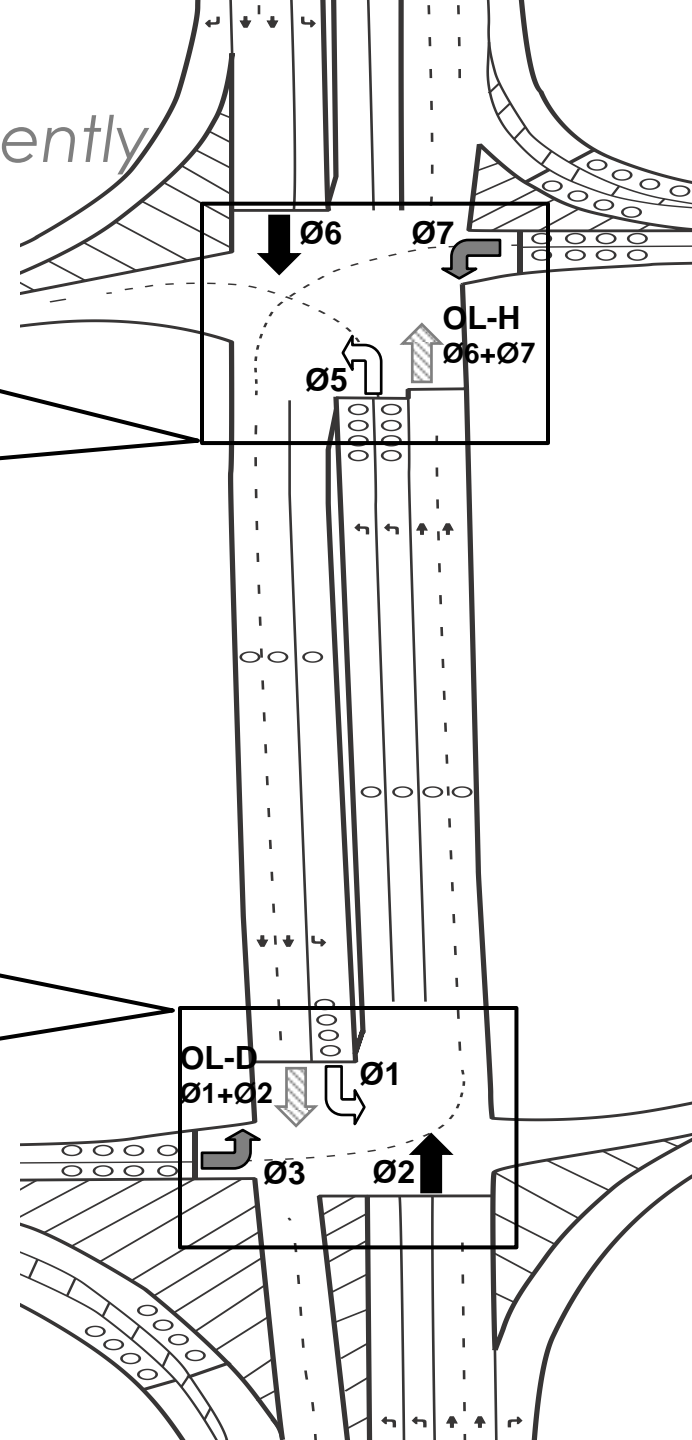
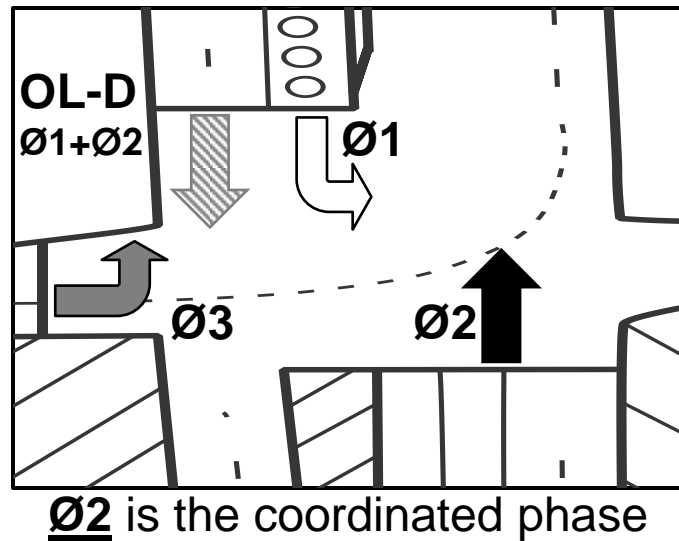
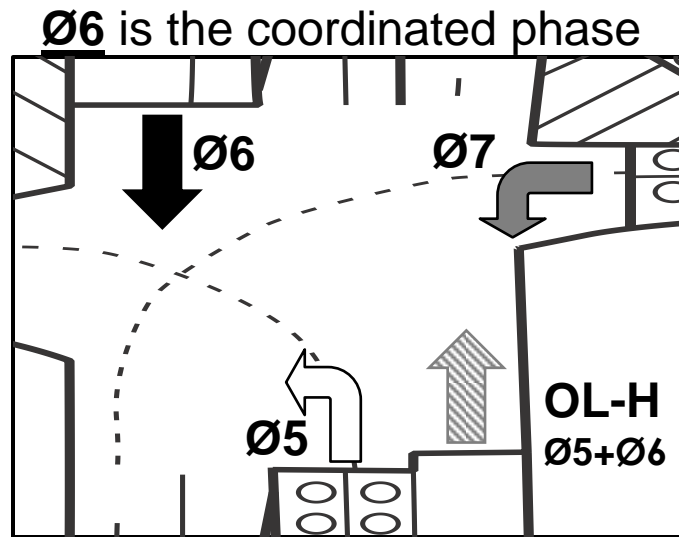
# I-465 @ SR-37

## Diamond Interchange w/Advanced Loops



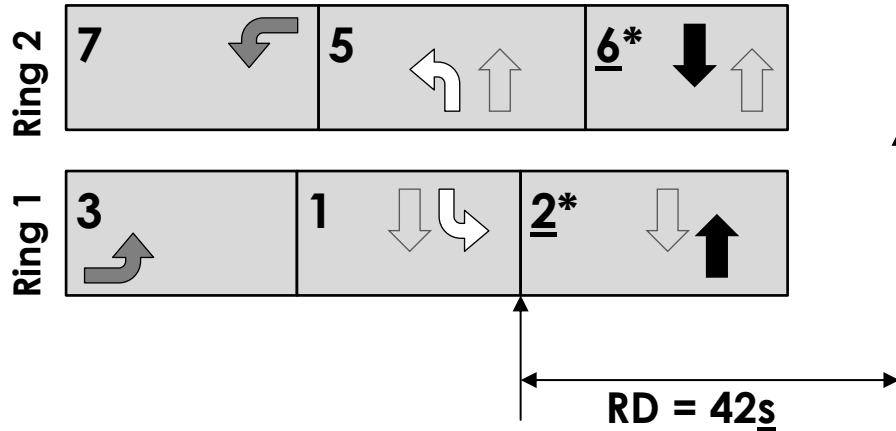
# Phasing

Two "T"-Intersections Treated Independently



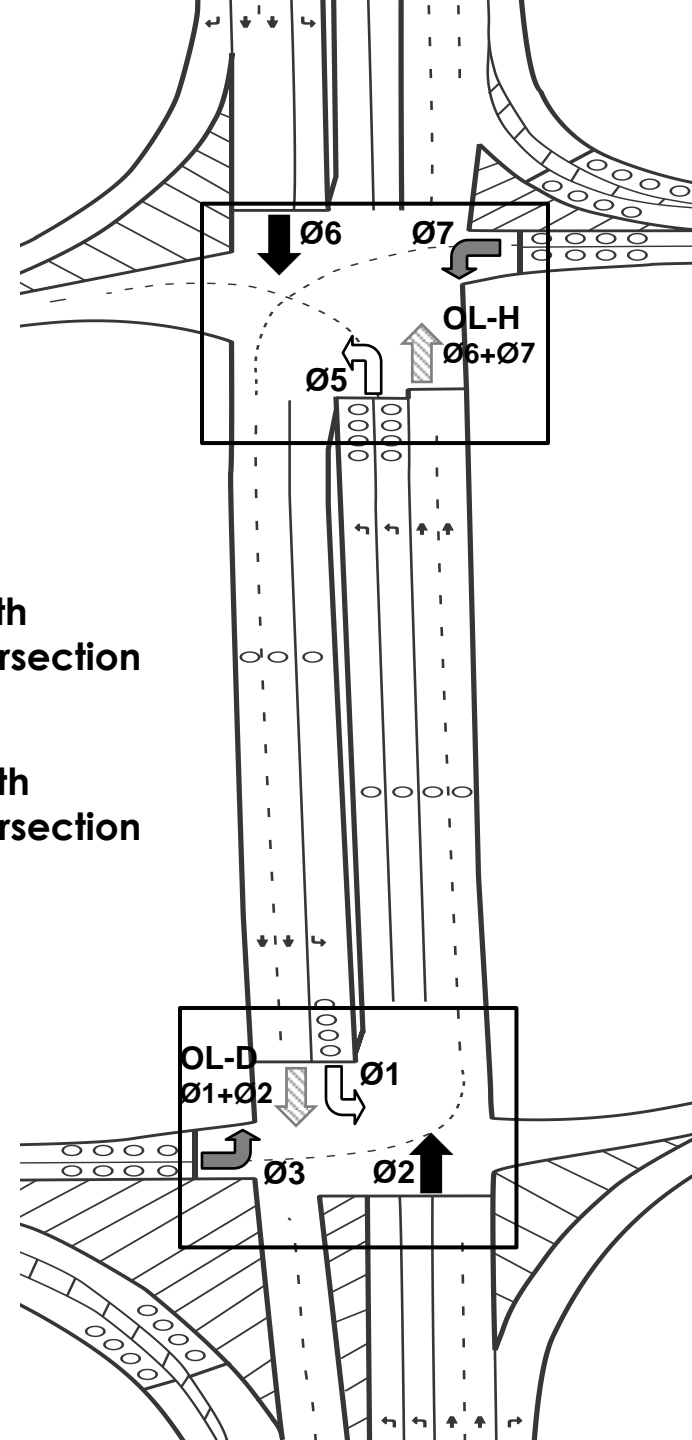
# Ring Displacement

*Offset Between Coordinated Phases*



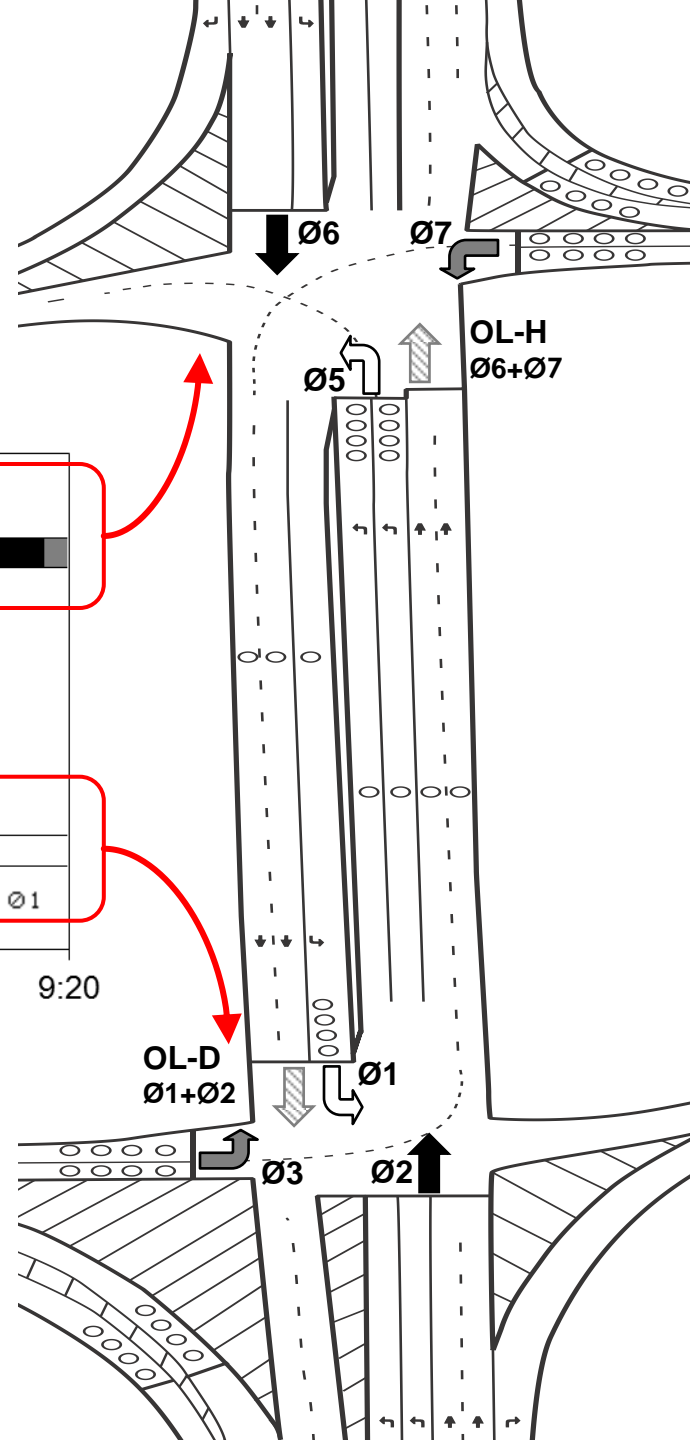
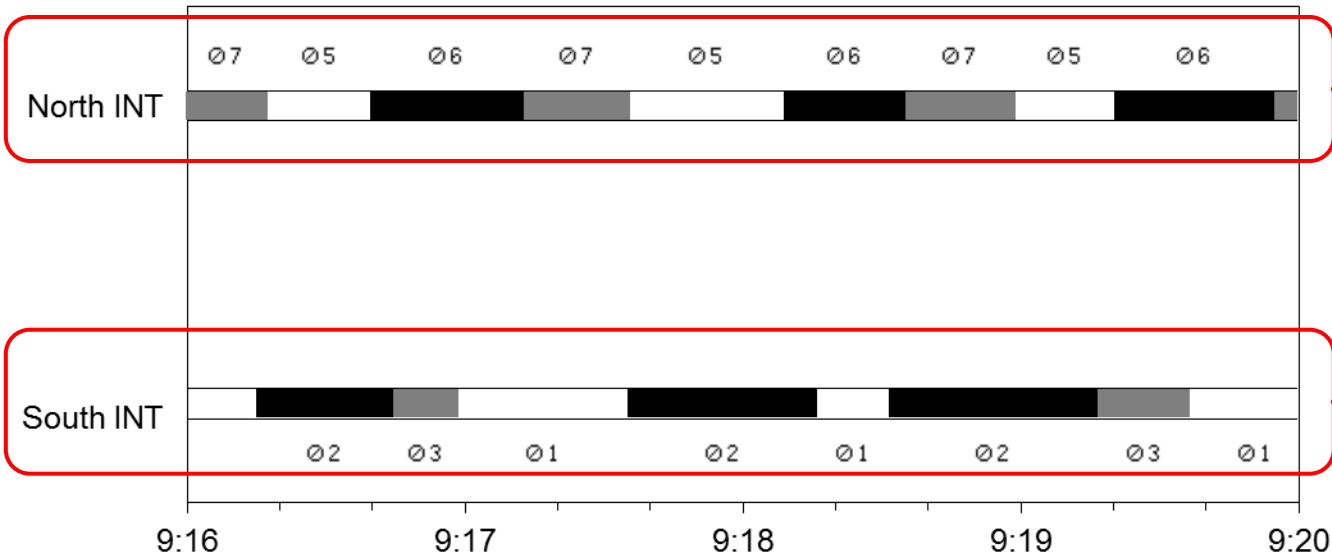
North Intersection

South Intersection



# Ring Structure

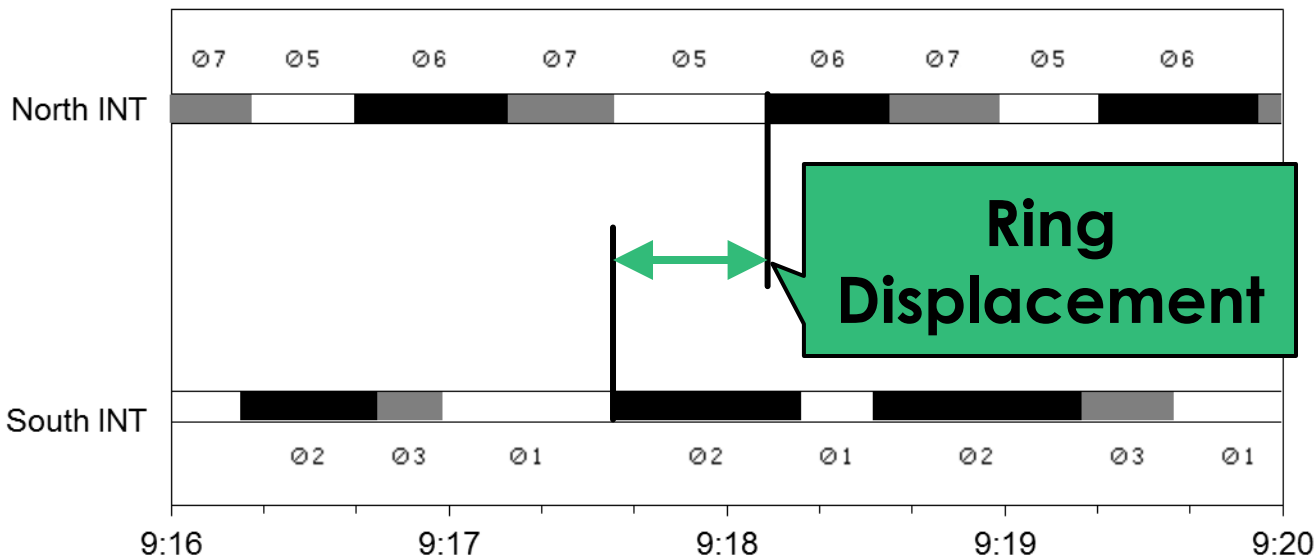
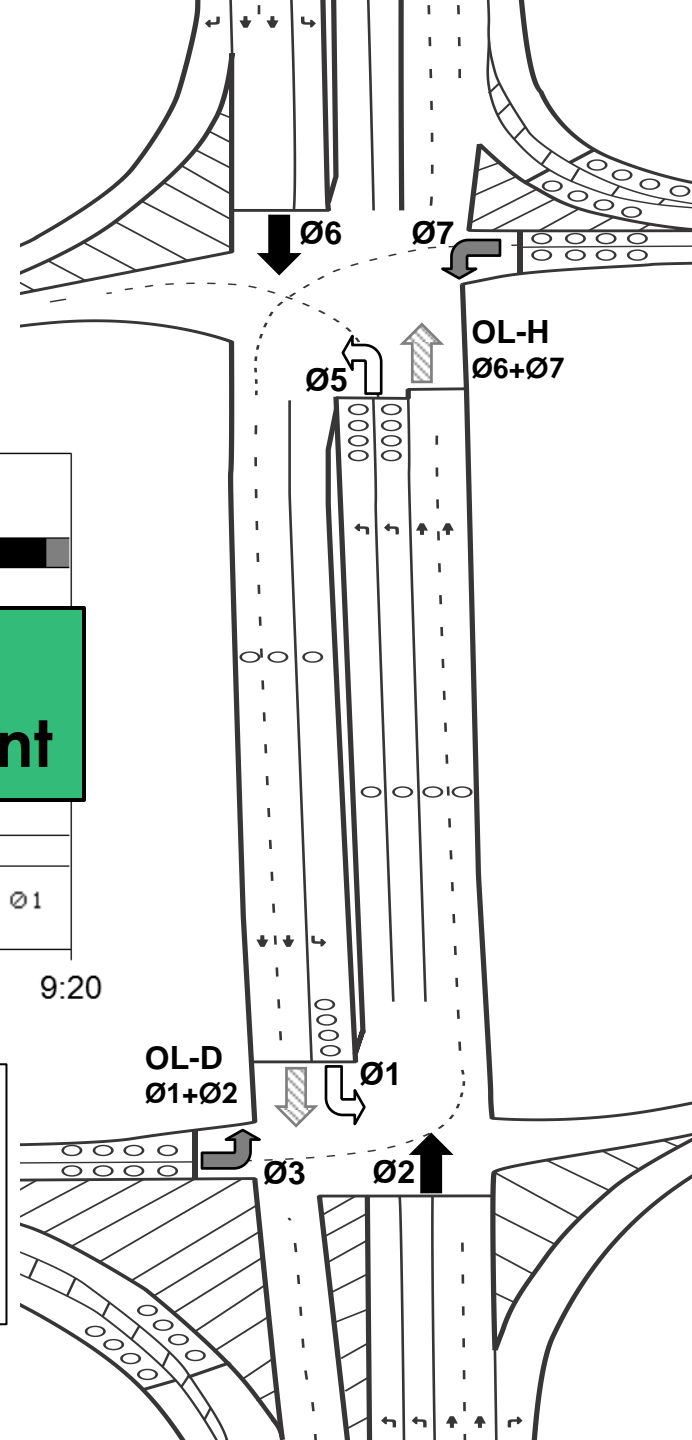
*From the HiRes Data, Plot the Rings*





# Ring Displacement

How is this parameter set?



```

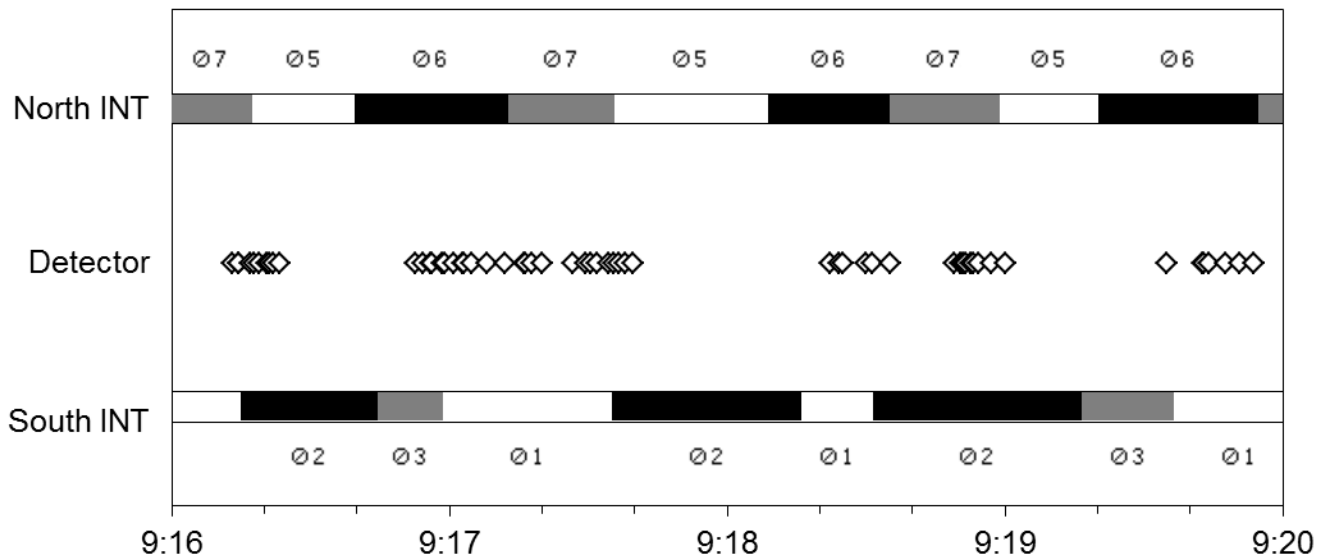
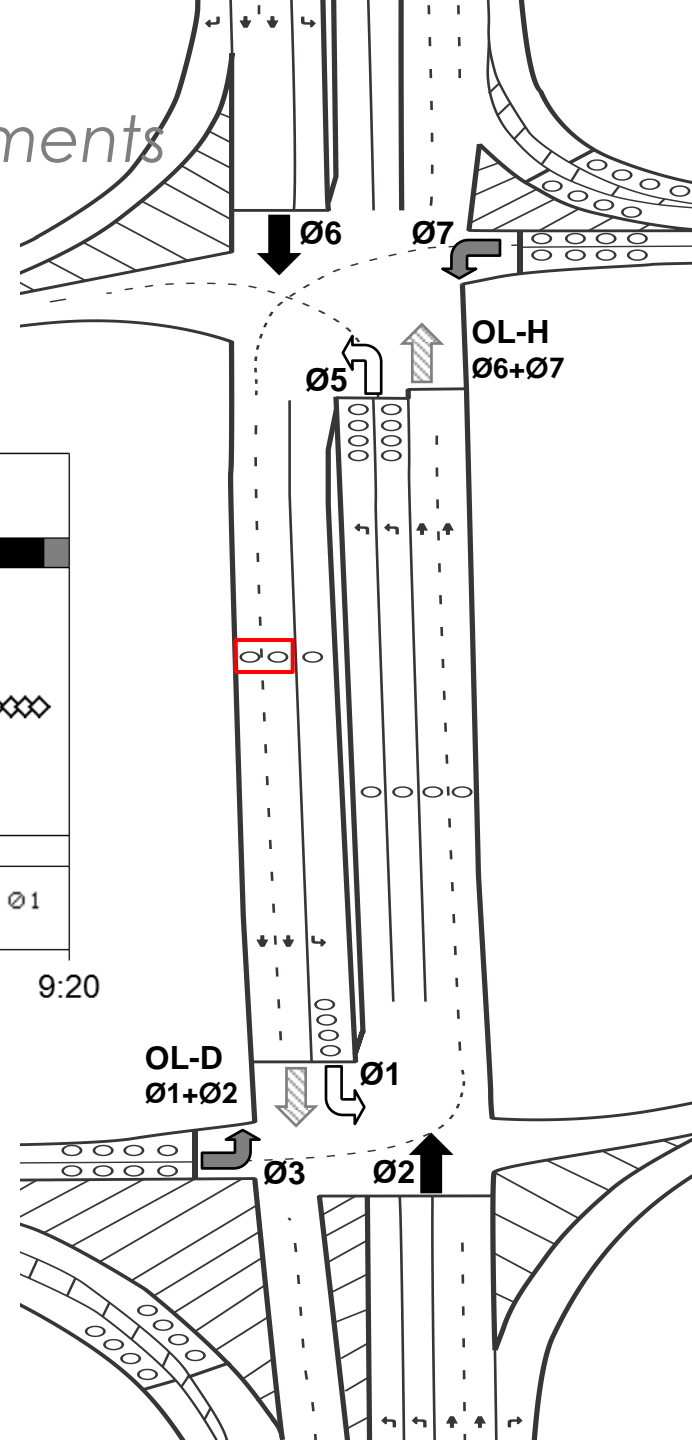
COORDINATOR PATTERN [ 1 ]
TS2 (PAT-OFF)... 0-1
CYCLE..... 0s STD (COS).....111
OFFSET VAL..... 0s DWELL/ADD TIME. 0
ACTUATED COORD... NO TIMING PLAN...
ACT WALK REST... NO SEQUENCE.....
PHASE RESRUC... NO ACTION PLAN...
MAX SELECT..... NONE FORCE OFF.... NONE
SPLIT PREFERENCE PHASES
  PHASE[1s] 1 2 3 4 5 6 7 8
SPT[ 1] 0 0 0 0 0 0 0 0
PREF 1... 0 0 0 0 0 0 0 0
PREF 2... 0 0 0 0 0 0 0 0
SPLT EXT...0s 0s 0s 0s
VEH PERM. 0c 0c 0c DISP
RING DISP - 0s 0s 0s (RING 2-4)
    
```

```

DIAL 1 SPLIT 1 PARAMETERS
OFFSET TIME  ALT  PATN  R2  R3  R4
#      SEC  SEQ  MODE  LAG  LAG  LAG
1      0    0    0    LAG  LAG  LAG
2      0    0    0    LAG  LAG  LAG
3      0    0    0    LAG  LAG  LAG
MODE (0-6) : NRM/PRM/YLD/PYL/POM/SOM/FAC
A-UP B-DN C-LT D-RT E-ENTER F-PRIOR MENU
    
```

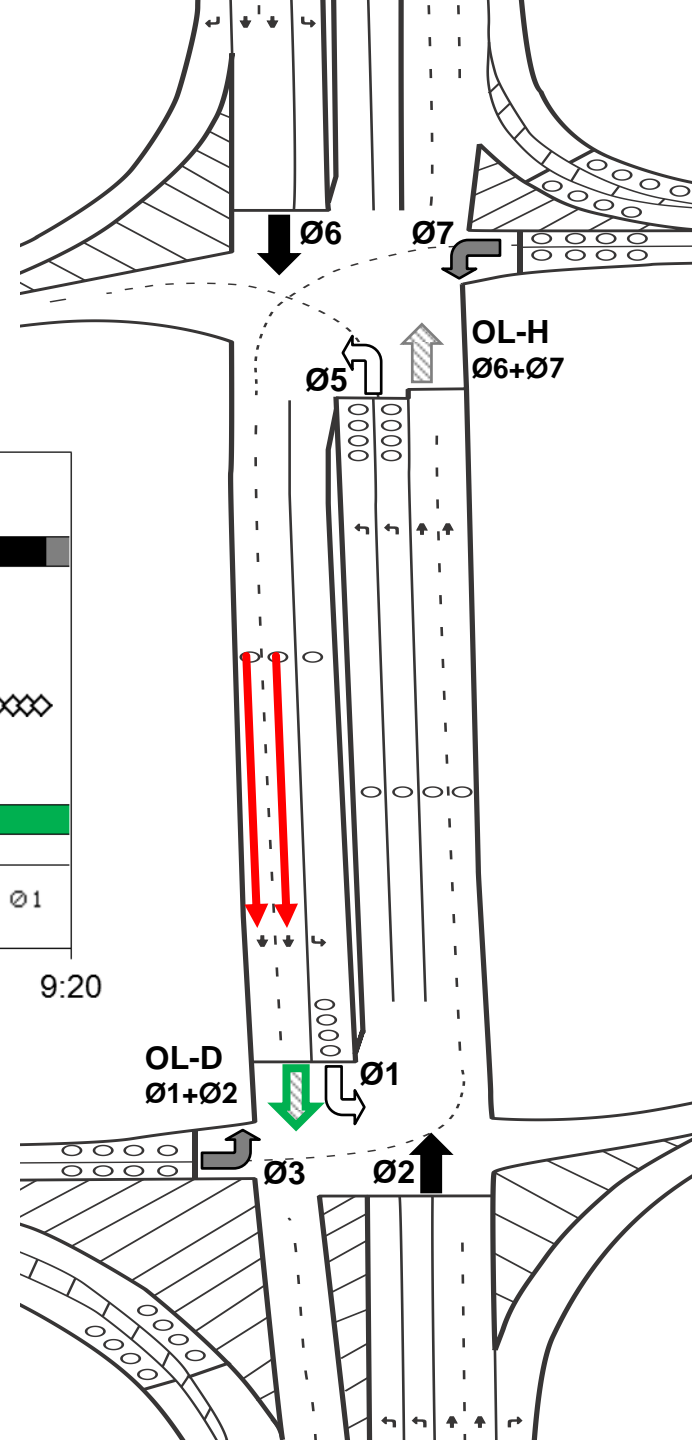
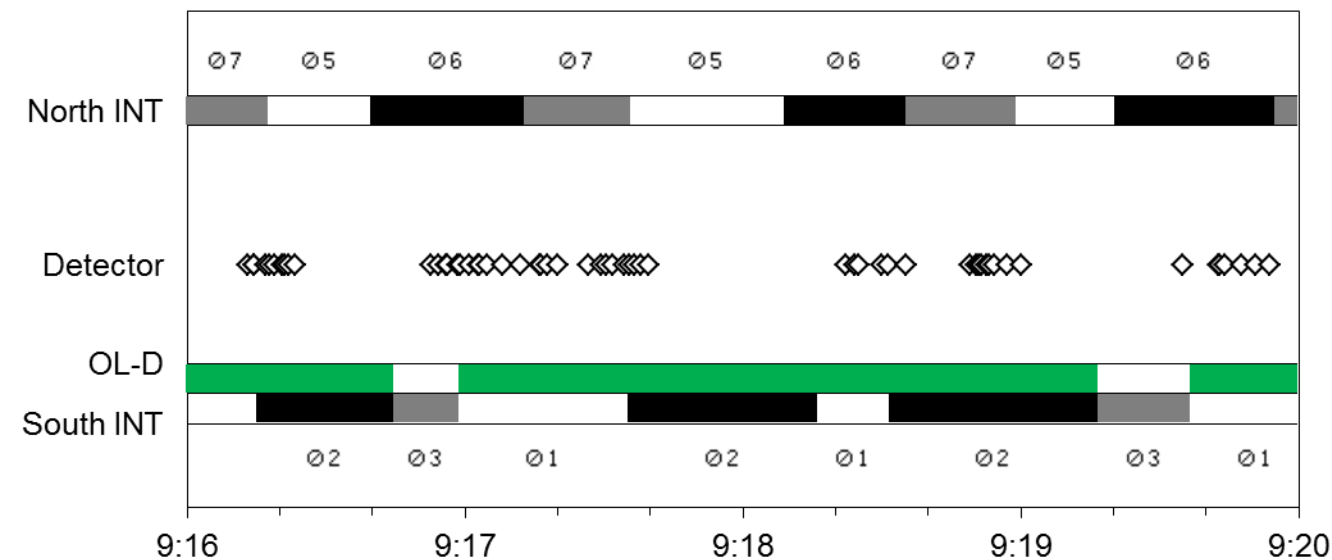
# SB Thru Detectors

*Consider one of the four internal movements*



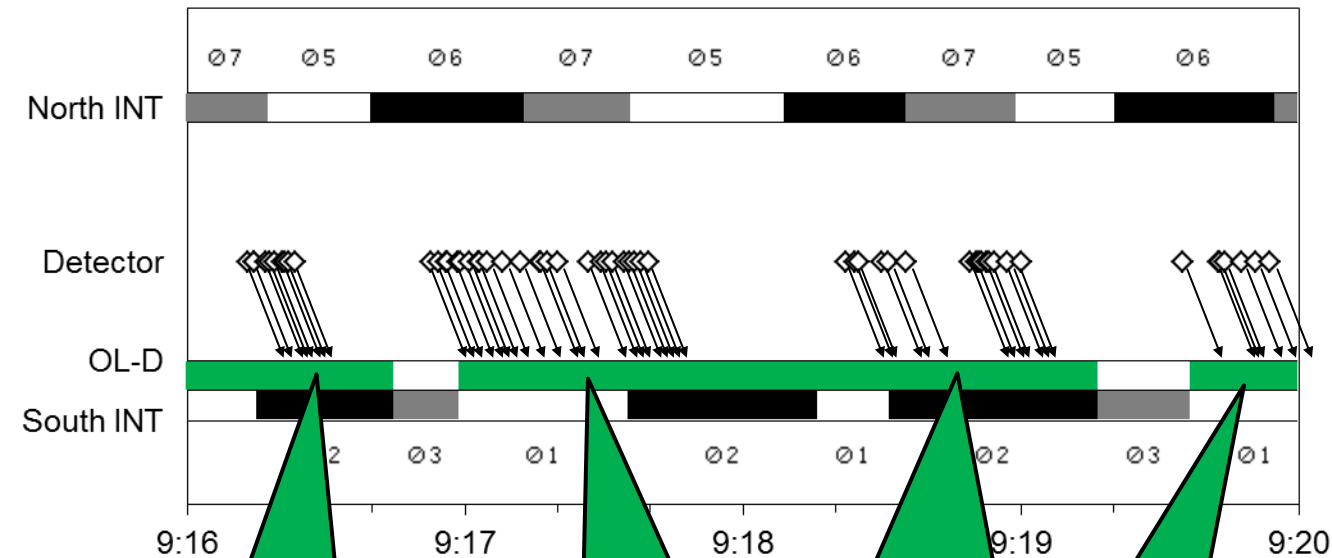
# Arrival on Green?

*Plot the green status of the overlap*

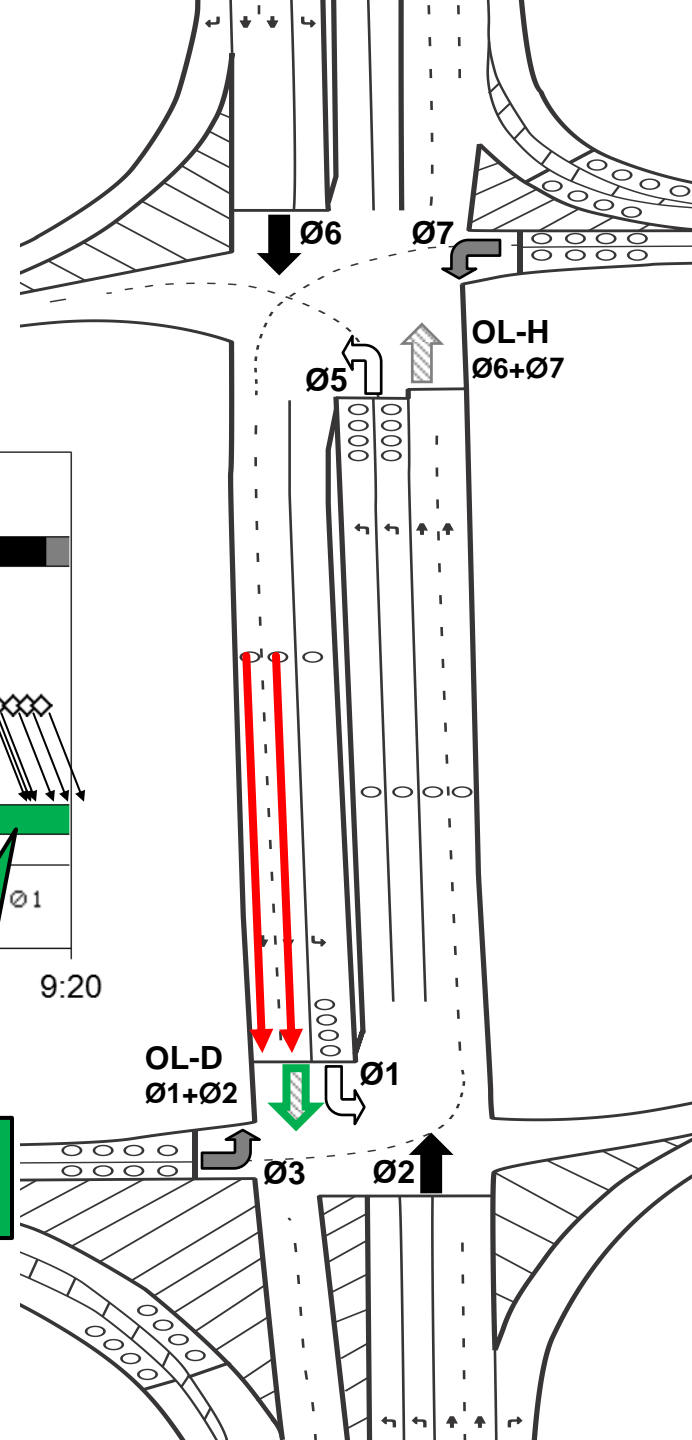


# Project the Detector Data

*295' upstream  $\approx$  5 seconds @ 40 MPH*

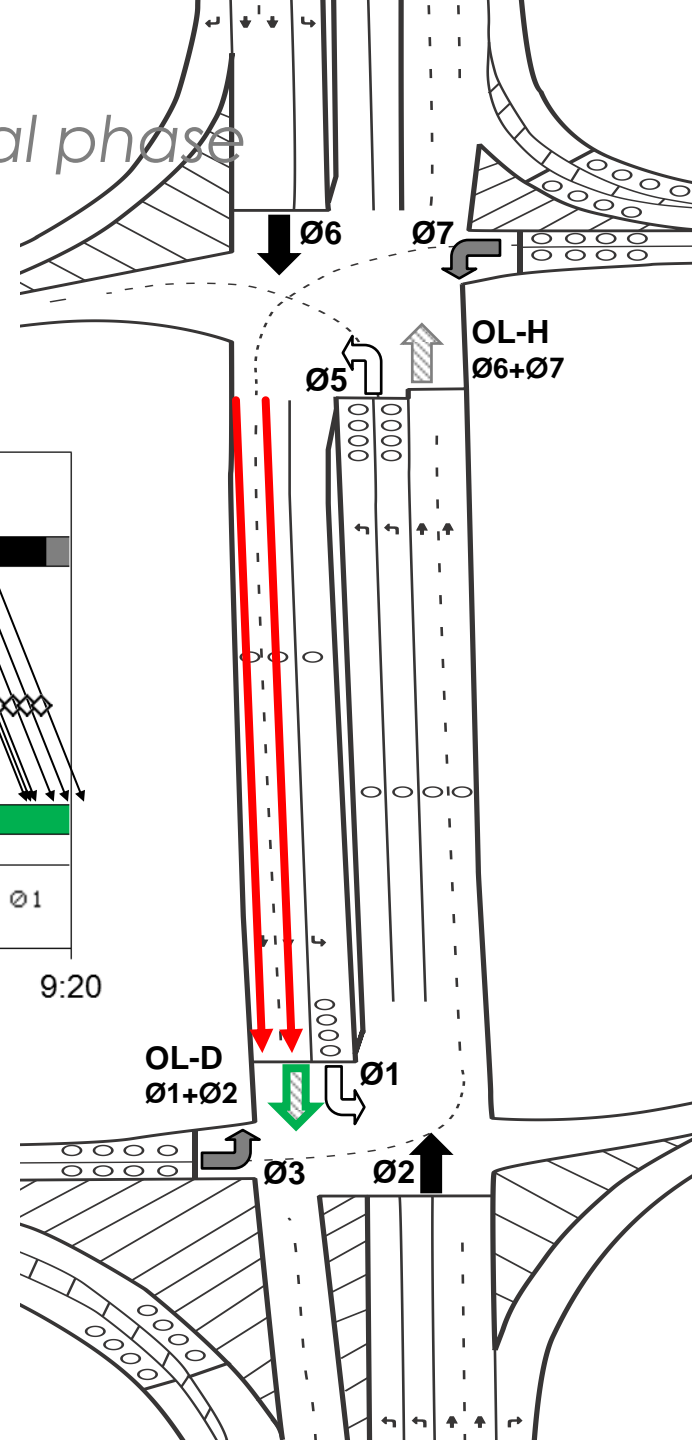
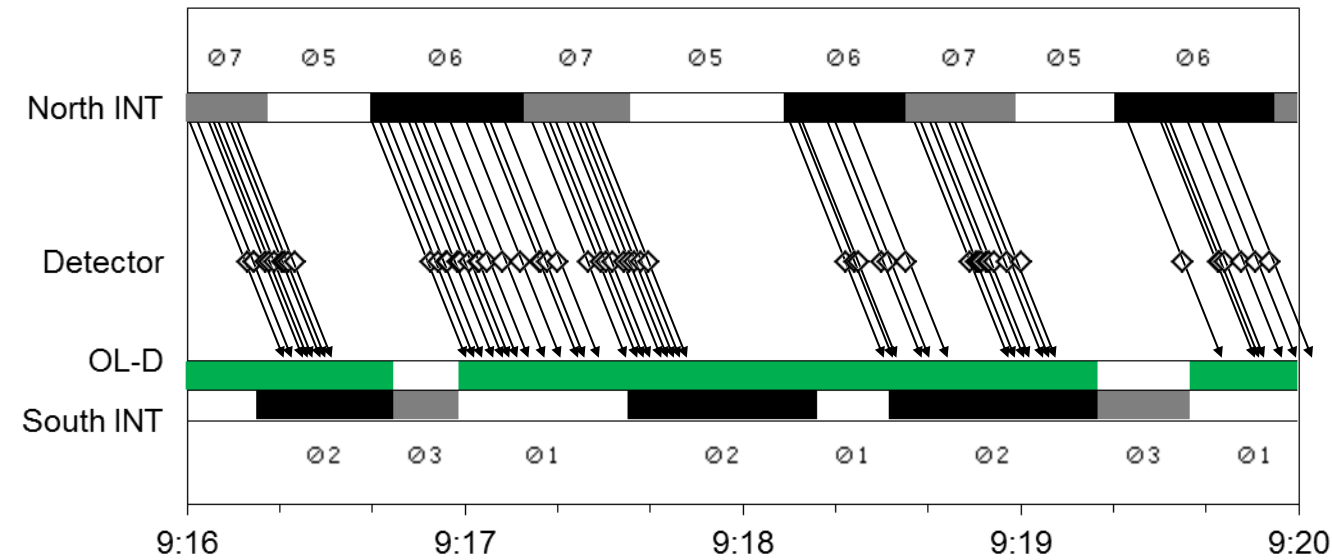


**The engineer who set the ring displacement did a fantastic job at arrivals on green for this movement!**



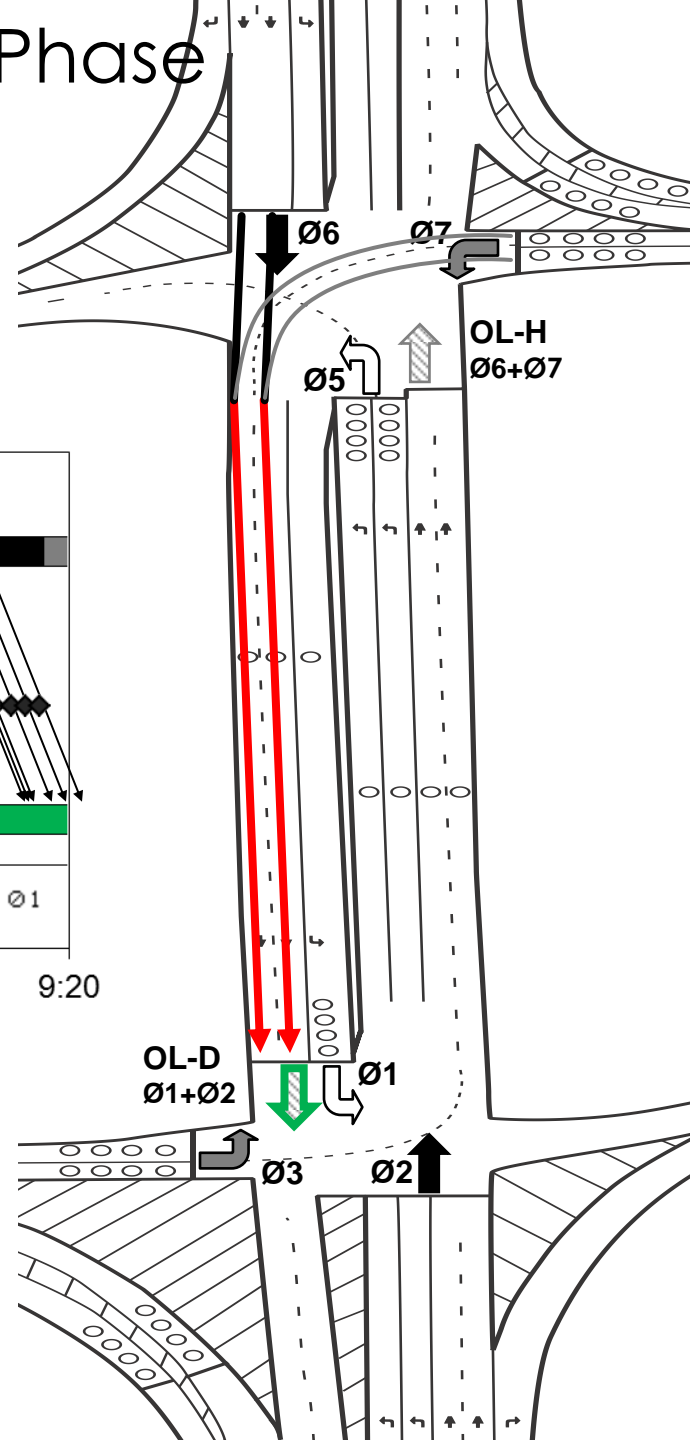
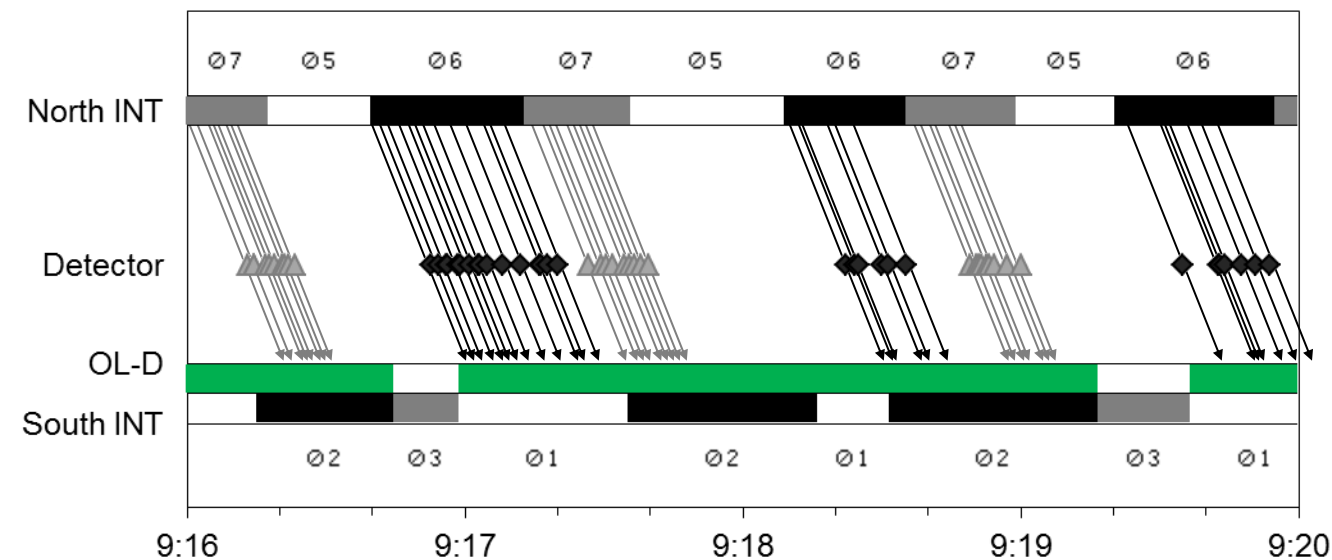
# Upstream Source Phase?

*Look upstream ~10 seconds at the signal phase*



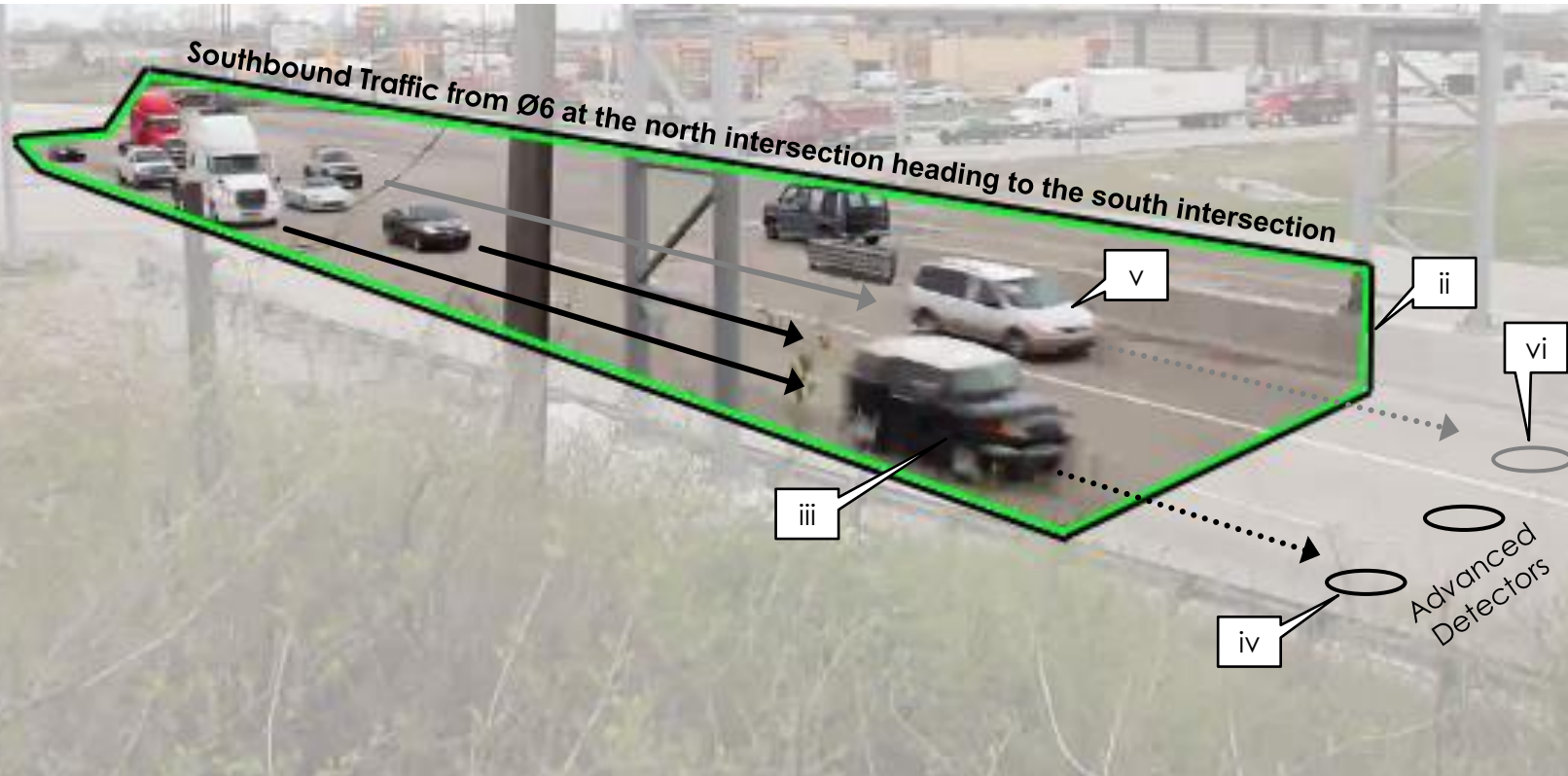
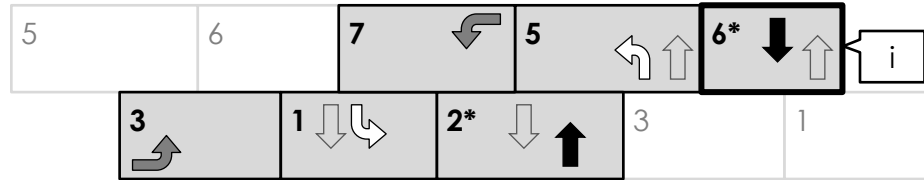
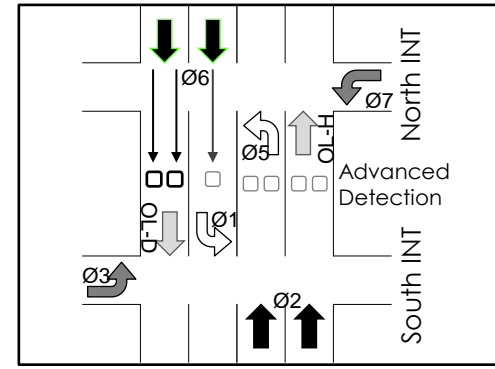
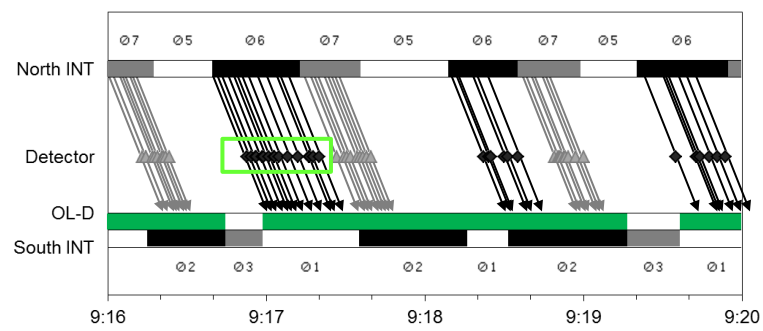
# Now Platoons are Attributed to a Phase

*The vehicles' sources are known*



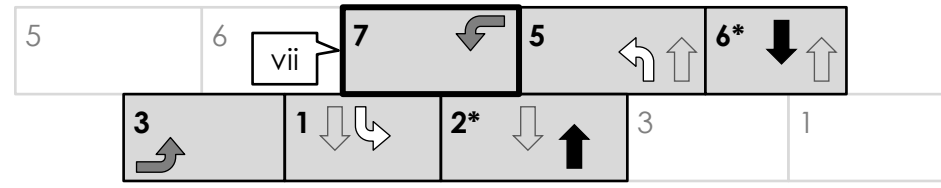
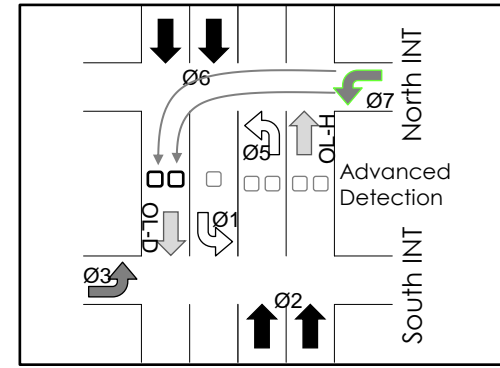
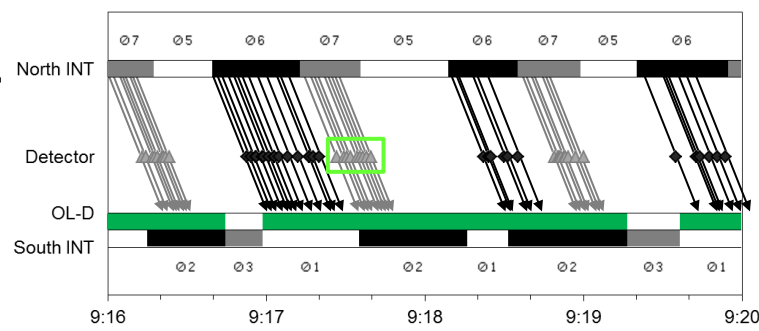
# Traffic from SBT

## Vehicles from $\emptyset 6$

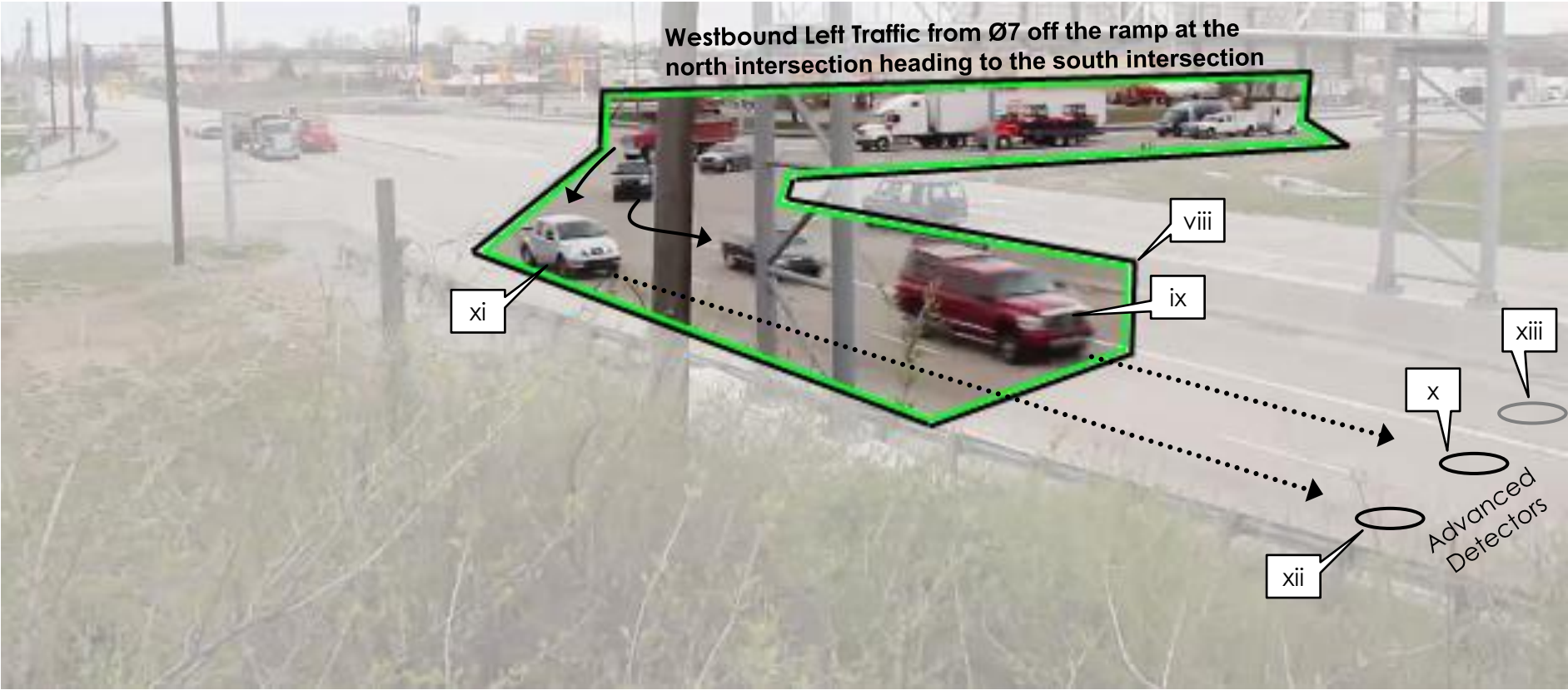


# Traffic from WBL

## Vehicles from $\emptyset 7$



Westbound Left Traffic from  $\emptyset 7$  off the ramp at the north intersection heading to the south intersection

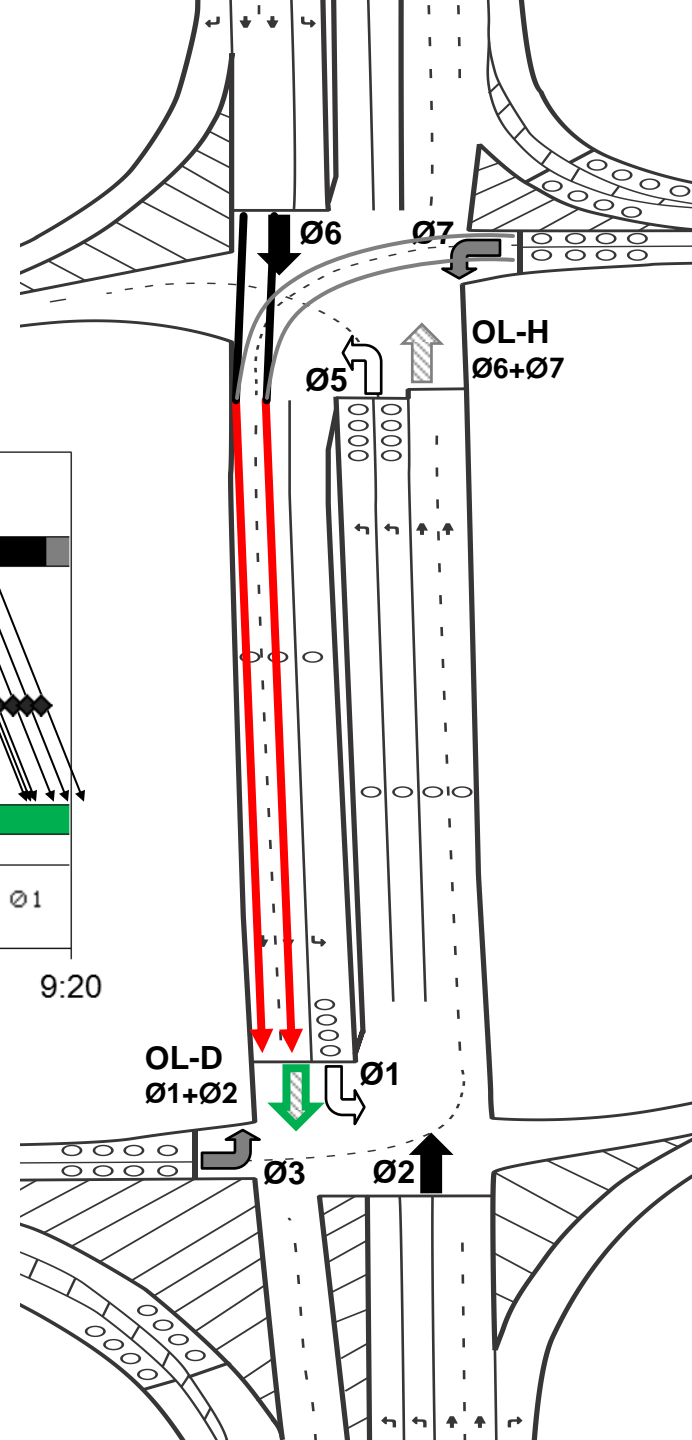
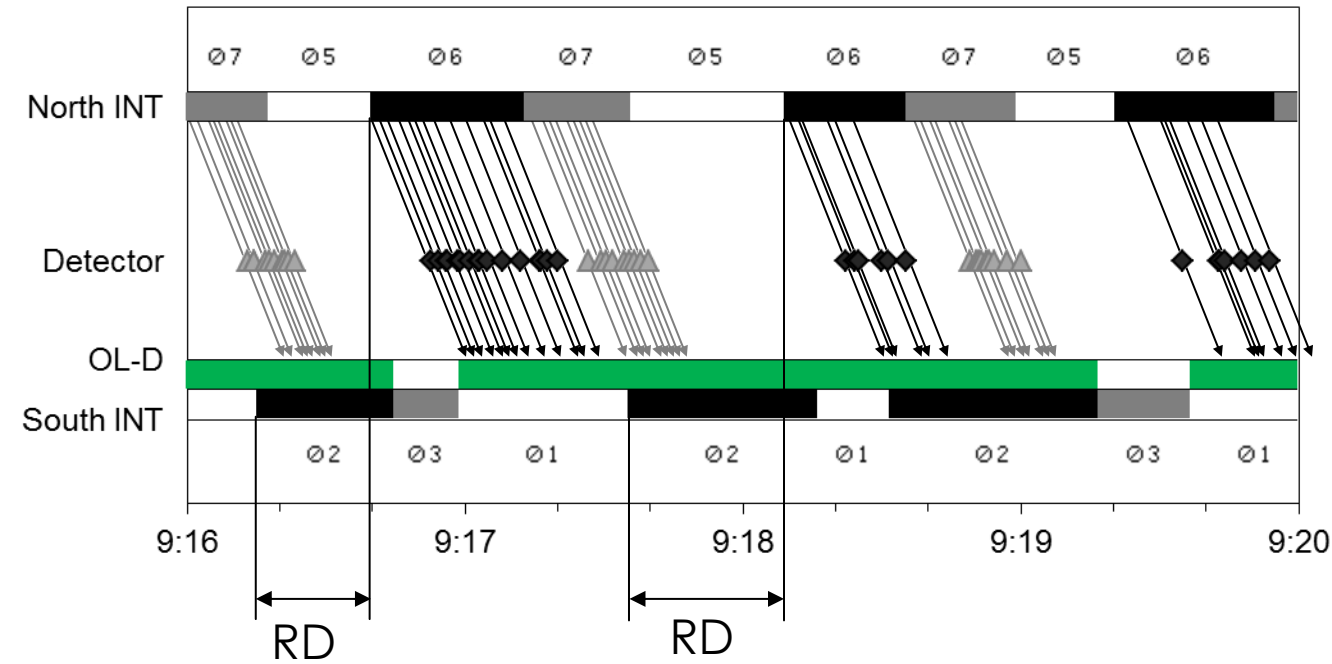


Advanced Detectors



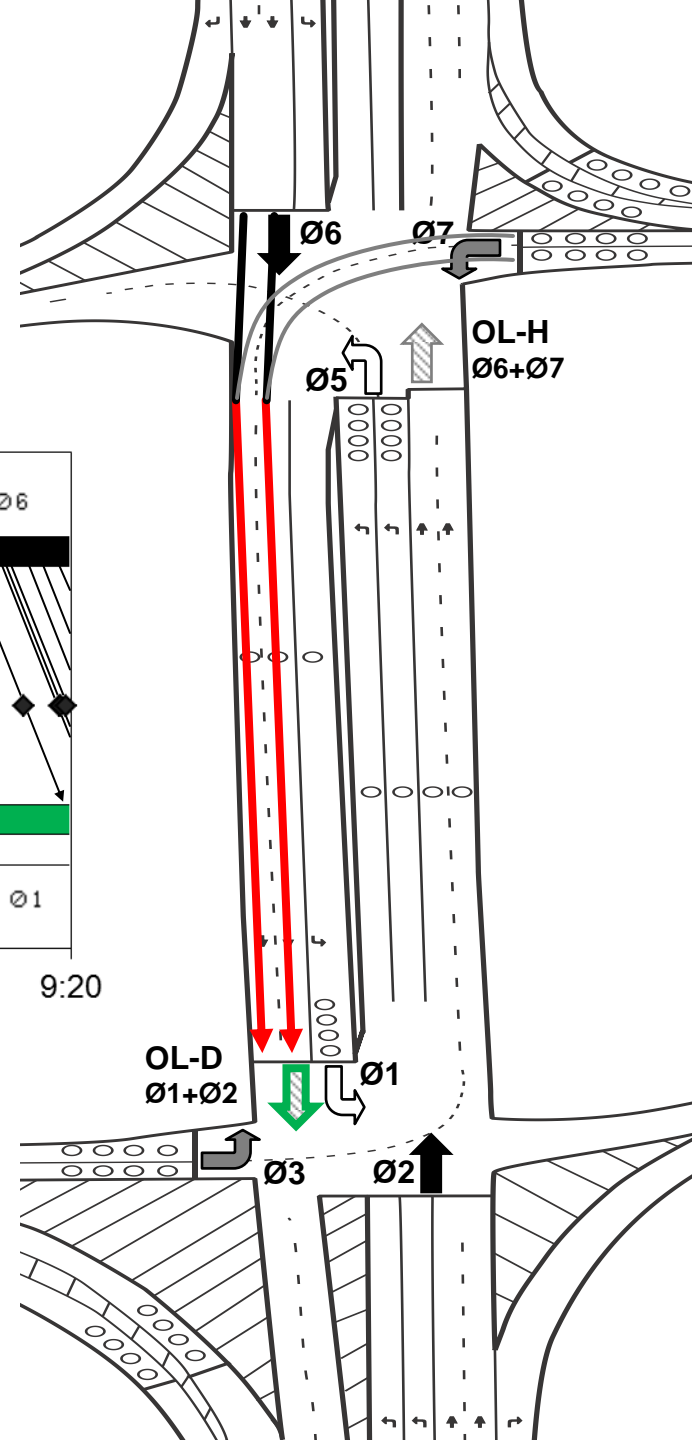
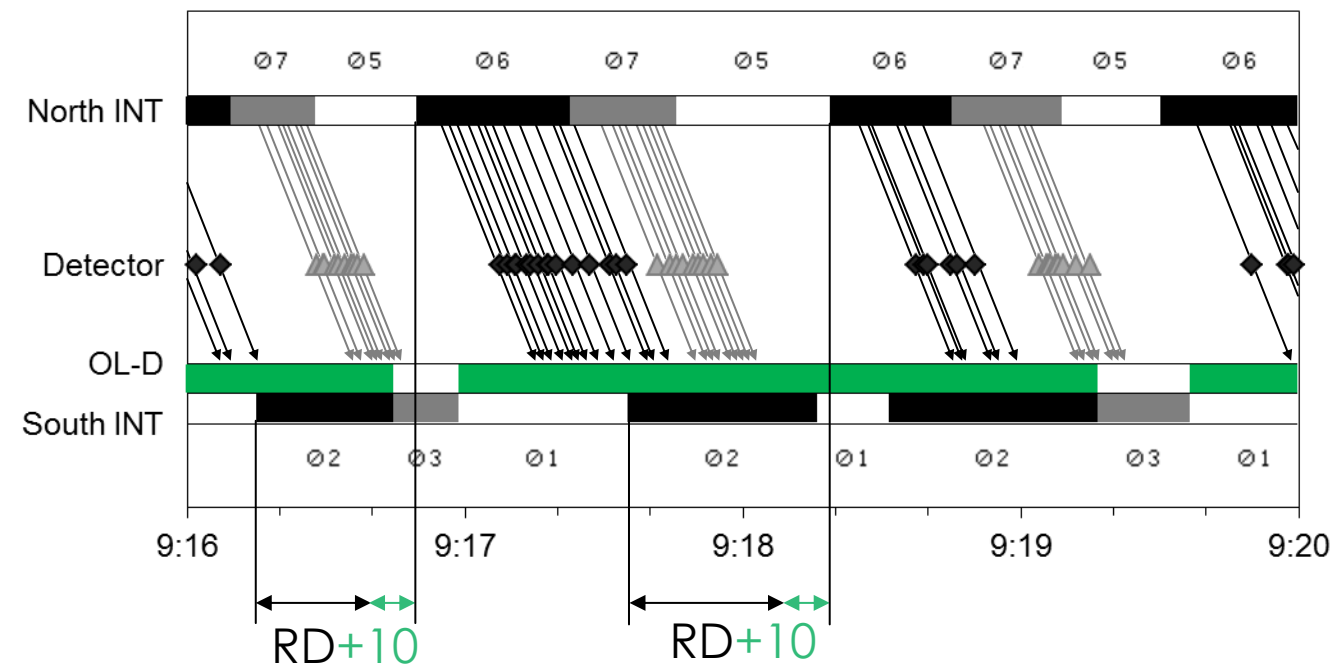
# Adjusting the ring displacement

*What effect would it have?*



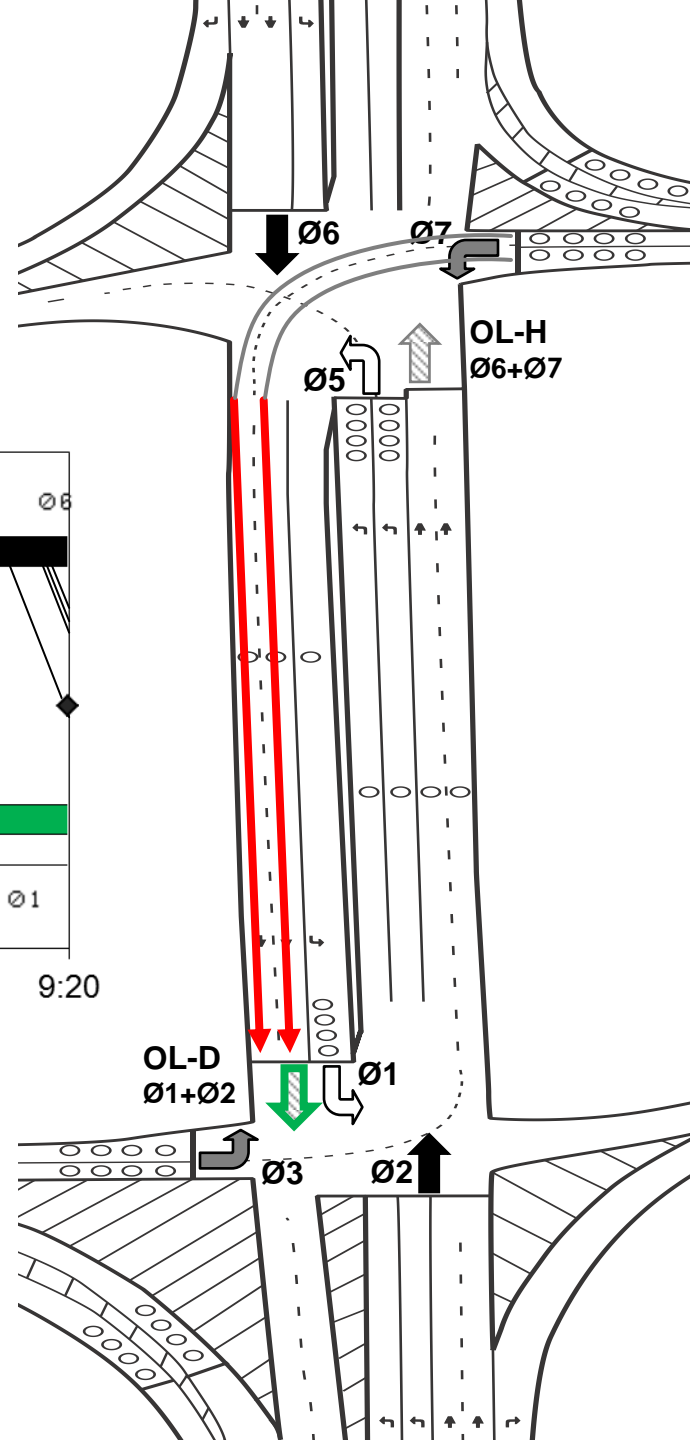
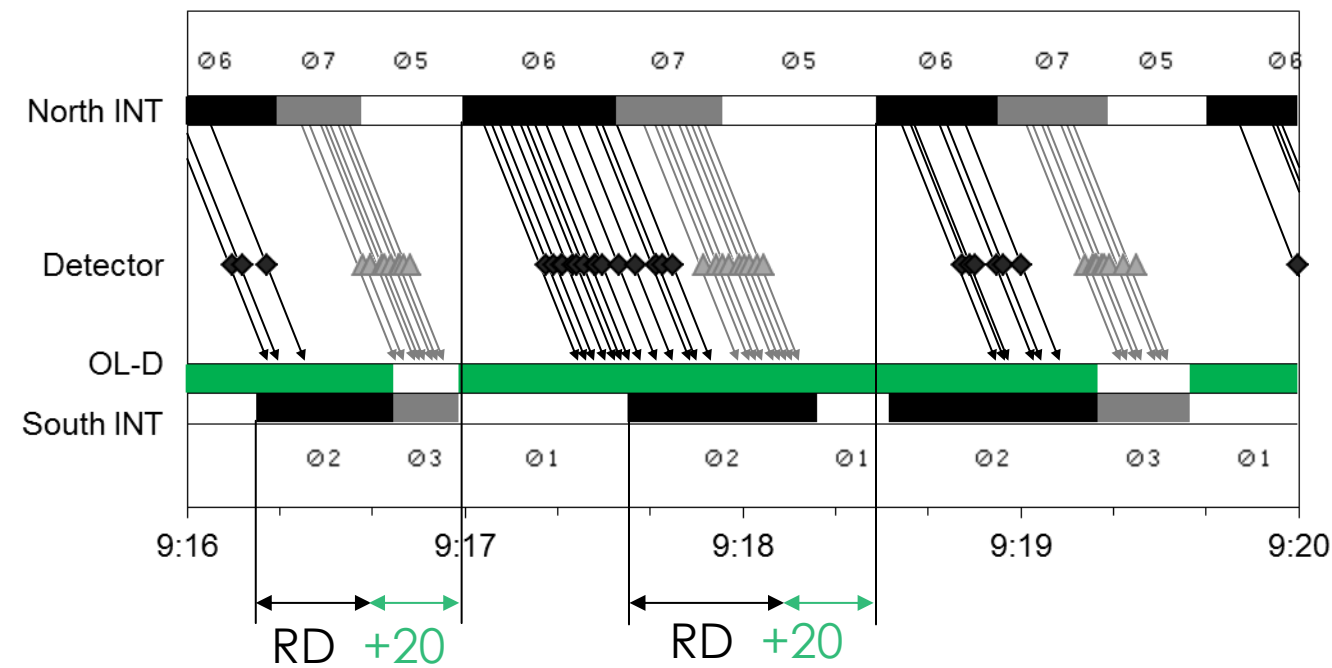
# Ring Displacement +10 Seconds

*What effect would it have?*



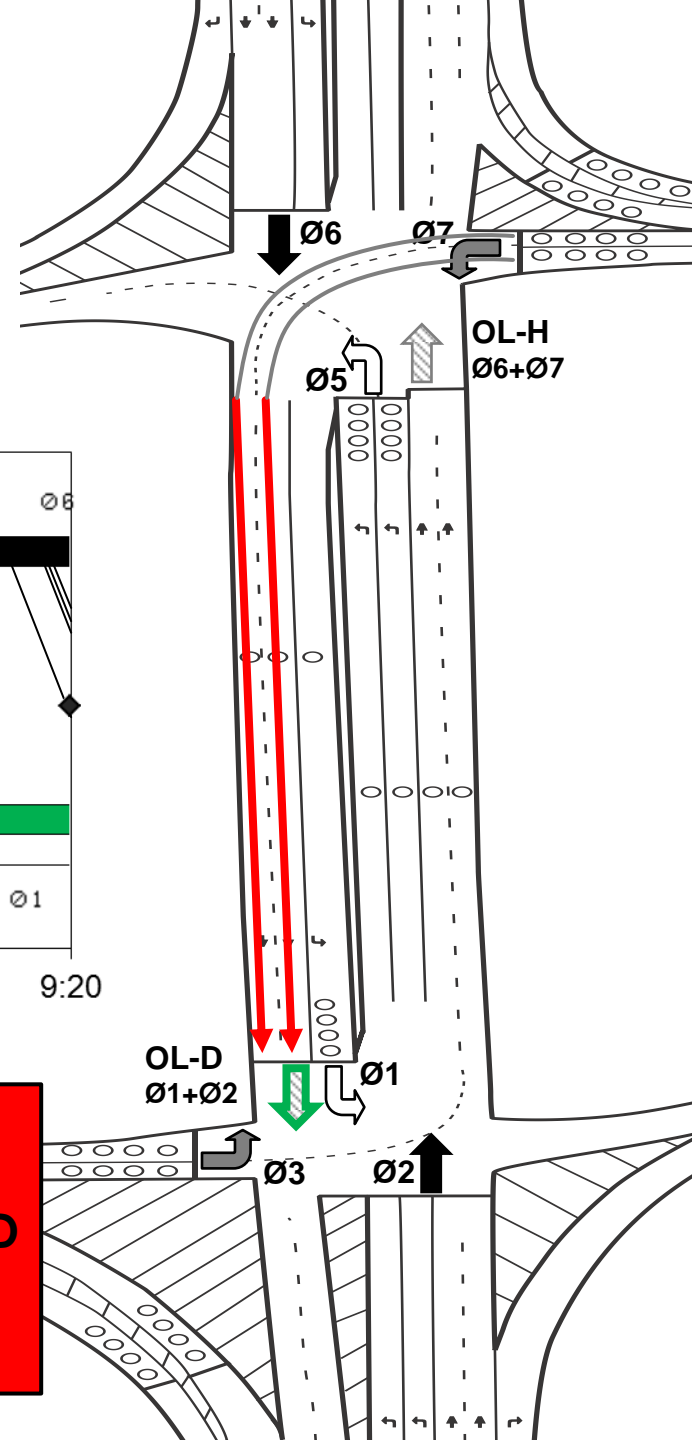
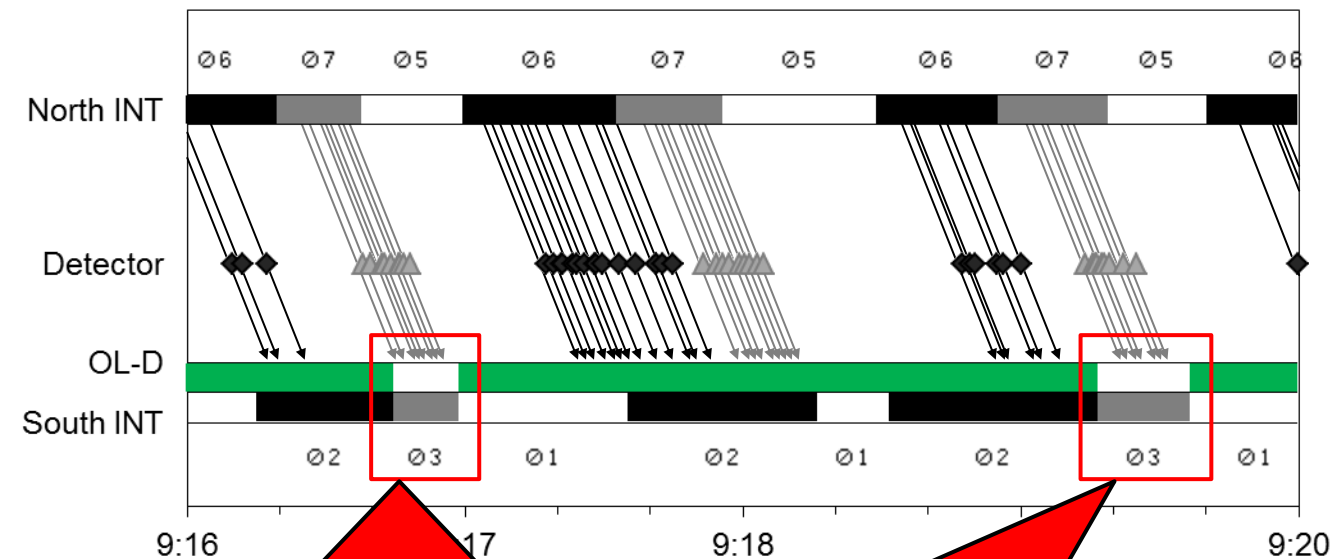
# Ring Displacement +20 Seconds

*Vehicles from upstream arrive later*



# Ring Displacement +20 Seconds

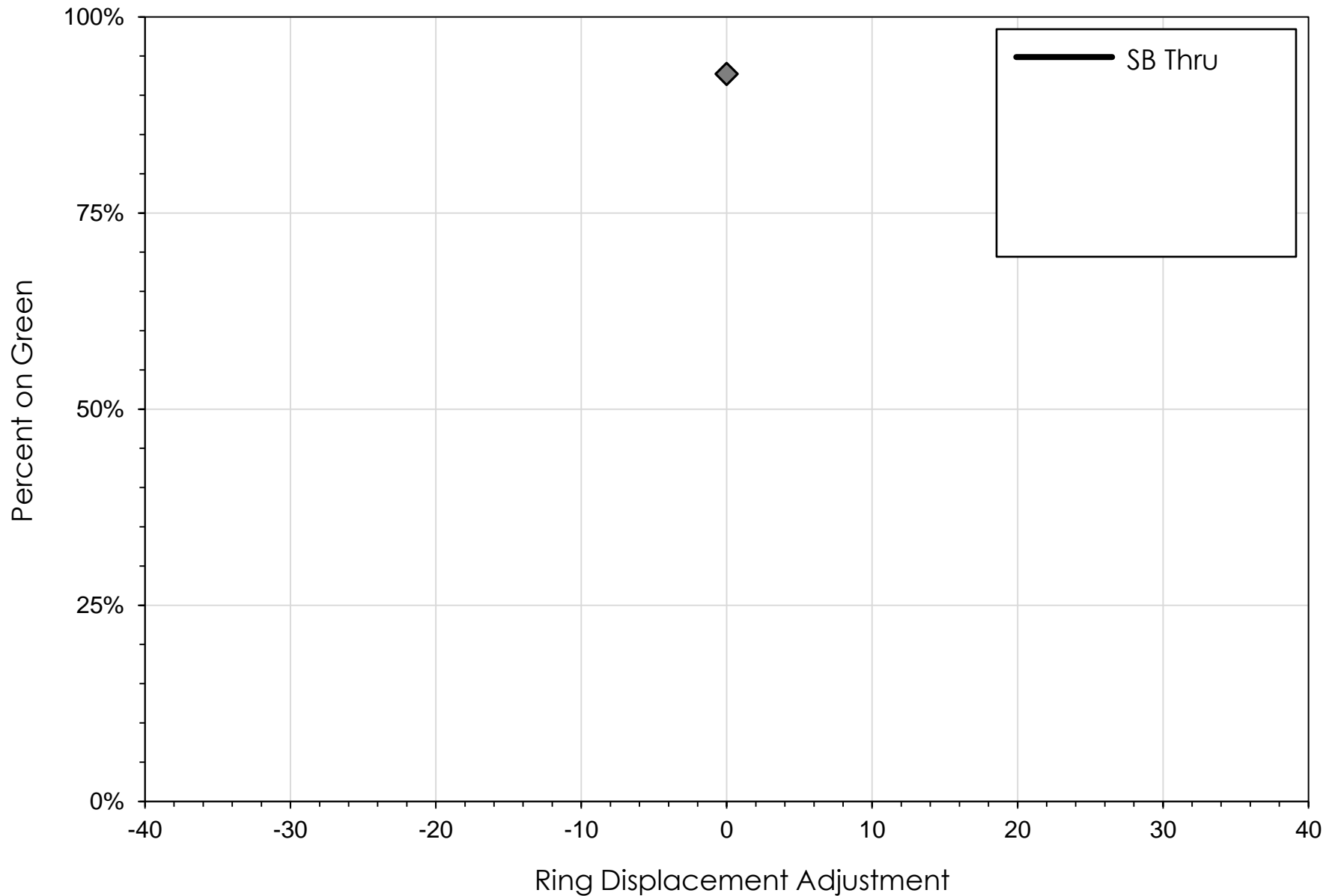
*Vehicles from upstream arrive later*



**By moving the ring displacement 20 seconds forward, the lagging WBL from the north ramp movement arrives at the south intersection on OL-D red while the EBL at the south ramp is served...  
Not Good!**

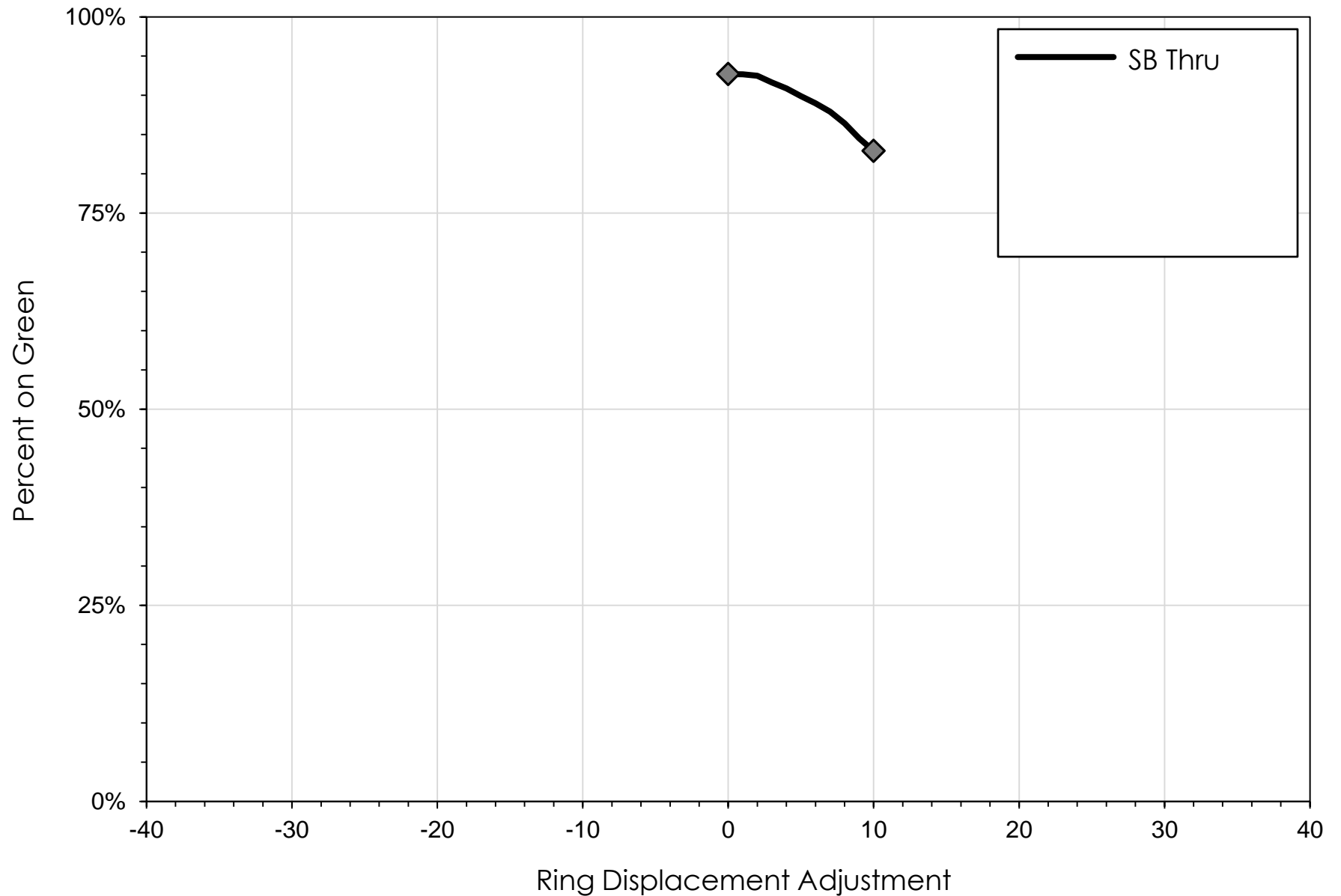
# Optimization Curves

*Let's Look at the Southbound Thru (Our +0, +10, +20 example)*



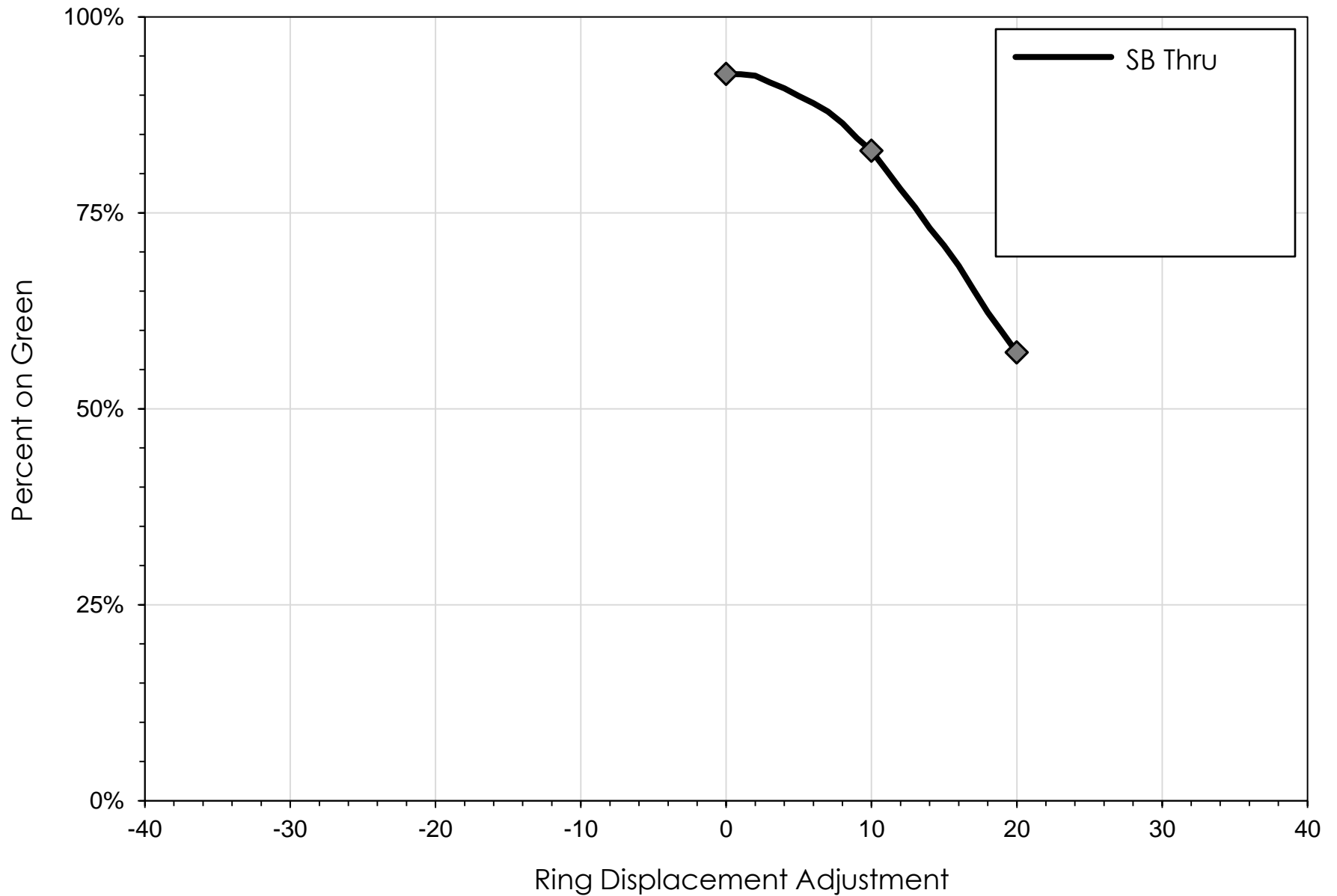
# Optimization Curves

*Southbound Thru +10*



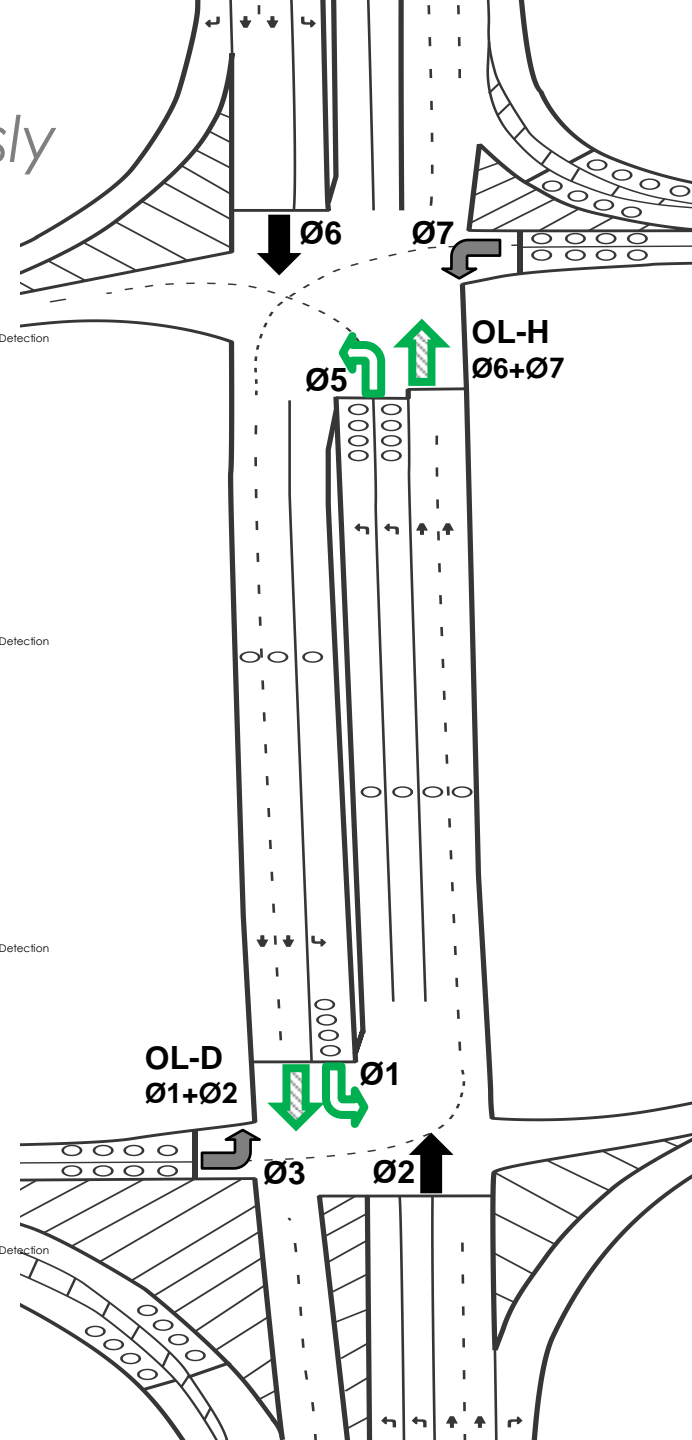
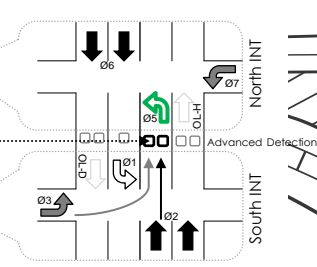
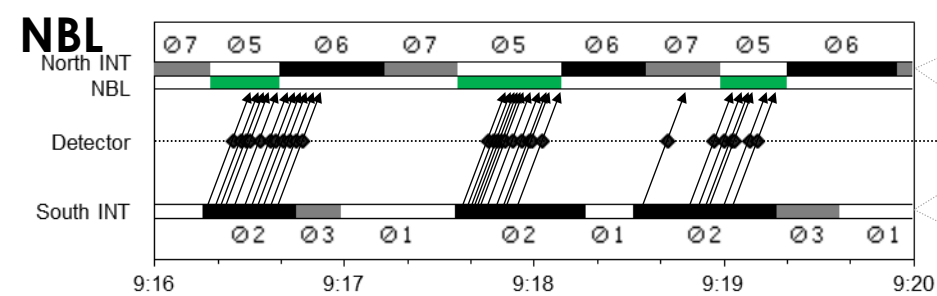
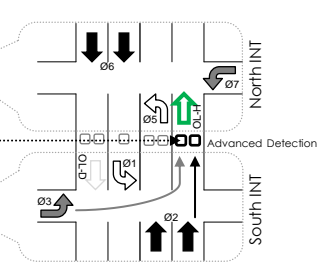
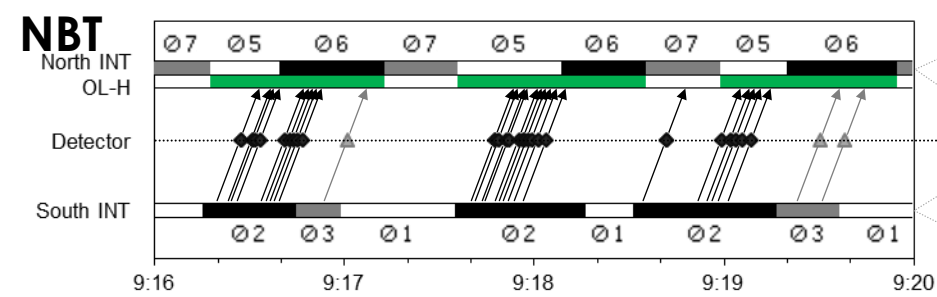
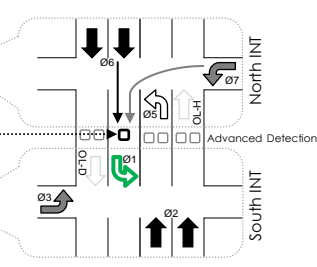
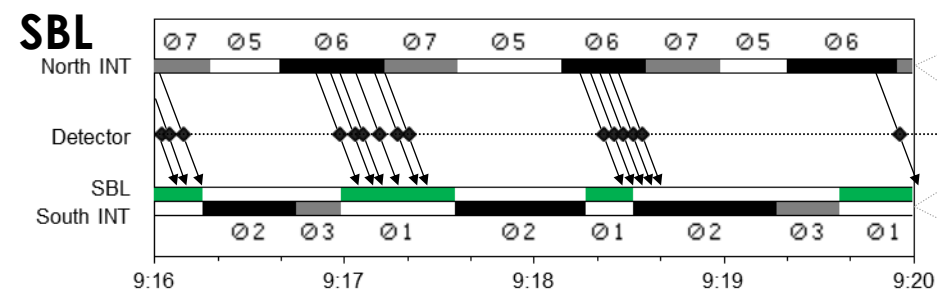
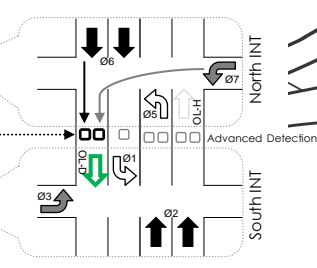
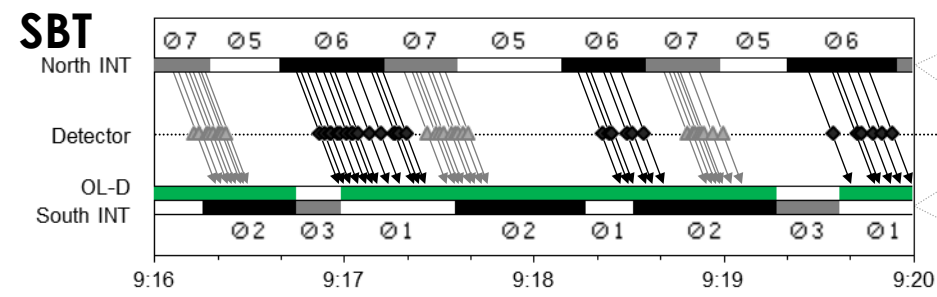
# Optimization Curves

*Southbound Thru +20*



# Optimization Consideration

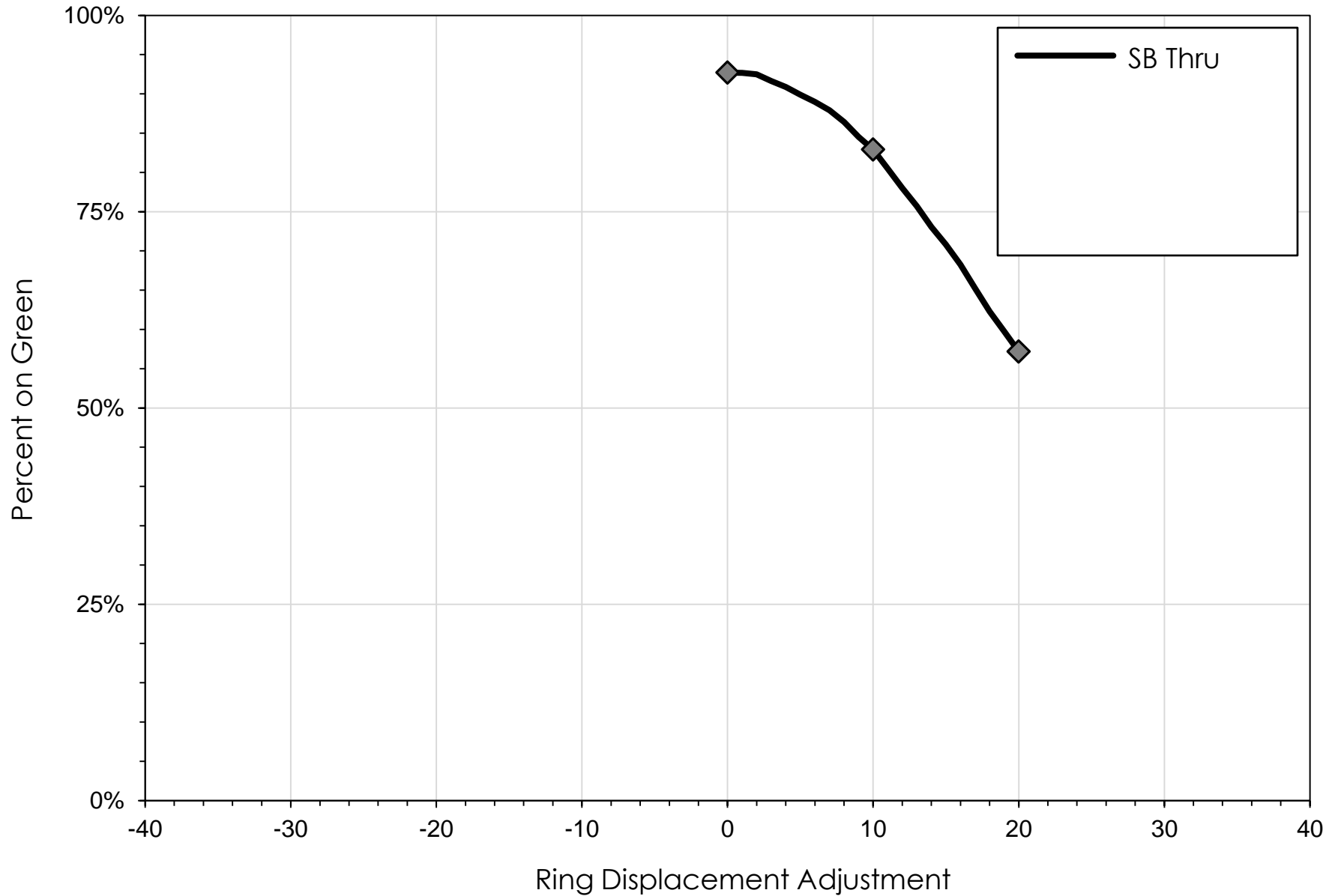
## Consider All 4 Movements Simultaneously





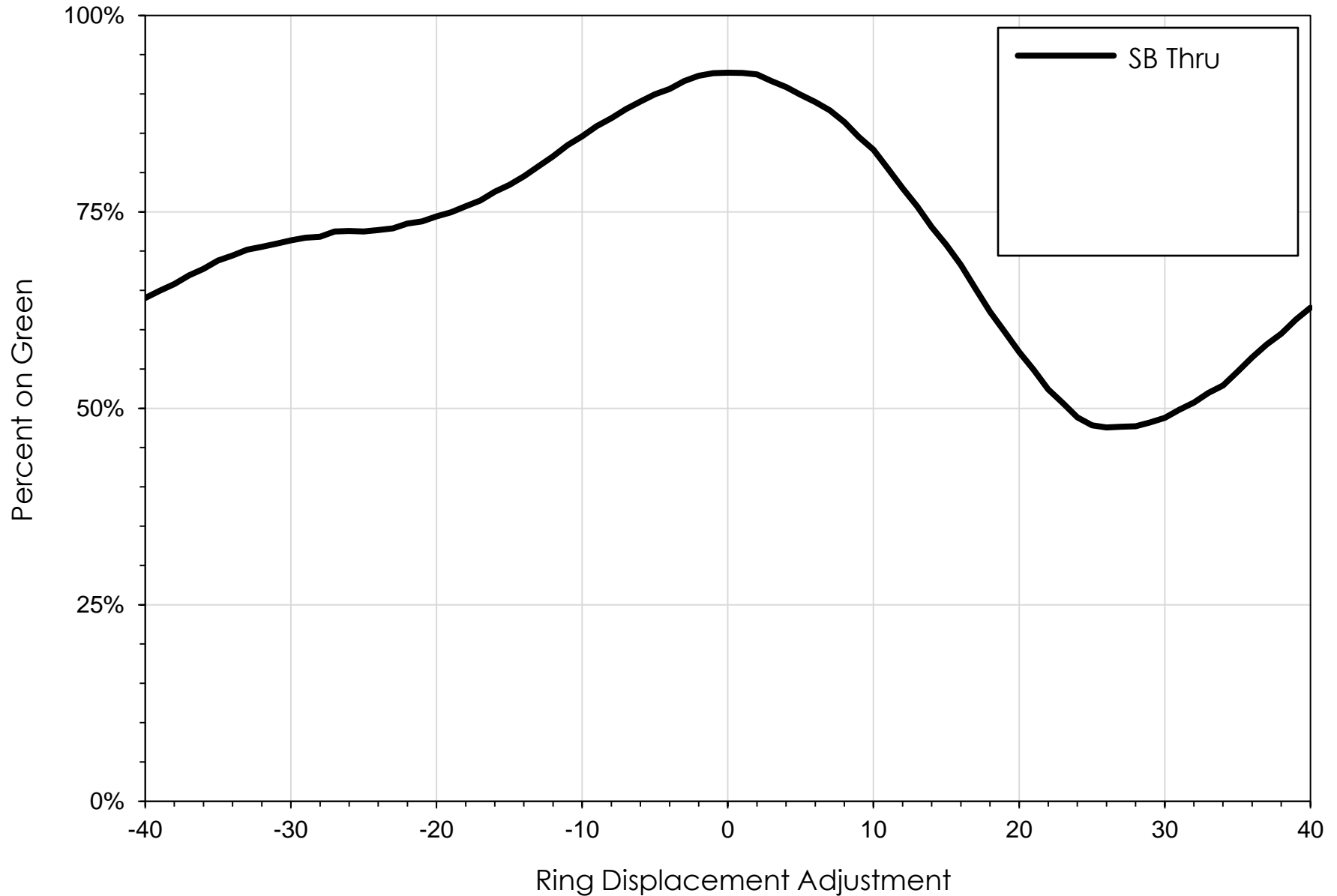
# Optimization Curves

*Southbound Thru +20*



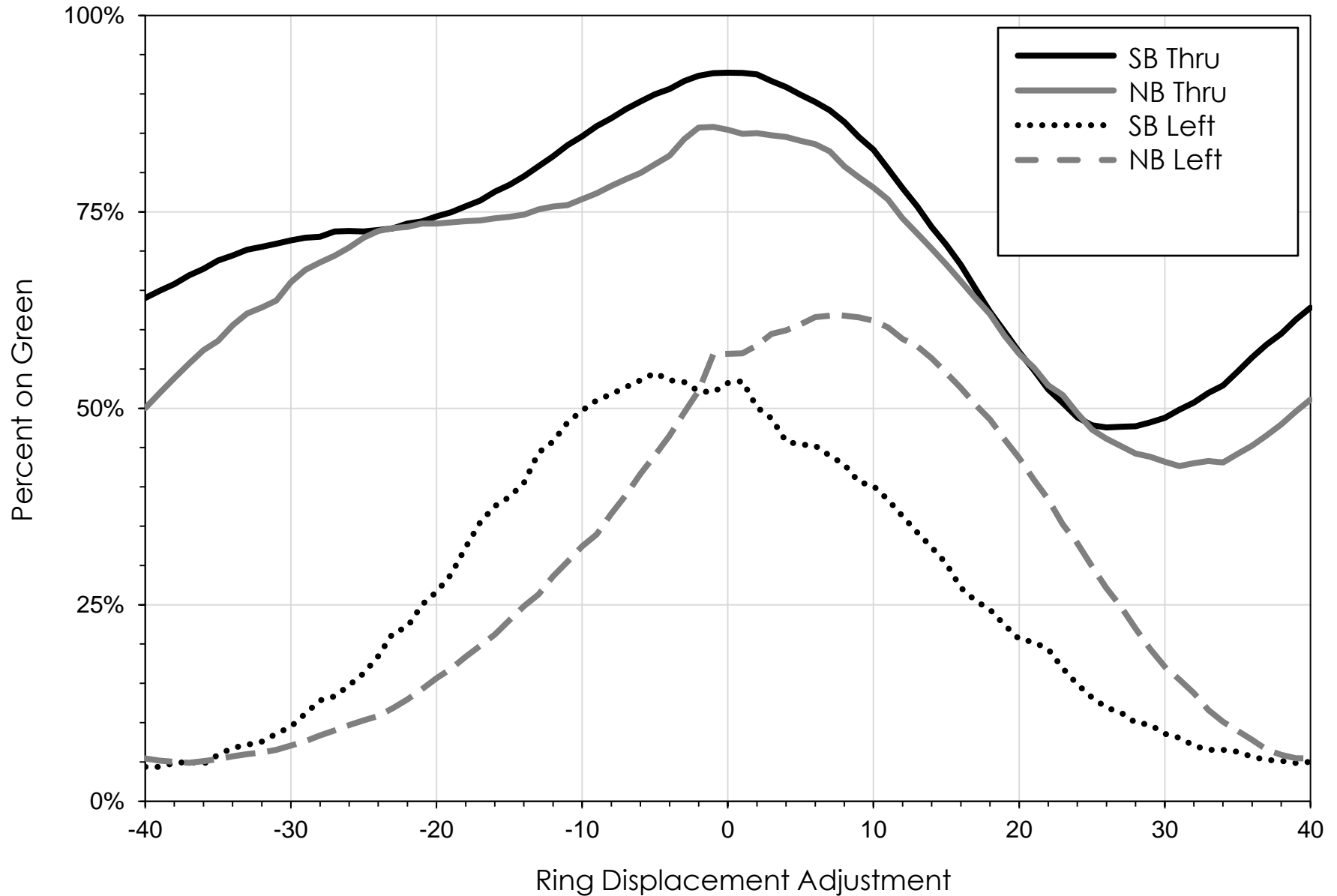
# Optimization Curves

*Southbound Thru for the Full Sweep*



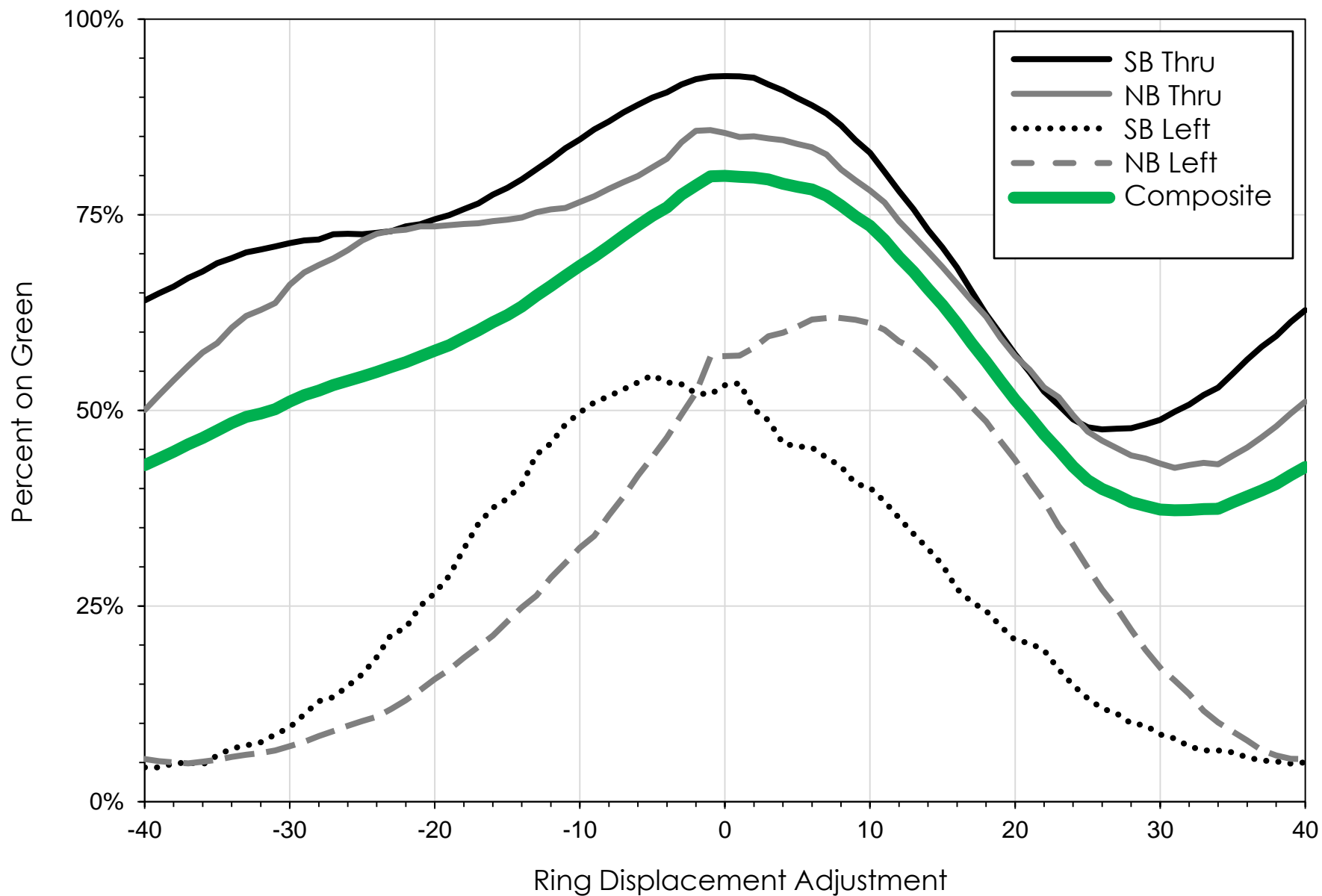
# Optimization Curves

## *Northbound Left*



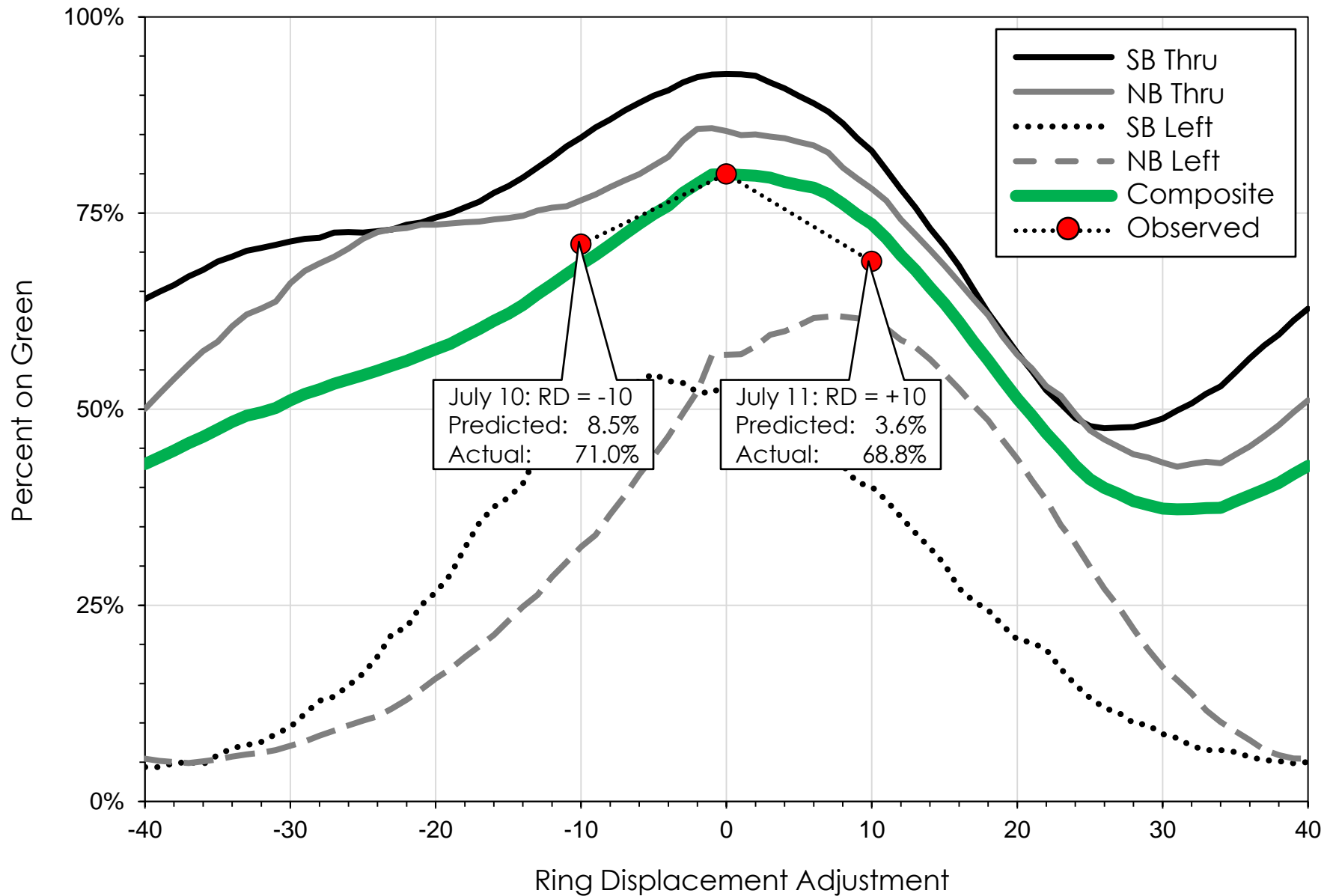
# Composite Interchange Sweep

*This is where all four movements are considered simultaneously*



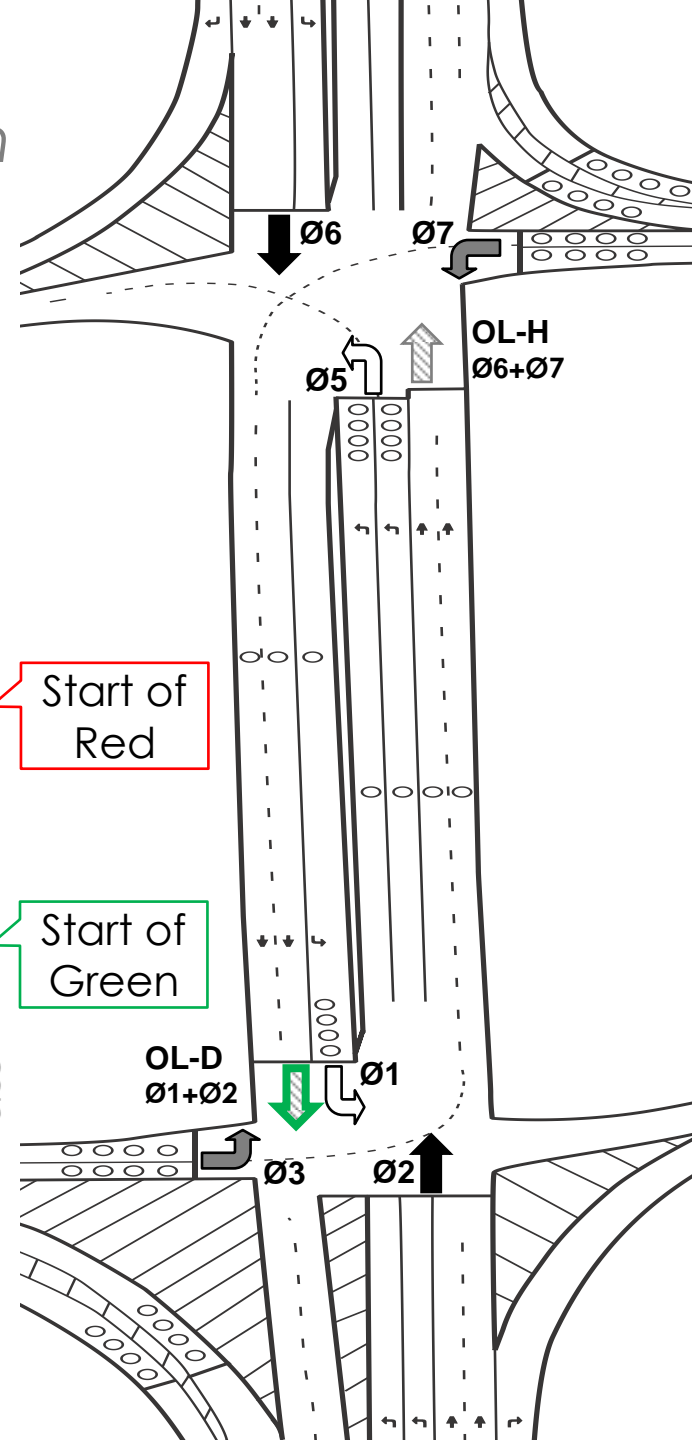
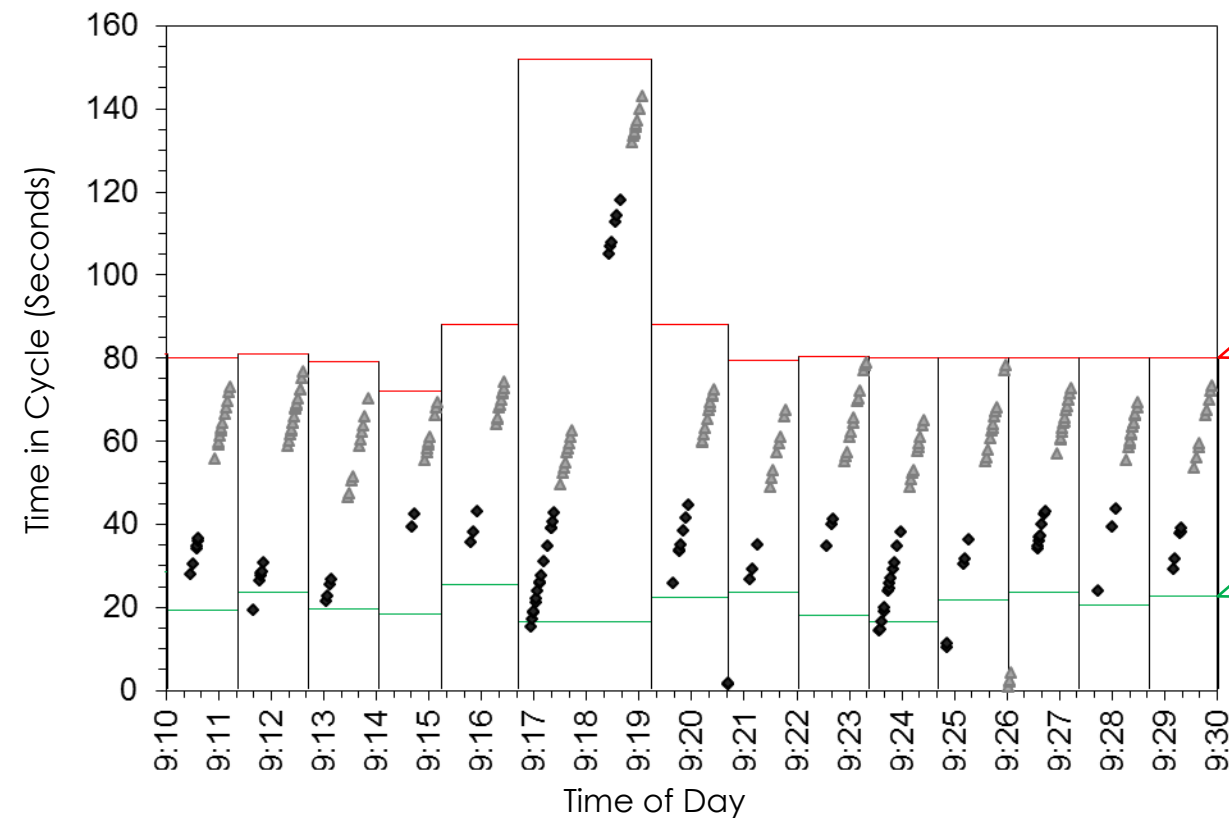
# Field Evaluation

*Adjust +/- 10 to see how it worked in the field*



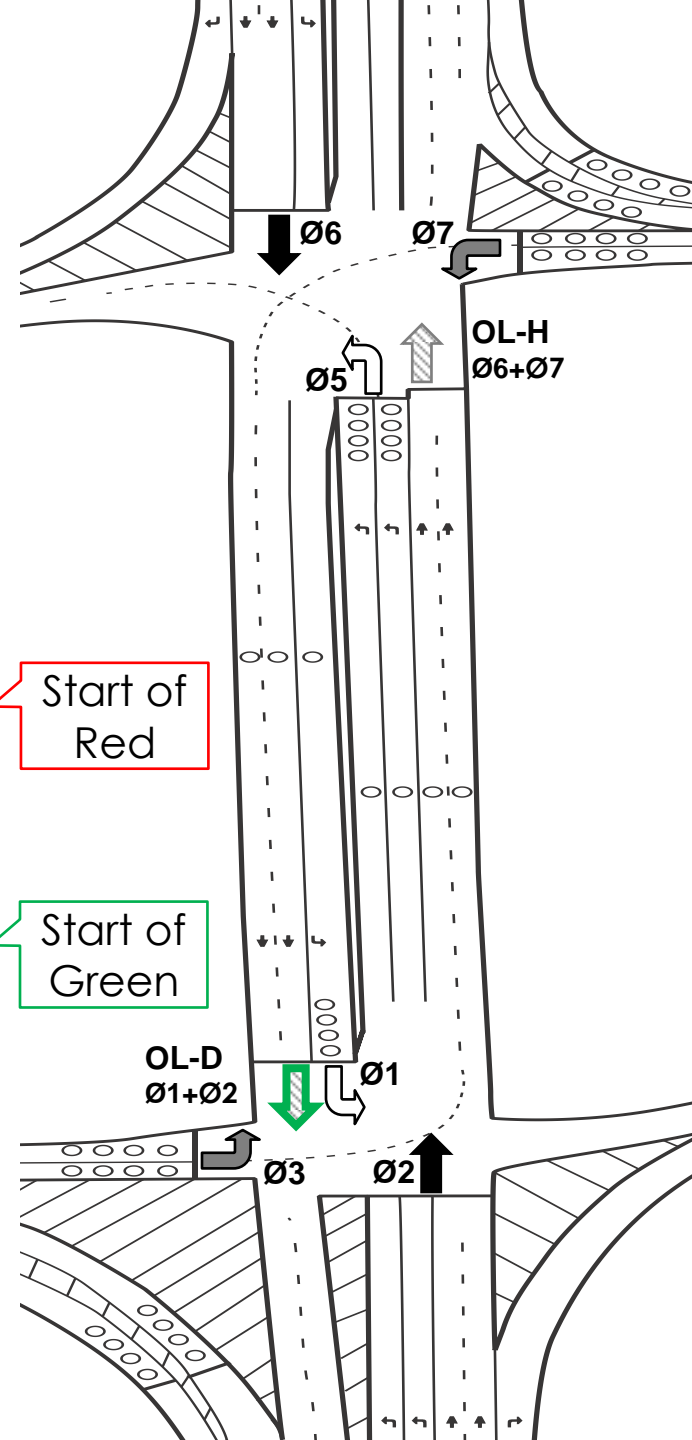
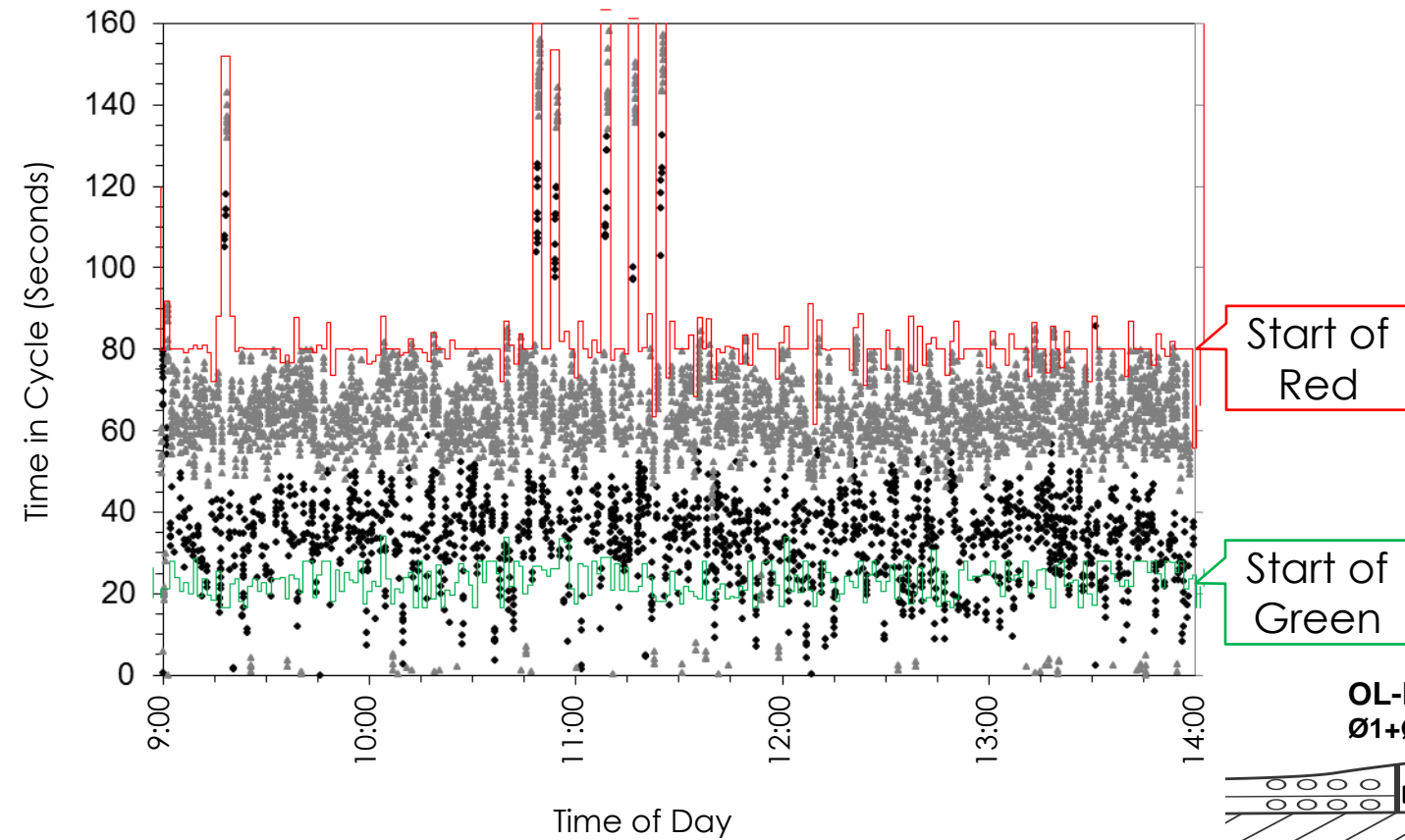
# Purdue Coordination Diagram

*Also Useful to Visualize Arrivals on Green*



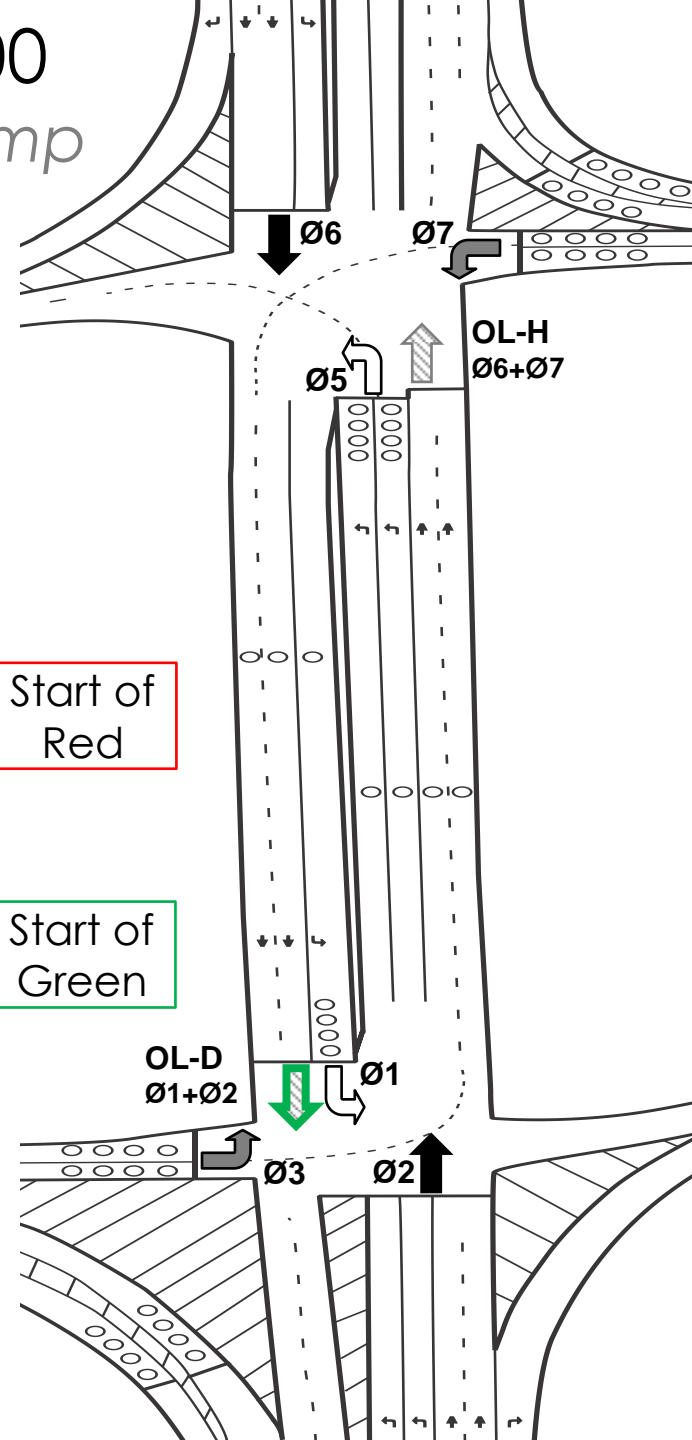
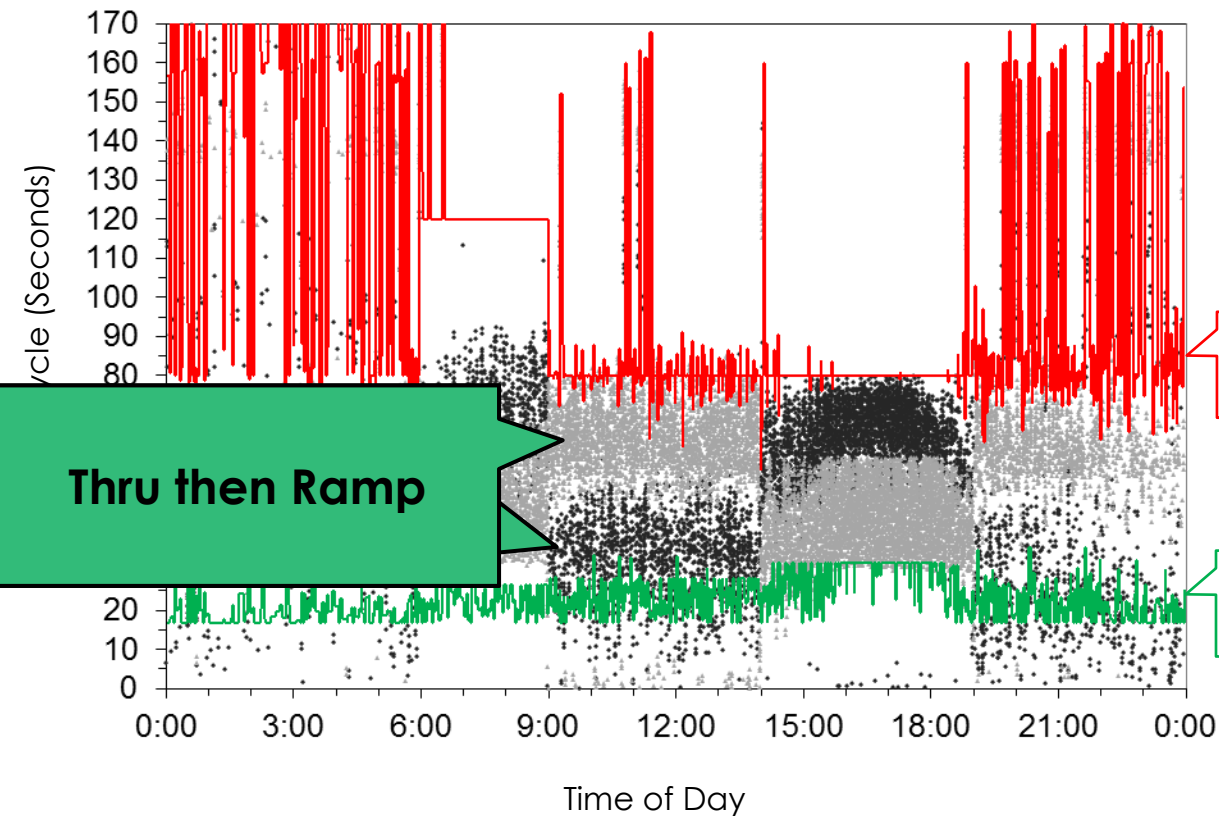
# Purdue Coordination Diagram

*Looking at an entire plan (0900-1400)*



# 24HR PCD: Sequence for 0900-1400

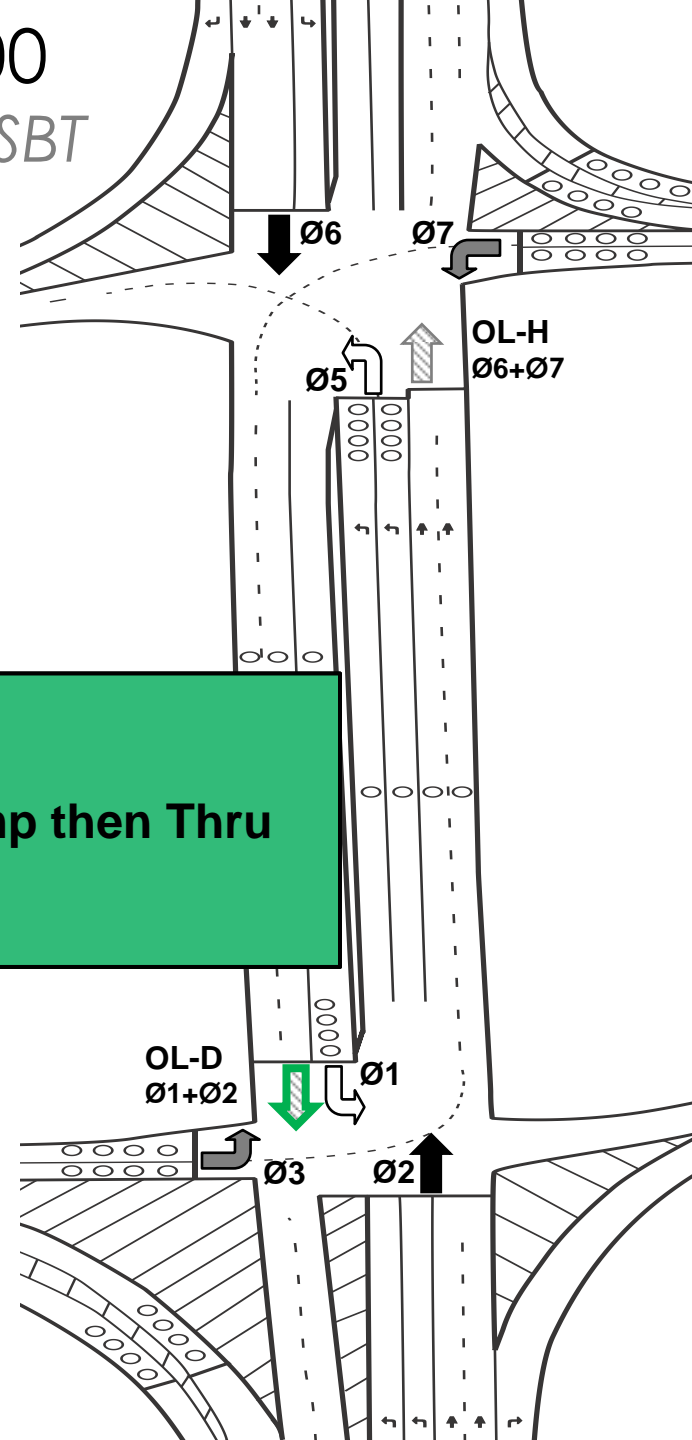
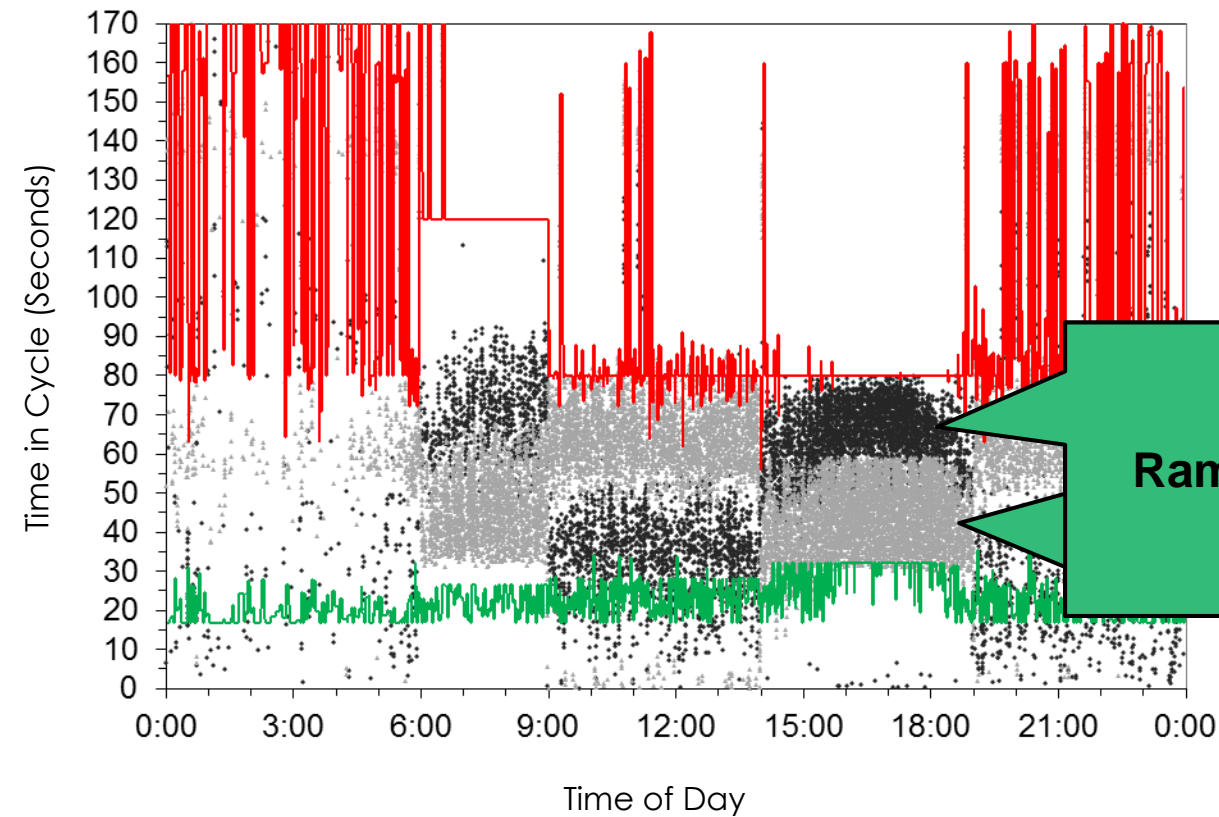
*First is Ø6 SBT, then Ø7 WBL from the ramp*





# 24HR PCD: Sequence for 1400-1900

*First is Ø7 WBL from the ramp, then Ø6 SBT*



Conclusion: These Graphics are Useful!

*Can they be included on newer generation traffic controllers?*



Conclusion: These Graphics are Useful!

*Can they be included on newer generation traffic controllers?*



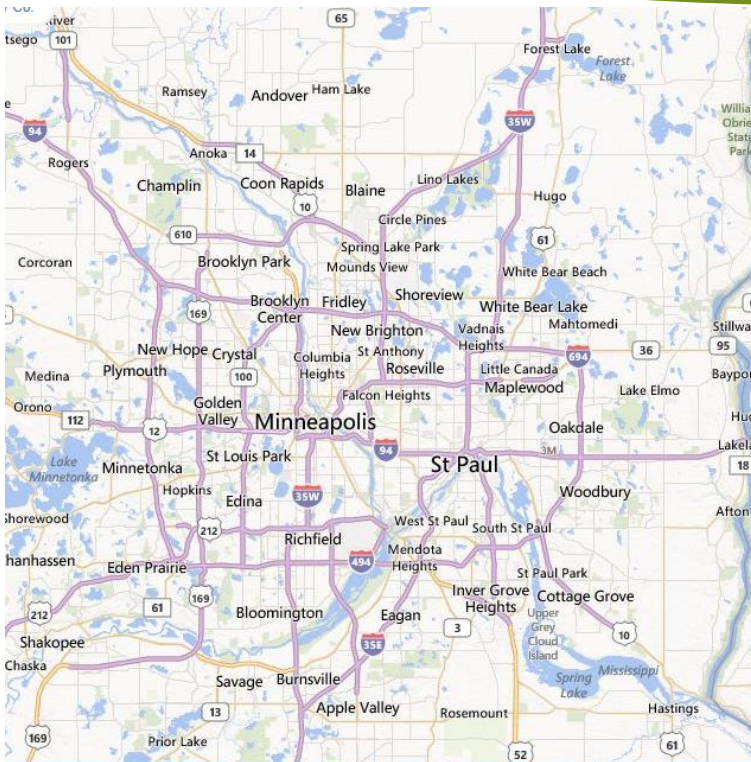
# AUTOMATED TRAFFIC SIGNAL PERFORMANCE MEASURES CASE STUDIES: MnDOT



INSTITUTE OF TRANSPORTATION ENGINEERS WEBINAR PART 1 – MAY 7, 2014

PRESENTED BY STEVE MISGEN, MNDOT

# MnDOT - Metro District Background



- ▶ Operates about 700 signals (Mpls/St. Paul Metro area)
  - ▶ 250 signal on i2 central system
  - ▶ 450 on ARIES dial-up
- ▶ Econolite ASC2/ASC2S or ASC3 controllers
- ▶ Signal Performance Measure
  - ▶ 83 on Smart Signal
  - ▶ 21 on Utah SPM

# Smart Signal

- ▶ University of Minnesota
  - ▶ Henry Liu
- ▶ Minnesota Department of Transportation
- ▶ <http://dotapp7.dot.state.mn.us/smartsignal>
  - ▶ iMonitor – “Real-time” Level of Service
  - ▶ iMeasure – Data extraction tool

# Smart Signal

iMonitor™ / iMeasure™



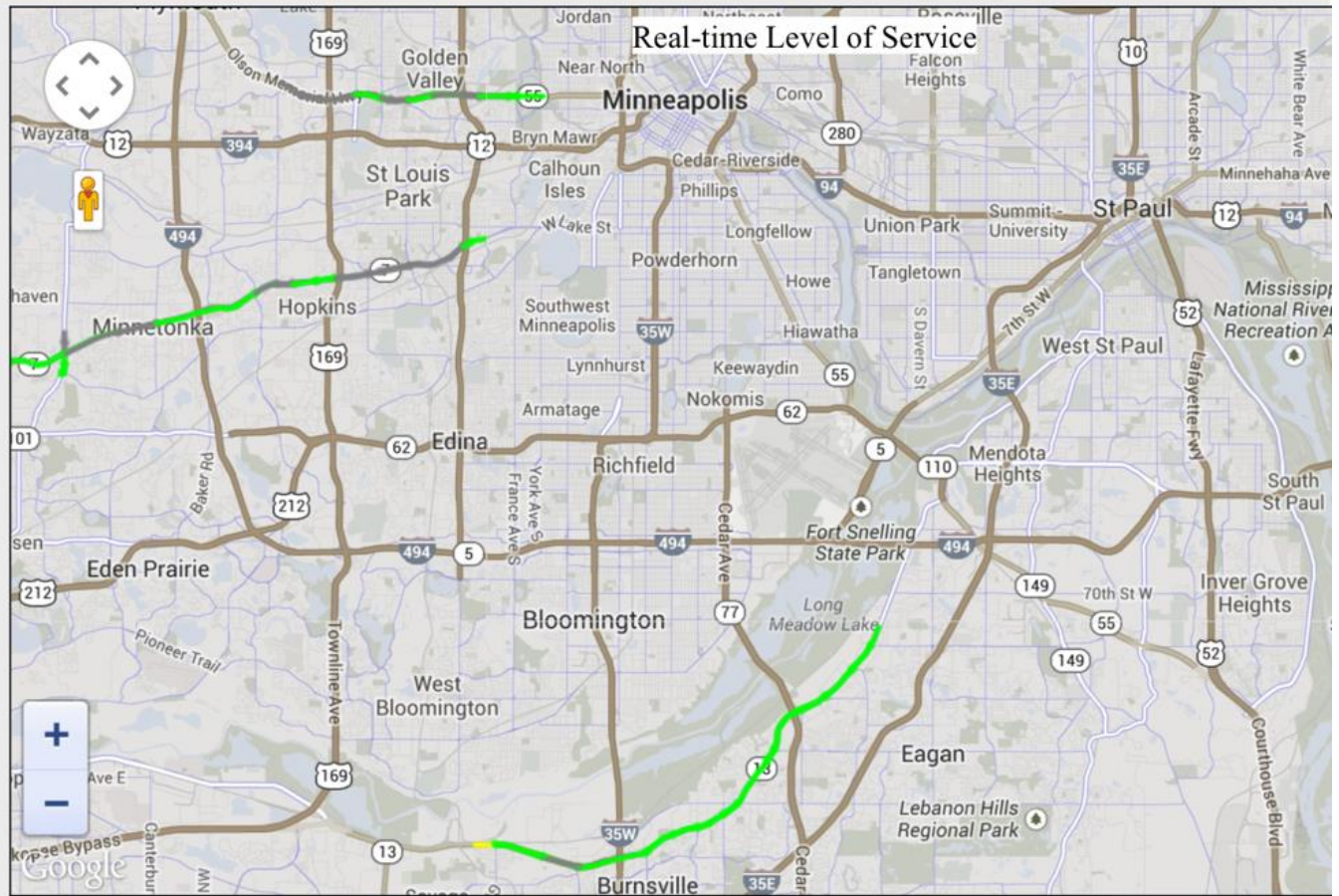
- System Overview
- System Check
- Site Access
- Help

LOS Legend:

- A&B
- C&D
- E
- F
- Real time data not available

Link Delay Legend:

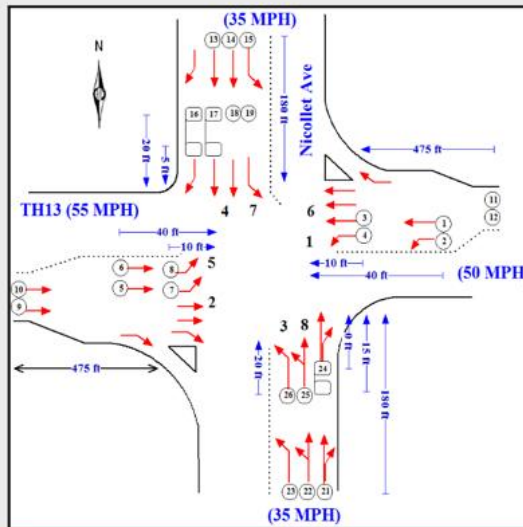
- < 20 Sec./Veh.
- Between 20 and 55 Sec./Veh.
- Between 55 and 80 Sec./Veh.
- > 80 Sec./Veh.
- Real time data not available



# Smart Signal

- Performance Assessment
- Optimization Preparation
- Fine-tuning Analysis
- Performance Comparison
- Retiming Benefits
- Periodic Report
- Help

## Volume Output



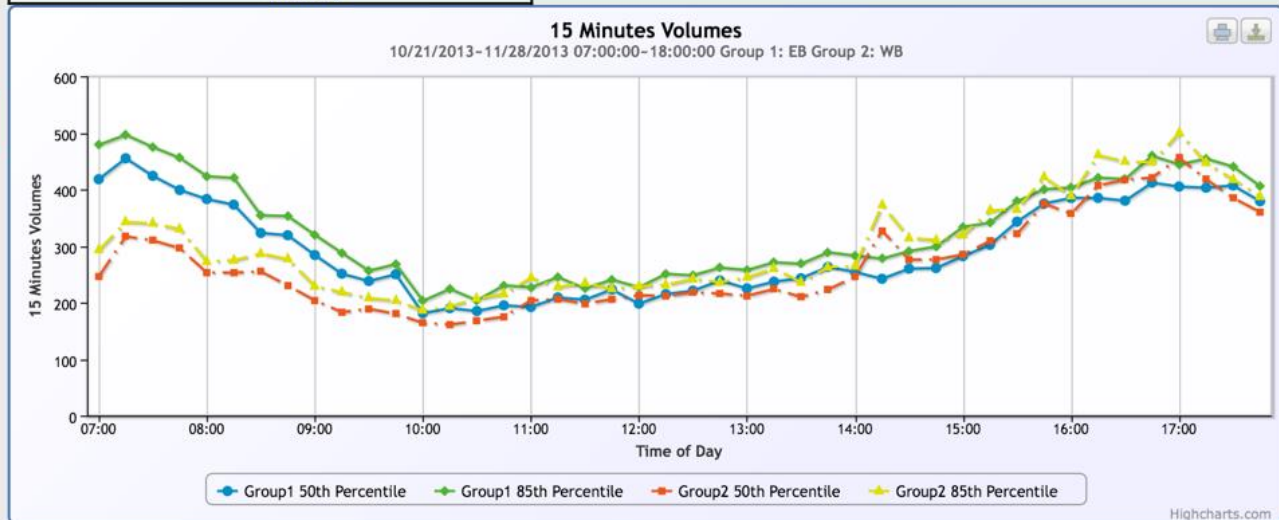
Intersection: TH13/Nicollet Approach Selection Mode:  Normal  Expert

Approaches (Group 1): Select Approaches (Group 2): Select

Start Date: 10/21/2013 End Date: 11/28/2013 Day of Week: Select Days

Start Time: 07:00:00 End Time: 18:00:00 Interval: 15 Minutes

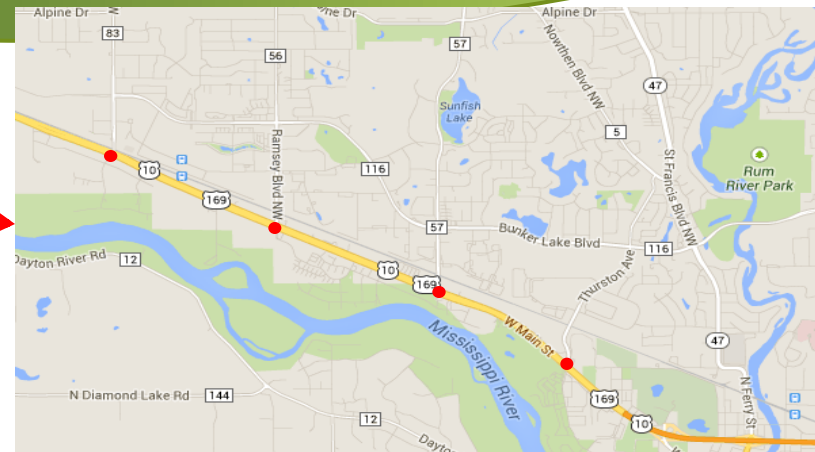
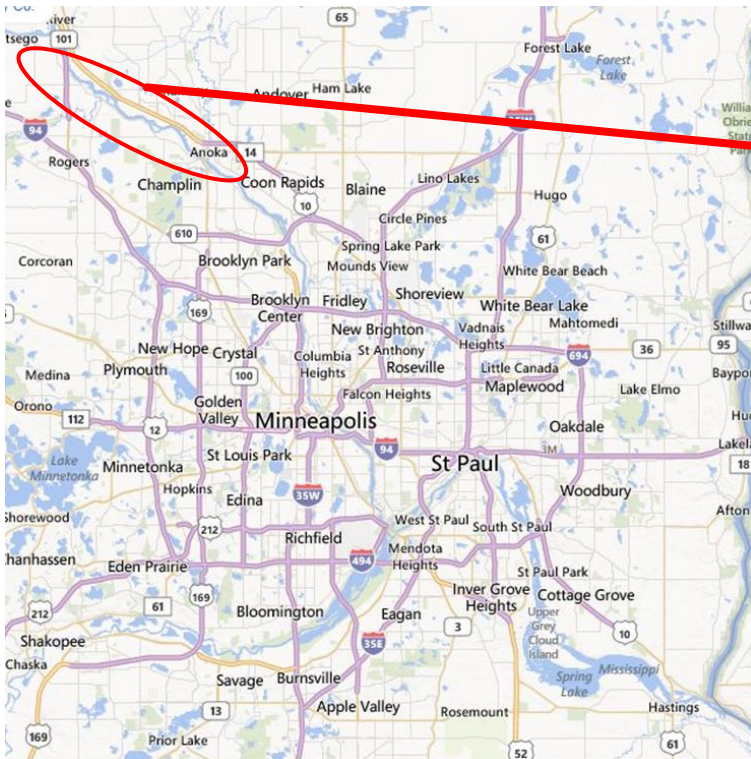
Plot Save Data





# The Project

Develop New Timing Using High Resolution Data collected from SmartSignal



- ▶ 4 fully-actuated signals
- ▶ High speed 60-65 mph posted
- ▶ 33,000-68,000 AADT
- ▶ 7 TOD plans
- ▶ Last retimed 2009

# Signal Timing Development

## Standard Method

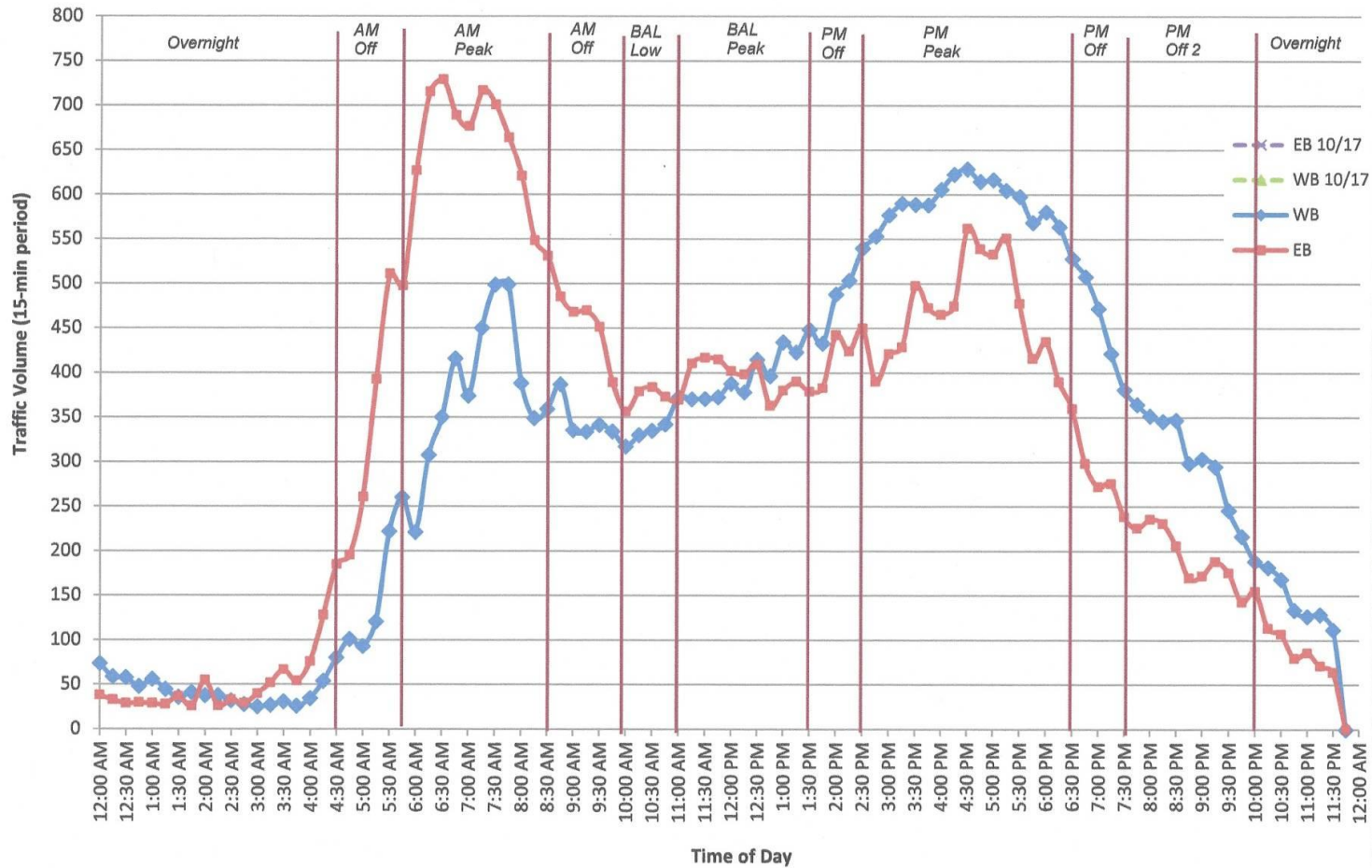
- Data Collection
  - Manual Turning Movement Count – 12 hour
  - System Detectors
- Synchro – approximation of splits & cycle lengths
- Implementation & fine turning completed by time space diagram and field observations
- Before/After Comparison using Travel Time Studies

## Improved Method

- Data Collection
  - Automated collection averaged over Sept-Oct for each movement (M-Th, F, S & S)
- Synchro - Time-space diagram for best two-way progression
- Implementation & fine turning completed by time-space diagram and field observations
- Smart Signal – monitor and make adjustments to insure efficiency
- Before/After Comparison using signal performance metrics

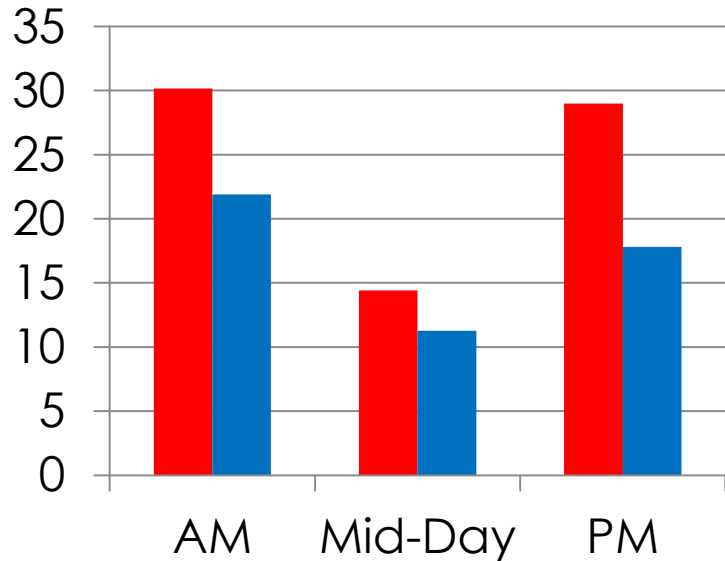
# Volumes

September/October 2013 85th % Weekday Volumes - TH 10 at Thurston Avenue

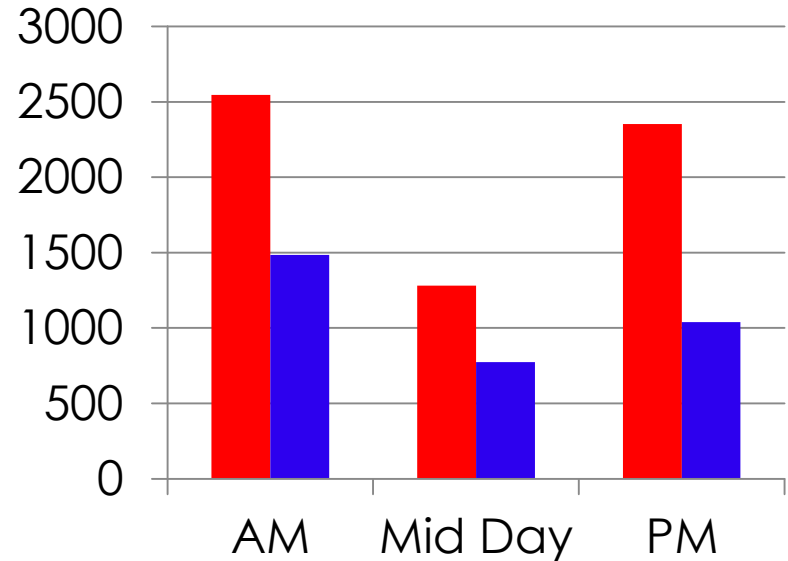


# Peak Periods Before/After Performance Comparison

Total Delay (Hours)

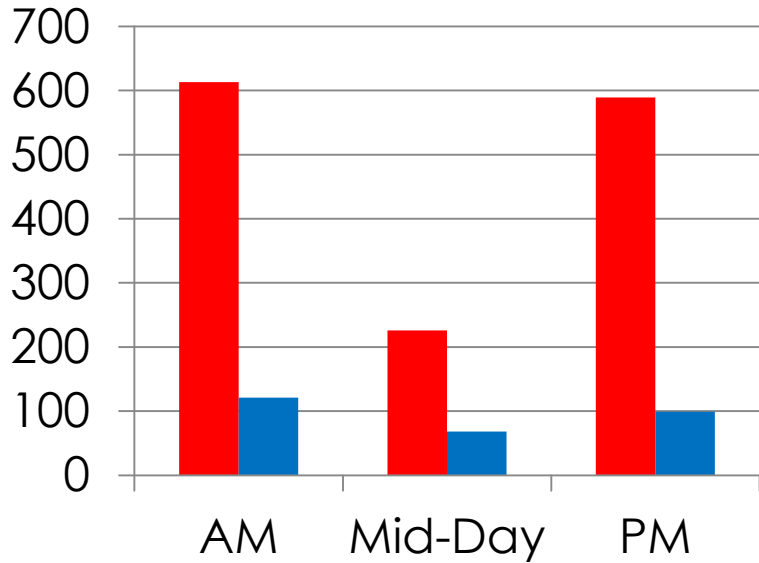


Number of Stops

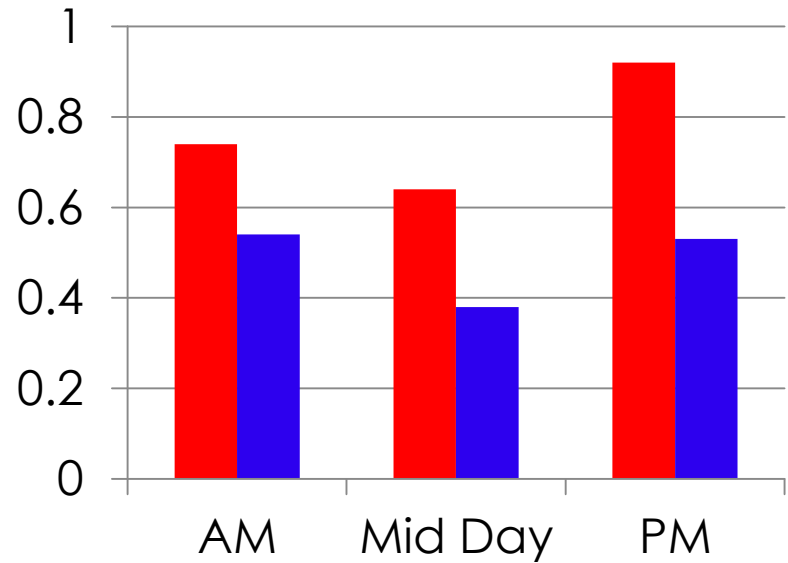


# Peak Periods Before/After Performance Comparison

Max Queue Length (Ft)



Saturation Level



# Future Plans

## ▶ Performance Index

- ▶ based on volume, delay, number of stops, max queue length, saturation level & percent of vehicles arriving on Green
- ▶ Calculate the PI for a given period on time (PM Peak) over a period of time (every Wednesday for the past year)
- ▶ Track the change on performance over time
  - ▶ **When do you need to retime!**

## ▶ Time-space Diagram

- ▶ Real-time TSD based on detector actuations

## ▶ Performance Metrics

- ▶ Emissions – CO<sub>2</sub> fuel consumed

# MnDOT Signal Performance Measures

Steve Misgen, PE, PTOE

MnDOT – Metro District

Traffic Engineer

[Steve.misgen@state.mn.us](mailto:Steve.misgen@state.mn.us)

# Find out more: <http://tig.transportation.org>



## AASHTO TIG

## TIG Home

AASHTO > AASHTO Technology Implementation Group > TIG Home

AASHTO's Technology Implementation Group — or TIG — scans the horizon for outstanding technology and invests time and money to accelerate their adoption by agencies nationwide.

Each year, TIG selects a highly valuable, but largely unrecognized procedure, process, software that has been adopted by at least one agency, is market ready and is available for use by other agencies.

Guided by the vision of "a culture where rapid advancement and implementation of high payoff, expectation of the transportation community," TIG's objective is to share information with AASHTO agencies, and their industry partners to improve the Nation's transportation system.

Recently selected technologies with links to additional information are listed below. Also, you may view [Additionally Selected Technologies](#) categorized by AASHTO subcommittee interest area.

### Lead States Team Focus Technologies

### Additionally Selected Technologies

#### 2013 Focus Technologies

#### 2013 ASTs

- [Automated Traffic Signal Performance Measures](#)
- [UPlan Phase II](#)

- [Double Crossover Diagonal](#)

#### Prior Four Years Focus Technologies

#### Prior Four Years ASTs

- [Embedded Data Collector](#)
- [Environmental Planning GIS Tools](#)

- [Anonymous Wireless Time Data Collection](#)
- [Curvature Extension](#)





# ITE Webinar Series on Automated Traffic Signal Performance Measures (SPMs)

- ▶ Achieve Your Agency's Objectives Using SPMs  
April 9, 2014, 12:00 pm to 1:30 pm. Eastern
- ▶ SPM Case Studies  
May 7, 2014, 12:00 pm to 1:30 pm. Eastern
- ▶ **Critical Infrastructure Elements for SPMs**  
**June 11, 2014, 12:00 pm to 1:30 pm. Eastern**



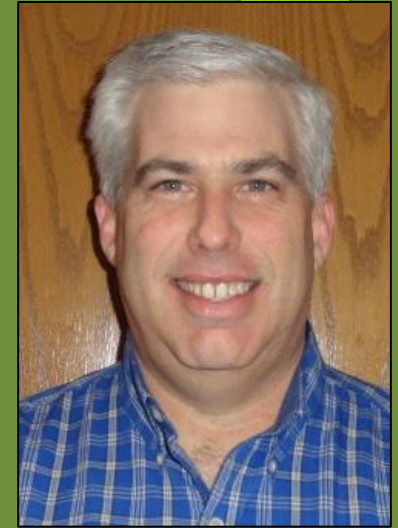
Jamie Mackey  
UDOT



Amanda Stevens  
INDOT



Alex Hainen  
Purdue



Steve Misgen  
MnDOT

# Thank you.

## QUESTIONS?

<http://tig.transportation.org>



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